$\mathbb{Z}_2$ –Thurston Norm and Complexity of 3–Manifolds

William Jaco* · J. Hyam Rubinstein · Stephan Tillmann**

Received: date / Revised version: date – © Springer-Verlag 2012

Abstract. A new lower bound on the complexity of a 3–manifold is given using the $\mathbb{Z}_2$ –Thurston norm. This bound is shown to be sharp, and the minimal triangulations realising it are characterised using normal surfaces consisting entirely of quadrilateral discs.

Key words. 3–manifold, minimal triangulation, efficient triangulation, complexity, Thurston norm, normal surface, generalised quaternionic space

Mathematics Subject Classification (2000): 57M25, 57N10

Prologue

Given a closed, irreducible 3–manifold, its complexity is the minimum number of tetrahedra in a (pseudo–simplicial) triangulation of the manifold. This number agrees with the complexity defined by Matveev [9] unless the manifold is S^3 , $\mathbb{R}P^3$ or $L(3, 1)$. It follows from the definition that the complexity is known for all closed, irreducible manifolds which appear in certain computer generated censuses. In general, the question of determining the complexity of a given closed 3–manifold is difficult and one is therefore interested in finding both upper and lower bounds. Whilst an upper bound arises from the presentation of a manifold via a spine, a Heegaard splitting or a triangulation, Matveev [10]

WILLIAM JACO

Department of Mathematics, Oklahoma State University, Stillwater, OK 74078-1058, USA
e-mail: jaco@math.okstate.edu

J. HYAM RUBINSTEIN

Department of Mathematics and Statistics, The University of Melbourne, VIC 3010, Australia
e-mail: rubin@ms.unimelb.edu.au

STEPHAN TILLMANN

School of Mathematics and Physics, The University of Queensland, QLD 4072, Australia
e-mail: tillmann@maths.uq.edu.au

* The first author is partially supported by NSF Grant DMS-0505609 and the Grayce B. Kerr Foundation.

** The second and third authors are partially supported under the Australian Research Council's Discovery funding scheme (project number DP0664276).

states that the problem of finding lower bounds is quite difficult. Lower bounds using homology groups or the fundamental group are given by Matveev and Pervova [14], and lower bounds using hyperbolic volume are given by Matveev, Petronio and Vesnin [15]. These bounds are only known to be sharp for a few census examples.

In [6] the authors found a lower bound for the complexity using covering spaces and used it to classify all manifolds realising this lower bound. In particular, this determined two infinite families of minimal triangulations, and hence the complexity for infinitely many manifolds. This lower bound supposes the existence of a non-trivial $\mathbb{Z}_2$ -cohomology class (or, equivalently, the existence of a connected double cover of the manifold). The present paper uses the existence of multiple $\mathbb{Z}_2$ -cohomology classes to give a new lower bound for complexity using an analogue of Thurston's norm, and the minimal triangulations realising this bound are characterised. Moreover, it is shown that an infinite family of triangulations realises this bound. Whilst this family already arose in [6], the methods are more generally applicable and lead to a structure theory for the minimal triangulations which are close to realising the lower bound. The new lower bound also gives very tight two sided bounds for many new examples. Moreover, the bootstrapping method of [6] using covers can be combined with this approach — using higher covering degree and the existence of covers with arbitrarily large $\mathbb{Z}_2$ -cohomology.

The effectiveness of the new bounds arising in this work result from the desire not only to know the complexity of a manifold but also some or all minimal triangulations realising this complexity. The combinatorial structure of a minimal triangulation is governed by 0-efficiency [3] and low degree edges [5]. From this one can extrapolate building blocks for minimal triangulations. Understanding how they fit together under extra constraints on the manifold is a guiding principle in this work. Using these ideas, one can effectively try to understand vertical sections of the census which pick up a finite cover of every manifold. Especially with view towards infinite families of minimal triangulations of closed hyperbolic 3-manifolds, this seems to be the most promising approach to date as the largest known census of closed orientable 3-manifolds at the time of writing is due to Matveev [13] and goes up to complexity 12. However, hyperbolic examples only appear from complexity 9 and are sparse amongst these low complexity manifolds (see [12] for an analysis).

1. Definitions, results and applications

Let M be a closed, orientable, irreducible, connected 3-manifold, and let S be a properly embedded surface dual to a given $\varphi \in H^1(M; \mathbb{Z}_2)$. An analogue of Thurston's norm [17] can be defined as follows. If S is connected, let $\chi_-(S) =$

$\max\{0, -\chi(S)\}$, and otherwise let

$$\chi_-(S) = \sum_{S_i \subset S} \max\{0, -\chi(S_i)\},$$

where the sum is taken over all connected components of S . Note that S_i is not necessarily orientable. Define:

$$\|\varphi\| = \min\{\chi_-(S) \mid S \text{ dual to } \varphi\}.$$

The surface S dual to $\varphi \in H^1(M; \mathbb{Z}_2)$ is said to be $\mathbb{Z}_2$ -*taut* if no component of S is a sphere and $\chi(S) = -\|\varphi\|$. As in [17], one observes that every component of a $\mathbb{Z}_2$ -taut surface is non-separating and geometrically incompressible.

Theorem 1 (Thurston norm bounds complexity). *Let M be a closed, orientable, irreducible, connected 3-manifold with triangulation $\mathcal{T}$, and denote by $|\mathcal{T}|$ the number of tetrahedra. If $H \leq H^1(M; \mathbb{Z}_2)$ is a subgroup of rank two, then:*

$$|\mathcal{T}| \geq 2 + \sum_{0 \neq \varphi \in H} \|\varphi\|.$$

There is a nice characterisation for triangulations realising the above lower bound. Let $\mathcal{T}$ be a triangulation of M having a single vertex. Place three quadrilateral discs in each tetrahedron, one of each type, such that the result is a (possibly branched immersed) normal surface. This surface is denoted Q and called the *canonical quadrilateral surface*. Suppose Q is the union of three embedded normal surfaces. Then each of them meets each tetrahedron in a single quadrilateral disc and is hence a one-sided Heegaard splitting surface. It defines a dual $\mathbb{Z}_2$ -cohomology class and $H^1(M; \mathbb{Z}_2)$ has rank at least two.

Theorem 2. *Let M be a closed, orientable, irreducible, connected 3-manifold with triangulation $\mathcal{T}$. Let $H \leq H^1(M; \mathbb{Z}_2)$ be a subgroup of rank two. Then the following two statements are equivalent.*

1. *We have*

$$|\mathcal{T}| = 2 + \sum_{0 \neq \varphi \in H} \|\varphi\|.$$

2. *The triangulation has a single vertex and the canonical quadrilateral surface is the union of three $\mathbb{Z}_2$ -taut surfaces representing the non-trivial elements of H .*

Note that (1) implies that $\mathcal{T}$ is minimal by Theorem 1. Moreover, (2) implies that each non-trivial element of H has a $\mathbb{Z}_2$ -taut representative, which is a one-sided Heegaard splitting surface, and that each edge has even degree.

The proofs of the theorems are based on a refinement of the methods of [5]. This paper gives new results concerning combinatorial constraints from $\mathbb{Z}_2$ -cohomology classes and intersections of maximal layered solid tori. These results can be found in Sections 2 and 3 respectively. In Section 4, we study quadrilateral surfaces and their relationship with Heegaard splittings. It is interesting to note that one-sided splittings of lowest complexity are obtained from the minimal triangulations in [5] and [6]. In contrast, determining two-sided Heegaard splittings of lowest complexity is in general very difficult. The proofs of the main results are given in Section 5.

In Section 6, we show that the *twisted layered loop triangulation* of S^3/Q_{8k} , k any positive integer, satisfies the equivalent statements in Theorem 2. It was already shown in [6] that this triangulation is the unique minimal triangulation.

We conclude this introduction with a few open problems:

1. Are there more manifolds (in particular with $\mathbb{Z}_2$ -cohomology of rank three or more) satisfying the equivalent statements of Theorem 2?
2. Are there triangulations with more than one vertex and such that the canonical quadrilateral surface is the union of three $\mathbb{Z}_2$ -taut surfaces?
3. The small Seifert fibred space

$$M_{m,n} = S^2((1, -1), (2, 1), (2m + 2, 1), (2n + 2, 1)),$$

where m and n are positive integers, is triangulated by a *layered chain pair* having $2(m + n) + 2$ tetrahedra (see [1]). This satisfies $|\mathcal{T}| = 4 + \sum \|\varphi\|$. Theorem 2 therefore implies that $M_{m,n}$ has complexity $2(m + n)$, $2(m + n) + 1$ or $2(m + n) + 2$. What is the complexity of $M_{m,n}$?

4. The Seifert fibred space

$$M_{k,m,n} = S^2((1, -1), (2k + 2, 1), (2m + 2, 1), (2n + 2, 1)),$$

where k, m and n are positive integers, is triangulated by an *augmented solid torus* having $2k + 2m + 2n + 3$ tetrahedra (see [1]). Is this a minimal triangulation satisfying $|\mathcal{T}| = 3 + \sum \|\varphi\|$?

5. In general, the above theorem gives a very good estimate for the complexity of manifolds having triangulations satisfying $|\mathcal{T}| = 3 + \sum \|\varphi\|$ or $|\mathcal{T}| = 4 + \sum \|\varphi\|$. Determine a complete profile of all minimal triangulations satisfying these equalities. From work of Martelli and Petronio [8], it appears likely that the minimal triangulations for many Seifert fibred spaces with the appropriate cohomology fall into this range.
6. Determine an effective bound for the complexity of M using a rank k subgroup of $H^1(M; \mathbb{Z}_2)$ for $k \geq 3$.

2. Normal surfaces dual to $\mathbb{Z}_2$ –cohomology classes

Throughout this section, let $\mathcal{T}$ be an arbitrary 1–vertex triangulation of the closed, orientable, connected 3–manifold M . A non-trivial class in $H^1(M, \mathbb{Z}_2)$ was used in [5] to study $\mathcal{T}$. This generalises to subgroups of $H^1(M, \mathbb{Z}_2)$ of arbitrary rank in a natural way. For the purpose of this paper, it suffices to consider rank–2 subgroups. To fix notation, assume that $\varphi_1, \varphi_2 \in H^1(M, \mathbb{Z}_2)$ such that

$$H = \langle \varphi_1, \varphi_2 \rangle \cong \mathbb{Z}_2 \oplus \mathbb{Z}_2.$$

We let $\varphi_3 = \varphi_1 + \varphi_2$. A colouring of the edges arising from H is introduced and a canonical surface is associated to H . It is shown that this yields a combinatorial constraint for the triangulation.

2.1. Triangulations

The notation of [3] and [4] will be used in this paper. Hence $\mathcal{T}$ consists of a union of pairwise disjoint 3–simplices, $\tilde{\Delta}$, a set of face pairings, Φ , and a natural quotient map $p: \tilde{\Delta} \rightarrow \tilde{\Delta}/\Phi = M$. Since the quotient map is injective on the interior of each 3–simplex, we will refer to the image of a 3–simplex in M as a *tetrahedron* and to its faces, edges and vertices with respect to the pre-image. Similarly for images of 2– and 1–simplices, which will be referred to as *faces* and *edges* in M . For edge e , the number of pairwise distinct 1–simplices in $p^{-1}(e)$ is termed its *degree*, denoted $d(e)$. If e is contained in ∂M , then it is a *boundary edge*; otherwise it is an *interior edge*.

2.2. Rank–1 colouring of edges and canonical surface

Let $0 \neq \varphi \in H^1(M, \mathbb{Z}_2)$. The following construction can be found in [5]. Edge e is given an orientation, and hence represents an element $[e] \in \pi_1(M)$. If $\varphi[e] = 0$, e is termed φ –even, otherwise it is termed φ –odd. This terminology is independent of the chosen orientation for e . Faces in the triangulation give relations between loops represented by edges. It follows that a tetrahedron falls into one of the following categories, which are illustrated in Figure 1(a):

- Type 1: A pair of opposite edges are φ –even, all others are φ –odd.
- Type 2: The three edges incident to a vertex are φ –odd, all others are φ –even.
- Type 3: All edges are φ –even.

Since φ is non-trivial, one obtains a unique normal surface, $S_\varphi = S_\varphi(\mathcal{T})$, with respect to $\mathcal{T}$ by introducing a single vertex on each φ –odd edge. This surface is disjoint from the tetrahedra of type 3; it meets each tetrahedron of type 2 in a single triangle meeting all φ –odd edges; and each tetrahedron of type 1 in a single quadrilateral dual to the φ –even edges. Moreover, S_φ is dual to φ and will be termed the *canonical surface dual to φ* .

Fig. 1. Colouring of edges and dual normal discs

Lemma 1. *Let M be a closed, orientable, irreducible, connected 3-manifold and $\mathcal{T}$ be a triangulation with one vertex. Given $0 \neq \varphi \in H^1(M; \mathbb{Z}_2)$, we have*

$$\|\varphi\| \leq -\chi(S_\varphi)$$

unless $M = \mathbb{R}P^3$.

Proof. Suppose M is not homeomorphic with $\mathbb{R}P^3$. It follows from the construction that S_φ is dual to φ , and it suffices to show that no component of S_φ is a sphere or a projective plane. Since M is irreducible and not $\mathbb{R}P^3$, no component can be a projective plane. Since each component of S_φ meets some edge, and it meets each edge in at most one point, no component can be a sphere.

2.3. Rank-2 colouring of edges

Given the subgroup $H = \langle \varphi_1, \varphi_2 \rangle \cong \mathbb{Z}_2 \oplus \mathbb{Z}_2$ of $H^1(M; \mathbb{Z}_2)$, we now introduce a refinement of the above colouring. Since $\varphi_1 + \varphi_2 = \varphi_3$, there are four types of edges:

- edge e is H -even or 0-even if $\varphi_i[e] = 0$ for each $i \in \{1, 2, 3\}$; and
- edge e is i -even if $\varphi_i[e] = 0$ for a unique $i \in \{1, 2, 3\}$.

Let $\{i, j, k\} = \{1, 2, 3\}$. The normal corners of the normal surface $S_{\varphi_i}(\mathcal{T})$ are precisely on the j -even and k -even edges. Edge e is φ_i -even if it is i -even or 0-even. It follows that a face of a tetrahedron either has all of its edges 0-even; or it has two i -even and one 0-even edge; or it has one 1-even, one 2-even and one 3-even edge. Whence an *oriented* tetrahedron falls into one of the following categories:

Type I: One edge is 0-even, the opposite edge is i -even, and one vertex of the latter is incident with two j -even edges, and the other with two k -even edges, where $\{i, j, k\} = \{1, 2, 3\}$. (There are six distinct sub-types.)

Type II: A pair of opposite edges are 0-even, all others are i -even for a unique $i \in \{1, 2, 3\}$. (There are hence three distinct sub-types.)

Type III: The three edges incident to a vertex are i -even for a fixed $i \in \{1, 2, 3\}$, and all others are 0-even. (There are hence three distinct sub-types.)

Type IV: All edges are 0-even.

Type V: Each vertex is incident to an i -even edge for each $i \in \{1, 2, 3\}$. (In particular, no edge is 0-even, opposite edges are of the same type, and there are two distinct sub-types of tetrahedra.)

For each type, one sub-type is shown in Figure 1(b); the black edges correspond to 0-even edges and the normal discs in S_{φ_i} have the same colour as the i -even edges. The remaining subtypes are obtained by permuting the colours other than black.

2.4. Combinatorial bounds for triangulations

The set-up and notation of the previous subsection is continued. Let

- $A(\mathcal{T})$ = number of tetrahedra of type I,
- $B(\mathcal{T})$ = number of tetrahedra of type II,
- $C(\mathcal{T})$ = number of tetrahedra of type III,
- $D(\mathcal{T})$ = number of tetrahedra of type IV,
- $E(\mathcal{T})$ = number of tetrahedra of type V,
- $\epsilon(\mathcal{T})$ = number of 0-even edges,
- $\tilde{\epsilon}(\mathcal{T})$ = number of pre-images of 0-even edges in $\tilde{\Delta}$.

The number of tetrahedra in $\mathcal{T}$ is

$$T(\mathcal{T}) = A(\mathcal{T}) + B(\mathcal{T}) + C(\mathcal{T}) + D(\mathcal{T}) + E(\mathcal{T}).$$

For the remainder of this subsection, we will write $A = A(\mathcal{T})$, etc.

Lemma 2. *C and E are even.*

Proof. The colouring of edges is pulled back to $\tilde{\Delta}$. Then the number of faces in $\tilde{\Delta}$ having all edges 0-even is $C + 4D$. Since faces match up in pairs and no face is identified with itself, it follows that C is even. Now consider the normal surface $S_{\varphi_1}(\mathcal{T})$. It meets an edge in a normal corner if and only if the edge is either 2-even or 3-even. Every normal surface satisfies the so-called Q -matching equations [19], which can roughly be described as the fact that “at each edge, there have to be as many quadrilateral discs of positive slope as there

are quadrilateral discs of negative slope.” Each corner of each quadrilateral disc has a well-defined sign arising from the slope of the quadrilateral disc at this corner with respect to the edge. Given an edge in M , the sum of all signs associated with the corners incident with the edge equals zero. See [18], Sections 2.4, 2.5 and 2.9 for details.

We now examine the sum of the Q -matching equations of all 2-even edges. This sum, Σ , must equal zero. Since M is orientable, opposite corners of each quadrilateral disc have the same sign, and adjacent corners have opposite signs (see [18], Sections 2.4 and 2.9). Let $\square$ be a quadrilateral disc in $S_{\phi_1}(\mathcal{T})$. If $\square$ is contained in a tetrahedron of type I and meets a 2-even edge, then it has precisely two adjacent corners on 2-even edges; hence the contribution to Σ of the normal corners of $\square$ is $(+1) + (-1) = 0$. If $\square$ is contained in a tetrahedron of type II, and meets a 2-even edge, then it meets a 2-even edge with each of its corners; hence the contribution to Σ is $2(+1) + 2(-1) = 0$. If $\square$ is contained in a tetrahedron of type V and meets a 2-even edge, then it meets 2-even edges in a pair of diagonally opposite corners; hence the contribution to Σ is either $2(+1)$ or $2(-1)$. It follows that the number of tetrahedra of type IV, E , must be even.

Lemma 3. *Let M be a closed, orientable, irreducible 3-manifold with minimal triangulation $\mathcal{T}$. Suppose that all edge loops are coloured by the rank-2 subgroup H of $H^1(M; \mathbb{Z}_2)$. Suppose that $A + C \leq 3$. Then (A, B, C, D, E) is of one of the following forms:*

$$(0, 0, 0, 0, E), (2, B, 0, 0, E), (3, B, 0, 0, E),$$

and if $A \neq 0$, then there is a unique edge incident with all tetrahedra of type I.

Proof. We distinguish the cases $A = 0$ and $A \neq 0$.

(Case 1a) $A = 0$ and $E \neq 0$. Since each face of a tetrahedron of type II, III or IV contains an H -even edge and M is connected, we have $B = C = D = 0$.

(Case 1b) $A = 0$ and $E = 0$. In this case, the Haken sum $S_{\phi_1} + S_{\phi_2} + S_{\phi_3}$ is defined and is isotopic to the boundary of a regular neighbourhood, N , of the complex K spanned by all 0-even edges. Then $M \setminus N$ therefore meets a tetrahedron either in the empty set or in a product region and hence each component of $M \setminus N$ is an I -bundle or a twisted I -bundle over a surface. If $C = 0$, then either all tetrahedra are of type II or all tetrahedra are of type IV. In each case, this contradicts the fact that $H^1(M; \mathbb{Z}_2)$ has rank two. Hence $C = 2$ since C is even. Moreover, the two tetrahedra of type III must be of distinct sub-types since otherwise $H^1(M; \mathbb{Z}_2)$ has rank one. We may assume that one of them has three 0-even and three 1-even edges. Pulling back the colouring of faces to $\tilde{\Delta}$, we have an odd number of faces with one 0-even edge and two 1-even edges. This contradicts the fact that M is closed. Hence, $A = 0$ and $E = 0$ can not both occur.

(Case 2) $A \neq 0$. The abstract neighbourhood of each 0-even edge contained in a tetrahedron of type I contains either at least two distinct tetrahedra of type I, or one tetrahedron of type one and at least two tetrahedra of type III. Since C is even and $A + C \leq 3$, we have the following cases: $(A \in \{1, 2, 3\}, C = 0)$ and $(A = 1, C = 2)$.

We first show that $(A = 1, C = 2)$ is not possible. Note that there is a unique 0-even edge, e_0 , incident with the tetrahedron of type I, σ_0 . It follows that it must be incident with the two tetrahedra of type III, σ_1 and σ_2 . Denote the two remaining 0-even edges incident with σ_1 by e_1 and e_2 , oriented such that $e_0 + e_1 + e_2$ is homologically the boundary of the face. Consider the abstract neighbourhood $B(e_1)$ of e_1 , and recall that no face can be a cone or a dunce hat. It follows that either $e_0 \neq e_1 = e_2$ or $e_0 = e_1 = e_2$. Since $e_1 = e_2$, there are two tetrahedra in $B(e_1)$ mapping to σ_1 under the map $B(e_1) \rightarrow M$. Give $B(e_1)$ an orientation. Then the two tetrahedra mapping to σ_1 induce opposite orientations on σ_1 , contradicting the fact that M is orientable.

It is easy to see that $(A = 1, C = 0)$ is not possible by examining the neighbourhood of the unique 0-even edge, e_0 , incident with the tetrahedron of type I.

The remaining cases are $(A = 2, C = 0)$ and $(A = 3, C = 0)$. In each case, there is a unique 0-even edge, e_0 , contained in all tetrahedra of type I. Note that e_0 cannot be of degree three since otherwise the classification of degree three edges in [5] implies that e_0 is contained in a maximal layered torus subcomplex and hence every tetrahedron incident with it is of type II or IV. Moreover, if $A \neq 0$ but $C = 0$, then necessarily $D = 0$ since M is connected.

Let K be the complex in M spanned by all 0-even edges. Let N be a small regular neighbourhood of K . Then ∂N is a normal surface; it meets each tetrahedron in the same number and types of normal discs as $S_{\varphi_1} \cup S_{\varphi_2} \cup S_{\varphi_3}$ except for the tetrahedra of type V, which it meets in four distinct normal triangle types instead of three distinct normal quadrilateral types. The normal coordinate of ∂N is thus obtained by taking the sum of the normal coordinates of S_{φ_1} , S_{φ_2} , and S_{φ_3} , and adding to this the *tetrahedral solution* of each tetrahedron of type V. (The tetrahedral solution is obtained by adding all triangle coordinates of a tetrahedron and subtracting all quadrilateral coordinates; see, for instance, [7], Section 2, or [18], Section 2.8. Each tetrahedral solution has both positive and negative coordinates.) Hence

$$\chi(S_{\varphi_1}) + \chi(S_{\varphi_2}) + \chi(S_{\varphi_3}) + E = \chi(\partial N) = 2\chi(N) = 2\chi(K) = 2 - 2\epsilon + C + 2D,$$

where the Euler characteristic of K is computed from the combinatorial data. In particular, $\chi(S_{\varphi_1}) + \chi(S_{\varphi_2}) + \chi(S_{\varphi_3})$ is even. Rearranging the above equality gives

$$C + 2D - E = 2\epsilon - 2 + \chi(S_{\varphi_1}) + \chi(S_{\varphi_2}) + \chi(S_{\varphi_3}), \quad (2.1)$$

Fig. 2. Layered triangulation of the solid torus

and hence:

$$\begin{aligned}
 \tilde{\epsilon} &= A + 2B + 3C + 6D \\
 &= 2T - A + C + 4D - 2E \\
 &= 2T - A - C + 4\epsilon - 4 + 2(\chi(S_{\varphi_1}) + \chi(S_{\varphi_2}) + \chi(S_{\varphi_3})). \quad (2.2)
 \end{aligned}$$

Lemma 4. *Let M be a closed, orientable, irreducible 3-manifold, and suppose that $\varphi_1, \varphi_2 \in H^1(M; \mathbb{Z}_2)$ are non-trivial with $\varphi_1 + \varphi_2 = \varphi_3 \neq 0$. Let $\mathcal{T}$ be a minimal triangulation with T tetrahedra, and let S_{φ_i} be the canonical surface dual to φ_i . Letting ϵ_d denote the number of 0-even edges of degree d , we have:*

$$\epsilon_3 = 4 + A + C - 2(T + \chi(S_{\varphi_1}) + \chi(S_{\varphi_2}) + \chi(S_{\varphi_3})) + \sum_{d=5}^{\infty} (d-4)\epsilon_d. \quad (2.3)$$

Proof. First note that the existence of φ_1 and φ_2 implies that M is not homeomorphic to one of S^3 , $L(3, 1)$, $\mathbb{R}P^3$, or $L(4, 1)$. It now follows from [3], Theorem 6.1, that $\mathcal{T}$ has a single vertex; hence S_{φ_i} and ϵ_i are defined. Moreover, [3], Proposition 6.3 (see also Proposition 8 of [5]), implies that the smallest degree of an edge in $\mathcal{T}$ is three. One has $\tilde{\epsilon} = \sum d\epsilon_d$ and $\epsilon = \sum \epsilon_d$. Putting this into (2.2) gives the desired equation.

3. Intersections of maximal layered solid tori

Throughout this section, let M be a closed, irreducible, orientable, connected 3-manifold with triangulation $\mathcal{T}$. We extend results of [5] concerning maximal layered solid tori in M .

3.1. Layered solid tori

The following definitions and facts can be found with more detail in [4] and [5]. A *layered solid torus* is a solid torus with a special triangulation: the triangulation is obtained from the triangulation given in Figure 2(a) by iteratively *layering along boundary edges*. Layering along a boundary edge is illustrated in Figure 2(b). Namely, suppose N is a 3–manifold, $\mathcal{T}_\partial$ is a triangulation of ∂N , and e is an edge in $\mathcal{T}_\partial$ which is incident to two distinct faces. We say the 3–simplex σ is *layered along e* if two faces of σ are paired, “without a twist,” with the two faces of $\mathcal{T}_\partial$ incident with e . The resulting 3–manifold is homeomorphic with N . If $\mathcal{T}_\partial$ is the restriction of a triangulation of N to ∂N , then we get a new triangulation of N and a new triangulation of ∂N which differs from $\mathcal{T}_\partial$ by a diagonal flip. For every edge in M , we will also refer to its degree as its M –degree, and its degree with respect to the layered solid torus T in M is called its T –degree.

Definition 1 (Layered solid torus in M). A layered solid torus with respect to $\mathcal{T}$ in M is a subcomplex in M which is combinatorially equivalent to a layered solid torus.

Definition 2 (Maximal layered solid torus in M). A layered solid torus is a maximal layered solid torus with respect to $\mathcal{T}$ in M if it is not strictly contained in any other layered solid torus in M .

Lemma 5. [5] Assume that the triangulation is minimal and 0–efficient. If M is not a lens space with layered triangulation, then the intersection of two distinct maximal layered solid tori in M consists of at most a single edge.

Lemma 6. [5] Assume that the triangulation is minimal and 0–efficient, and suppose that M contains a layered solid torus, T , made up of at least two tetrahedra and having a boundary edge, e , which has degree four in M . Then either

1. T is not a maximal layered solid torus in M ; or
2. e is the univalent edge for T and it is contained in four distinct tetrahedra in M ; or
3. M is a lens space with minimal layered triangulation.

Recall the notion of rank–2 colouring from Subsection 2.3.

Lemma 7. Assume that the triangulation contains a single vertex and that all edge loops are coloured by the rank–2 subgroup H of $H^1(M; \mathbb{Z}_2)$. Then all tetrahedra in a layered solid torus in M are either of type II or type IV, but not both.

Proof. The colouring of the layered solid torus is uniquely determined by the image of the longitude under the elements of H ; the result now follows from the layering procedure. Alternatively, a combinatorial argument can be given by noting that the only possible rank-2 colourings of the 1-tetrahedron layered solid torus shown in Figure 2(a) are of type II or IV, and it follows from the layering procedure that each subsequent tetrahedron must be of the same type as the initial tetrahedron.

Definition 3 (Types of layered solid tori). *Assume that the triangulation contains a single vertex and that all edge loops are coloured by the rank-2 subgroup H of $H^1(M; \mathbb{Z}_2)$. A layered solid torus containing a tetrahedron of type II (respectively IV) is accordingly termed of type II (respectively IV).*

3.2. Maximal layered solid tori in atoroidal manifolds

An orientable 3-manifold is termed *atoroidal* if it does not contain an embedded, incompressible torus.

Lemma 8. [5] *Suppose M is atoroidal and $\mathcal{T}$ is minimal and 0-efficient. Then every torus which is normal with respect to $\mathcal{T}$ bounds a solid torus in M on at least one side.*

It is shown in [3], Section 6, that a minimal triangulation of a closed, irreducible and orientable 3-manifold is 0-efficient unless the manifold is homeomorphic with $\mathbb{R}P^3$ or $L(3, 1)$. So in particular, if there is a rank-2 subgroup H of $H^1(M; \mathbb{Z}_2)$, then every minimal triangulation of M is 0-efficient.

Lemma 9. *Assume that $\mathcal{T}$ is minimal and that M is atoroidal. Suppose the edges are coloured by the rank-2 subgroup H of $H^1(M; \mathbb{Z}_2)$, and that three pairwise distinct maximal layered solid tori of type II meet in a H -even edge. Then these are the only maximal layered solid tori of type II in the triangulation and M is a Seifert fibred space with base S^2 and precisely three exceptional fibres.*

Proof. Denote the three maximal layered solid tori by T_1, T_2, T_3 , and the common H -even edge by e . If $T_i \cap T_j$ properly contains e for $i \neq j$, then M is a lens space with layered triangulation according to Lemma 5. But this contradicts the assumption that $H^1(M; \mathbb{Z}_2)$ has rank at least two. Hence $T_i \cap T_j = \{e\}$.

Let N be a small regular neighbourhood of $T_1 \cup T_2 \cup T_3$. Then ∂N is a (topological) torus and a barrier surface; see [3], Section 3.2. Hence, either ∂N is isotopic to a normal surface or $\overline{M \setminus N}$ is a solid torus. In the first case, Lemma 8 implies that either N or $\overline{M \setminus N}$ is a solid torus. However, e is not a longitude of either T_1, T_2 or T_3 since e is H -even and each torus is of type II. So N cannot be a solid torus. Hence $\overline{M \setminus N}$ is a solid torus and, in particular, N admits

a Seifert fibration with three exceptional fibres, and M admits a Seifert fibration with three or four exceptional fibres. If M admits a Seifert fibration with four exceptional fibres, then it contains an embedded, incompressible (vertical) torus, contradicting the assumption that M is atoroidal. Similarly, if M admits a Seifert fibration with three exceptional fibres but the base is not S^2 , then M contains an embedded, incompressible (vertical) torus. Hence M is a Seifert fibred space with base S^2 and precisely three exceptional fibres. This forces e to be homotopic to a longitude of $\overline{M \setminus N}$. Moreover, each $\varphi \in H$ restricted to $\overline{M \setminus N}$ is trivial since e is H –even. Suppose T_4 is a maximal layered solid torus of type II which is distinct from T_1, T_2, T_3 . Then the longitude of T_4 is not H –even. But it is clearly homotopic into $\overline{M \setminus N}$, contradicting the fact that each φ restricted to $\overline{M \setminus N}$ is trivial. Whence T_1, T_2 and T_3 are the only maximal layered solid tori of type II in the triangulation.

Lemma 10. *Assume that $\mathcal{T}$ is minimal and that M is atoroidal. Suppose the edges are coloured by the rank–2 subgroup H of $H^1(M; \mathbb{Z}_2)$, and that precisely two distinct maximal layered solid tori of type II meet in an H –even edge, e . Then e is the only H –even edge in the triangulation which is contained in more than one maximal layered solid torus of type II and M is a Seifert fibred space with base S^2 and precisely three exceptional fibres.*

Proof. Denote the two maximal layered solid tori of type II meeting in e by T_1, T_2 . Then, as above, the boundary of a small regular neighborhood N of $T_1 \cup T_2$ is a (topological) torus and a barrier surface, and it follows that $\overline{M \setminus N}$ is a solid torus. If e is homotopic to a longitude of $\overline{M \setminus N}$, then M admits a Seifert fibration with two exceptional fibres. Hence either M is toroidal or M is a lens space; the first is not possible and the second contradicts the assumption that $H^1(M; \mathbb{Z}_2)$ has rank at least two. Hence e is not homotopic to a longitude of $\overline{M \setminus N}$. Hence, M is a Seifert fibred space with precisely three exceptional fibres, and the base must be S^2 since there are no vertical incompressible tori.

Now assume that T'_1 and T'_2 are two distinct maximal layered solid tori of type II meeting in the H –even edge $e' \neq e$. Then e' cannot be the longitude of either T'_1 nor T'_2 . But this contradicts the fact that the interiors of T'_1 and T'_2 are contained in the solid torus $\overline{M \setminus N}$.

4. Quadrilateral surfaces and Heegaard splittings

Let M denote a closed, orientable, irreducible, connected 3–manifold throughout this section.

4.1. *Quadrilateral surfaces*

Let $\mathcal{T}$ be a triangulation of M . Place three quadrilateral discs in each tetrahedron, one of each type, such that the result is a (possibly branched immersed) normal surface, denoted Q and called the *canonical quadrilateral surface*. The surface Q can be viewed as the image in M of a surface Q' with a cell decomposition into quadrilaterals, and the image of a connected component of Q' will be termed a component of Q .

If S is a component of Q and meets some tetrahedron, σ , in i normal quadrilaterals, $i \in \{0, 1, 2, 3\}$, then the same is true for each tetrahedron meeting σ in a face. Since M is connected, the same is true for every tetrahedron in the triangulation (and in particular $i \neq 0$ since $S \neq \emptyset$). It follows that Q has at most three components.

Suppose that the component S of Q is embedded. Then S meets every tetrahedron in a single quadrilateral disc. Such an embedded normal surface consisting entirely of quadrilateral discs, one in each tetrahedron, is called a *quadrilateral surface*.

Let S be a quadrilateral surface, and let $C(S)$ denote the 1-complex in M consisting of all edges disjoint from S . Notice that S divides each tetrahedron into two prisms. Then $M \setminus C(S)$ is foliated by S and infinitely many copies of the boundary of a regular neighbourhood of S . It follows that $M \setminus S$ is either an open handlebody or the disjoint union of two open handlebodies having the same genus, depending on whether S is non-separating or separating. In particular, S is either a one-sided or a two-sided Heegaard splitting surface for M . A set of discs for the Heegaard splitting is dual to the set of edges in $C(S)$. The disc associated to edge e in $C(S)$ is naturally triangulated with one triangle for each prism in $M \setminus S$ containing e . This system of discs is possibly larger than a standard set of meridian discs if the triangulation has many vertices.

We will now deduce a combinatorial obstruction on the existence of a quadrilateral surface from the Q -matching equations, which were used in the proof of Lemma 2. See [19] and [18], Sections 2.4, 2.5 and 2.9, for more details on the Q -matching equations. Suppose S is a quadrilateral surface in M and let e be an edge, which S meets. Since S meets each tetrahedron in a single quadrilateral disc, and e is incident with as many quadrilateral discs of positive slope as of negative slope, it follows that e must have even degree. In particular, if the canonical quadrilateral surface Q has three components, then each is a quadrilateral surface and it follows that every edge in the triangulation has even degree.

It follows from this discussion that the existence of a canonical quadrilateral surface Q with three components places strong constraints on the Heegaard diagram associated to each of its components. For instance, (1) the intersection of component S with any of the two other components of Q is a spine for S ; and (2) since edges dual to the other surfaces must be of even order, it follows

that each meridian on S contains an even number of intersections with itself and other meridians.

4.2. Heegaard splittings

The above construction of a Heegaard splitting from a quadrilateral surface can be reversed. Given the one-sided (resp. two-sided) Heegaard splitting surface S for M , choose a complete system of meridian discs. Then S together with the discs is a simple spine for the once (resp. twice) punctured manifold. The usual dual cell decomposition gives a triangulation with one (resp. two) vertices and one tetrahedron for each intersection point of the meridians. Moreover, S sits in this triangulation as a quadrilateral surface.

It follows that the complexity of M gives a lower bound for the complexity of a Heegaard splitting. In case of a two-sided Heegaard splitting, these complexities will not coincide unless M has a two-vertex minimal triangulation. But then $M = S^3, \mathbb{R}P^3$ or $L(3, 1)$, whence the complexities only coincide for $M = S^3$. In contrast, the minimal triangulations in [5] and [6] are all dual to one-sided Heegaard splittings and hence determine least complexity one-sided Heegaard splittings.

4.3. Consequences for one-vertex triangulations

Lemma 11. *Let M be a closed, orientable, irreducible, connected 3–manifold with one-vertex triangulation $\mathcal{T}$. If the canonical quadrilateral surface Q has three components, Q_1, Q_2, Q_3 , then each Q_i is dual to some element $0 \neq \varphi_i \in H^1(M; \mathbb{Z}_2)$, and $\langle \varphi_1, \varphi_2, \varphi_3 \rangle \cong \mathbb{Z}_2 \oplus \mathbb{Z}_2$. Moreover,*

$$|\mathcal{T}| + \sum \chi(Q_i) = 2.$$

Proof. Let v denote the single vertex. Each component of Q is non-separating. Since $\pi_1(M; v)$ is generated by the edges, an element $\varphi_i \in H^1(M; \mathbb{Z}_2)$ is defined by letting $\varphi_i[e] = 0$ if e is contained in $M \setminus Q_i$, and $\varphi_i[e] = 1$ otherwise. Hence $\varphi_i \neq 0$ and $\varphi_i + \varphi_j = \varphi_k$, where all three indices are distinct. In particular, $H^1(M; \mathbb{Z}_2)$ has rank at least two. The first equation follows from a simple Euler characteristic argument.

5. Proofs of the main results

Let M be a closed, orientable, irreducible, connected 3–manifold with minimal triangulation $\mathcal{T}$. Suppose that there is a rank–2 subgroup H of $H^1(M; \mathbb{Z}_2)$. Then every minimal triangulation of M is 0–efficient. In particular, there are no normal projective planes, and every normal 2–sphere is vertex linking.

Fig. 3. Edge flip: Labels indicate the changes in edge degree

5.1. Promoting triangulations using edge flips

The material of this subsection refines the argument in the proof of Theorem 5 in [5]. A maximal layered solid torus is *supportive* if it is of type II and each H -even edge incident with it has M -degree at most four. A maximal layered solid torus is *almost supportive* if it is of type II and each H -even edge incident with it has M -degree at most four except for one H -even edge which has M -degree five. A maximal layered solid torus is of *type (II,4)* if it is of type II and its H -even boundary edge has M -degree four. Every supportive maximal layered solid torus is of type (II,4). A minimal triangulation is termed *(II,4)-free* if it does not contain any maximal layered solid torus of type (II,4).

An *edge flip* is the replacement of an edge of degree four which is incident with four distinct tetrahedra by another edge incident with four distinct tetrahedra, see Figure 3. An edge flip may change the triangulation and the degree sequence associated to the edges, but it does not alter the number of tetrahedra.

Lemma 12. *Let M be a closed, orientable, irreducible 3-manifold with minimal triangulation $\mathcal{T}$. Suppose that all edge loops are coloured by the rank-2 subgroup H of $H^1(M; \mathbb{Z}_2)$. Then there is a minimal triangulation which is (II,4)-free and which is obtained from $\mathcal{T}$ by a finite number of edge flips.*

Proof. Let T be a maximal layered solid torus of type (II,4). Lemma 6 implies that e is the univalent edge of T , and that it is contained in four distinct tetrahedra in the triangulation. The argument proceeds by replacing the four tetrahedra around e by a different constellation of four tetrahedra using an appropriate edge flip. The resulting triangulation is also minimal, and it is shown to either contain fewer maximal layered solid tori of type (II,4) or fewer tetrahedra of type IV. Since both of these numbers are finite, we arrive at a (II,4)-free minimal triangulation after a finite number of edge flips.

It remains to describe the re-triangulation process. There are various different cases to consider; they are listed below using the types of tetrahedra ordered cyclically around the edge e , starting with the supportive maximal layered solid

torus T . The arguments given in [5], Proof of Theorem 5 on pages 173–175, apply almost verbatim, and we therefore merely list the case in [5], the corresponding neighbourhoods and the appropriate flip.

(1,1,1,1) in [5]: Corresponds to (II,II,II,II), (II,II,I,I), (II,I,II,I), (II, I,I,II), (II,I,I,I); any edge flip decreases the total number of maximal layered solid tori of type (II,4).

(1,2,2,1) in [5]: Corresponds to (II,III,III,II), (II, III, III, I); the edge flip with the property that the H –even edges (other than e) contained in the faces of the type II tetrahedra remain of the same degree decreases the total number of maximal layered solid tori of type (II,4).

(1,1,2,2) in [5]: Corresponds to (II,II,III,III), (II, I, III, III); the edge flip with the property that the H –even edges (other than e) contained in the faces of the type II tetrahedra remain of the same degree decreases the total number of maximal layered solid tori of type (II,4).

(1,2,3,2) in [5]: Corresponds to (II, III, IV, III); any edge flip reduces the number of tetrahedra of type IV.

5.2. Controlling triangulations using degree three edges

The proof of the following lemma contains a more explicit analysis which is not contained in the statement.

Lemma 13. *Let M be a closed, orientable, irreducible 3–manifold with minimal triangulation $\mathcal{T}$. Suppose that all edge loops are coloured by the rank–2 subgroup H of $H^1(M; \mathbb{Z}_2)$ and that $\mathcal{T}$ is (II,4)–free. Letting ϵ_d denote the number of H –even edges of degree d , we have:*

$$\epsilon_3 < 2 + \sum_{d=5}^{\infty} (d-4)\epsilon_d. \quad (5.1)$$

Proof. Assume, by way of contradiction, that

$$\epsilon_3 \geq 2 + \sum_{d=5}^{\infty} (d-4)\epsilon_d. \quad (5.2)$$

The argument refines the counting argument in the proof of Theorem 5 in [5]. Each edge of degree three is H –even, so (5.2) implies that there are at least two edges of degree three. Since the triangulation contains at least three tetrahedra, it follows from Proposition 9 in [5] that each edge of degree three, e , is the base edge of a layered solid torus subcomplex isomorphic to $\mathcal{S}_2 = \{4, 3, 1\}$. This subcomplex is contained in a unique maximal layered solid torus, $T(e)$. Conversely, if a maximal layered solid torus, T , contains an edge, e , of degree three, then e is unique and we write $e = e(T)$; otherwise, we let $e(T) = \emptyset$.

It follows from Lemma 5 that any two distinct maximal layered solid tori share at most an edge. We seek a contradiction guided by inequality (5.2). The proof, a basic counting argument, is organised as follows. The set of all edges of degree three, Y , is divided into pairwise disjoint subsets; denote the set of these subsets $S(Y)$. The set of all H -even edges, X , is similarly divided into pairwise disjoint subsets, giving a set $S(X)$. In defining these subsets, we also define an injective map $S(Y) \rightarrow S(X)$. If $Y_i \in S(Y)$ is associated with $X_i \in S(X)$, then the quantity

$$|Y_i| - \sum_{e \in X_i} (d(e) - 4)$$

is termed a *deficit* if it is negative, a *cancellation* if it is zero, and a *gain* if it is positive. Then (5.2) implies that the total gain is at least two.

Let $e \in Y$ such that $T(e)$ is of type IV. Then $\mathcal{S}_2 \cong T_0 \subseteq T(e)$. Denote e_0 the longitude of T_0 . This is a 0-even boundary edge with T_0 -degree 5 and M -degree $5 + m$ for some $m \geq 1$. The total number of maximal layered solid tori in M meeting in e_0 is bounded above by $\frac{m+1}{2}$, since no two meet in more than an edge. Hence the maximal layered solid tori containing a degree three edge and meeting in the 0-even edge e_0 contribute at most $\frac{m+1}{2}$ to the left hand side of (5.2). The contribution of e_0 to the right hand side is $d(e_0) - 4 = 1 + m$. One therefore obtains a *deficit* less or equal to $-\frac{m+1}{2}$. To $X_0 = \{e_0\}$ associate the set, Y_0 , of all degree three edges e' such that $T(e')$ contains e_0 .

We now proceed inductively. Let e be an edge of degree three such that $T(e)$ is of type IV and e is not contained in the collection of subsets $Y_0, \dots, Y_{i-1}$ of Y . Then $T(e)$ contains a subcomplex isomorphic to $\mathcal{S}_2$, whose longitude, e_i , cannot be any of the edges $e_0, \dots, e_{i-1}$. Consider the set Y_i of all degree three edges e' such that $T(e')$ contains e_i and e' is not contained in any of $Y_0, \dots, Y_{i-1}$. Then the above calculation shows that there is a deficit associated to $X_i = \{e_i\}$ and Y_i .

It follows that there must also be a maximal layered solid torus of type II which contains an edge of degree three not in $\cup Y_i$. Let T be such a maximal layered solid torus, and let e be its unique 0-even boundary edge. Since $\mathcal{T}$ is (II,4)-free, we have $d(e) \geq 5$. If e is the longitude of a maximal layered solid torus of type IV, then $e(T)$ is contained in one of the sets Y_i . Hence assume this is not the case. We make the following observations (with the amount of detail useful for future applications):

1. If e is not incident with another maximal layered solid torus of type II containing a degree three edge, and T is almost supportive, then $\{e\}$ is associated with $\{e(T)\}$ and gives a cancellation.
2. If e is not incident with another maximal layered solid torus of type II containing a degree three edge, and T is not almost supportive, then T also has an H -even interior edge, e_T , of degree at least five. Hence associate $\{e, e_T\}$ with $\{e(T)\}$, giving a deficit.

3. Suppose T_1 is the unique maximal layered solid torus of type II containing a degree three edge which meets T in e .
 (3a) Assume that no other maximal layered solid torus of type II contains e . Then Lemma 10 implies that T, T_1 are the only maximal layered solid tori of type II meeting in an H –even edge.
 If $d(e) \geq 7$, then $\{e\}$ is associated with $\{e(T), e(T_1)\}$ and we have a deficit.
 If $d(e) = 6$ and one of T, T_1 contains an H –even interior edge, e' of degree at least five, then $\{e, e'\}$ is associated with $\{e(T), e(T_1)\}$ and gives a deficit. If $d(e) = 6$ and all H –even interior edges of T, T_1 are of degree four, then $\{e\}$ is associated with $\{e(T), e(T_1)\}$ and gives a cancellation.
 If $d(e) = 5$ and both T, T_1 are almost supportive, then $\{e\}$ is associated with $\{e(T), e(T_1)\}$ and gives a gain of $+1$. If $d(e) = 5$ and one of T, T_1 is almost supportive and the other contains a unique H –even interior edge e' of degree five and all others have degree four, then $\{e, e'\}$ is associated with $\{e(T), e(T_1)\}$ and gives a cancellation. Otherwise a deficit is associated with at most three H –even edges. If $d(e) = 5$ and neither of T, T_1 is almost supportive, then there are distinct H –even interior edges, e', e'' of degrees at least five and $\{e, e', e''\}$ is associated with $\{e(T), e(T_1)\}$ and gives a deficit.
 (3b) Suppose the maximal layered solid torus of type II T_2 meets T and T_1 in e . Lemma 9 implies that T, T_1, T_2 are the only maximal layered solid tori of type II in the triangulation. Hence $Y = \cup Y_i \cup \{e(T), e(T_1)\}$. Since no two of the three can meet in a face, we have $d(e) \geq 6$. It follows that there is a cancellation if all H –even interior edges have degree four, and a deficit associated to e together with a collection of interior edges otherwise.
4. Suppose T_1 and T_2 are distinct maximal layered solid tori of type II containing degree three edges meeting T in e . Now $Y = \cup Y_i \cup \{e(T), e(T_1), e(T_2)\}$ and $d(e) \geq 6$ as above. Hence e together with a collection of interior edges can be associated with $\{e(T), e(T_1), e(T_2)\}$ giving a deficit unless one of the following cases occurs. If $d(e) = 7$ and every H –even interior edge of T, T_1, T_2 has degree four, then there is a cancellation. If $d(e) = 6$ and every H –even interior edge of T, T_1, T_2 has degree four, then there is a gain of $+1$. If $d(e) = 6$ and there is precisely one H –even interior edge of degree five and all others have degree four, then there is a cancellation.

It follows that the maximal gain which can be achieved is $+1$; whence (5.2) cannot be satisfied.

5.3. Proofs of the main results

Proposition 1. *Let M be a closed, orientable, irreducible 3–manifold with minimal triangulation $\mathcal{T}$. Suppose that H is a rank–2 subgroup of $H^1(M; \mathbb{Z}_2)$. Then*

$$|\mathcal{T}| \geq 2 + \sum_{0 \neq \varphi \in H} \|\varphi\|.$$

Suppose further that all edge loops are coloured by H and that $\mathcal{T}$ is $(II,4)$ -free. Then

$$|\mathcal{T}| - \sum_{0 \neq \varphi \in H} \|\varphi\| \geq |\mathcal{T}| + \sum_{0 \neq \varphi \in H} \chi(S_\varphi) \geq 2.$$

Proof. First replace $\mathcal{T}$ by a $(II,4)$ -free minimal triangulation, $\mathcal{T}_0$. Then $|\mathcal{T}| = |\mathcal{T}_0|$. If $|\mathcal{T}_0| + \sum \chi(S_\varphi) \leq 1$, then equation (2.3) in Lemma 4 and inequality (5.1) in Lemma 13 give a contradiction. Hence

$$|\mathcal{T}_0| - \sum_{0 \neq \varphi \in H} \|\varphi\| \geq |\mathcal{T}_0| + \sum_{0 \neq \varphi \in H} \chi(S_\varphi) \geq 2,$$

where the first inequality follows from Lemma 1.

The first part of the above proposition directly implies Theorem 1 by definition of a minimal triangulation. The implication (2) $\implies$ (1) in Theorem 2 is a consequence of Lemma 11 and Theorem 1. The reverse is contained in the following statement:

Proposition 2. *Let M be a closed, orientable, irreducible 3-manifold with arbitrary one-vertex triangulation $\mathcal{T}$. Suppose that H is a rank-2 subgroup of $H^1(M; \mathbb{Z}_2)$ and that*

$$|\mathcal{T}| = 2 + \sum_{0 \neq \varphi \in H} \|\varphi\|.$$

Then $\mathcal{T}$ is minimal. Moreover, every minimal triangulation of M has the property that each canonical surface dual to a non-zero element of H is a $\mathbb{Z}_2$ -taut quadrilateral surface.

Proof. Every minimal triangulation of M has a single vertex. Let $\mathcal{T}_0$ be a minimal triangulation which is $(II,4)$ -free with respect to the colouring of edges by H , and denote S_i the dual surfaces. Then

$$2 \leq |\mathcal{T}_0| + \sum \chi(S_i) \leq |\mathcal{T}| - \sum \|\varphi_i\| = 2$$

by Proposition 1 and Lemma 1. This forces equality and since $|\mathcal{T}_0| \leq |\mathcal{T}|$ and $\chi(S_i) \leq -\|\varphi_i\|$, we have equality for all terms. In particular, $\mathcal{T}$ is minimal and each canonical surface is taut.

Lemma 4 implies that $A(\mathcal{T}_0) + C(\mathcal{T}_0) \leq 1$, and using Lemma 3, this implies $E(\mathcal{T}_0) = |\mathcal{T}_0|$. This gives the desired conclusion for a $(II,4)$ -free minimal triangulation. Given an arbitrary minimal triangulation which is not $(II,4)$ -free, one may perform a finite sequence of edge flips to arrive at a $(II,4)$ -free minimal triangulation. The latter must have an edge of degree four which is contained in four distinct tetrahedra. Since each tetrahedron is of type V, there is an embedded disc in M which meets one of the canonical surfaces, say S_i , in precisely its boundary. If this is a trivial disc for S_i , then there is an embedded sphere in M

Fig. 4. The twisted layered loop triangulation

meeting some edge loop in precisely one point, contradicting the fact that M is irreducible. If this is a compression disc for S_i , then it contradicts the fact that it is taut. This completes the proof.

Remark 1. Under the hypothesis of Proposition 2, if there is a rank-2 subgroup $G \neq H$, then

$$\sum_{0 \neq \varphi \in G} \|\varphi\| < \sum_{0 \neq \varphi \in H} \|\varphi\|.$$

6. The twisted layered loop triangulation

This section shows that the twisted layered loop triangulation of $M_k = S^3/Q_{4k}$, $k \geq 1$, satisfies the hypothesis of Theorem 2 when k is even. If k is odd, then $H_1(M_k; \mathbb{Z}) = \mathbb{Z}\mathbb{Z}_4$ and the results of this paper do not apply.

6.1. The twisted layered loop triangulation

Starting point is the triangulation with two faces of the annulus shown with labelling in Figure 4. The edges corresponding to the two boundary components are denoted t for *top* and b for *bottom*, and oriented so that they correspond to the same element in fundamental group. The remaining two edges are e_1 and e_2 , oriented from t to b . Tetrahedron σ_1 is layered along e_1 , and the new edge denoted e_3 and oriented from t to b . The annulus is thus identified with two faces of σ_1 . Inductively, tetrahedron σ_h is layered along edge e_h , and the new edge e_{h+2} is oriented from t to b . Assume k tetrahedra have thus been attached; if $k = 0$ we have an annulus, if $k = 1$ a creased solid torus and if $k \geq 2$ a solid torus. Denote the resulting triangulation C_k .

The two free faces of tetrahedron σ_k in C_k are identified with the two free faces of tetrahedron σ_1 such that σ_1 is layered along e_{k+1} with $e_1 \leftrightarrow -e_{k+1}$, $e_2 \leftrightarrow -e_{k+2}$ and $t \leftrightarrow -b$. The result is M_k (see [1], Theorem 3.3.11, or [6]), and the triangulation, denoted $\hat{C}_k$, is termed its *twisted layered loop triangulation*.

6.2. One-sided incompressible surfaces

Note that there is a normal, one-sided Klein bottle, S_1 , in M_k , obtained by placing a quadrilateral in each tetrahedron dual to the edge t . When k is even, then there are two more embedded normal surfaces, S_2 and S_3 , just containing quadrilateral discs. One is dual to the set of all edges e_i , where i is even; the other is dual to the set of all edges e_i where i is odd. We have that $M_k \setminus S_1$ is a torus; and $M_k \setminus S_2$ and $M_k \setminus S_3$ are genus $\frac{k}{2}$ handlebodies. Using singular homology with $\mathbb{Z}_2$ -coefficients, the intersection pairing induces homomorphisms $\varphi_i: \pi_1(M_k) \rightarrow \mathbb{Z}_2$ defined by:

$$\begin{aligned} \varphi_1[e_i] &= 1 \text{ for each } i \text{ and } \varphi_1[t] = 0. \\ \varphi_2[e_i] &= 0 \text{ if } i \text{ is even, } \varphi_2[e_i] = 1 \text{ if } i \text{ is odd and } \varphi_2[t] = 1; \\ \varphi_3[e_i] &= 0 \text{ if } i \text{ is odd, } \varphi_3[e_i] = 1 \text{ if } i \text{ is even and } \varphi_3[t] = 1. \end{aligned}$$

We have $\varphi_1 + \varphi_2 = \varphi_3$, and $H^1(M; \mathbb{Z}_2) = \langle \varphi_1, \varphi_2 \rangle$. Since S_i is dual to φ_i , it follows that we have found a representative for each non-trivial $\mathbb{Z}_2$ -cohomology class. To show that the triangulation satisfies the hypothesis of Theorem 2, we need to show that these surfaces are in fact representatives of minimal genus. This follows from the following application of work by Waldhausen [20], Rubinstein [16] and Frohman [2].

Lemma 14. *If k is even, then S_1, S_2 and S_3 are, up to isotopy, the only connected, one-sided incompressible surfaces in M_k .*

Proof. Let N_1 be a small regular neighbourhood of S_1 in M_k . Then N_1 is a twisted I -bundle over the Klein bottle. Moreover, N_1 is homeomorphic to the S^1 -bundle over the Möbius band with orientable total space. This has a Seifert fibration over the disc with two cone points of order two. Denote the base orbifold D , its cone points p_1 and p_2 , and the fibration $p: N_1 \rightarrow D$. Equivalently, this description of N_1 can be obtained by cutting $M_k = S^2((2, 1), (2, 1), (k, 1 - k))$ along the vertical torus which is the pre-image of the boundary of a small regular neighbourhood of the cone point labelled $(k, 1 - k)$.

Waldhausen ([20], Section 3) showed that the only connected, two-sided incompressible and non-boundary parallel surfaces in N_1 are a vertical annulus which is the pre-image of a properly embedded arc in D separating p_1 and p_2 ; and a horizontal annulus which is a branched double cover of D . Using the methods of Frohman [2], one can similarly show that the only connected, one-sided incompressible surfaces in N_1 are a Klein bottle, K , (which is the pre-image in N_1 of an arc in D joining p_1 and p_2) as well as two Möbius bands, B_1 and B_2 , (where B_i is the pre-image in N_1 of an arc in D joining p_i to ∂D). Note that the Möbius bands have parallel boundary curves on ∂N_1 .

Similarly, it is known through the work of Waldhausen ([20], Section 2) that a connected, two-sided incompressible surface in the solid torus $M_k \setminus N_1$ is either a meridian disc or a boundary-parallel disc or annulus. Rubinstein [16] showed

that a one-sided incompressible surface in $M_k \setminus N_1$ has boundary a single curve which uniquely determines the surface up to isotopy.

Suppose S is a connected, one-sided, incompressible surface in M_k , and isotope S such that it meets ∂N_1 minimally in a collection of pairwise disjoint curves. Then $S \cap \partial N_1$ is either empty or consists of finitely many parallel, essential curves on ∂N_1 .

If $S \cap \partial N_1 = \emptyset$, then $S = K$, since the complement of N_1 is a solid torus. Hence assume $S \cap \partial N_1 \neq \emptyset$. We have that $S \cap N_1$ (respectively $S \cap (M_k \setminus N_1)$) is incompressible in N_1 (respectively $M_k \setminus N_1$).

First assume that $S \cap N_1$ is two-sided. Then $S \cap N_1$ is a family of parallel annuli and $S \cap \partial N_1$ has an even number of components. It follows that $S \cap (M_k \setminus N_1)$ must also be a family of parallel annuli. Since an outermost annulus in the latter family is boundary compressible, there is an isotopy of S reducing the number of curves in $S \cap \partial N_1$. This contradicts the assumption that S meets ∂N_1 minimally.

Hence assume that $S \cap N_1$ is one-sided. It follows that S is either B_1 , B_2 or $B_1 \cup B_2$. If $S \cap N_1$ is B_1 or B_2 , then $S \cap (M_k \setminus N_1)$ has a single boundary component and hence is a uniquely determined incompressible one-sided surface, F . If $S \cap N_1 = B_1 \cup B_2$, then $S \cap (M_k \setminus N_1)$ is a boundary parallel annulus, and there is an isotopy making $S \cap \partial N_1 = \emptyset$, which contradicts the assumption that S meets ∂N_1 minimally.

It follows that, up to isotopy, a connected, one-sided, incompressible surfaces in M_k is one of K , $B_1 \cup F$ and $B_2 \cup F$. Since $H^1(M; \mathbb{Z}_2)$ has rank two, each of these three surfaces must be incompressible.

It follows from the construction that $K = S_1$. We claim that, up to re-labeling, $S_2 = B_1 \cup F$ and $S_3 = B_2 \cup F$. Notice that the boundary curve of F is a regular fibre, and hence a $(k, 1)$ -curve on $M_k \setminus N_1$ with respect to the standard longitude and meridian. It now follows from [16] (see also [2] and [4]) that

$$\chi(S_2) = \chi(S_3) = \chi(B_1 \cup F) = \chi(B_2 \cup F).$$

This completes the proof.

References

1. Benjamin A. Burton: *Minimal triangulations and normal surfaces*, PhD thesis, The University of Melbourne, 2003.
2. Charles Frohman: *One-sided incompressible surfaces in Seifert fibered spaces*, Topology Appl. 23 (1986), no. 2, 103–116.
3. William Jaco and J. Hyam Rubinstein: *0-efficient triangulations of 3-manifolds*, Journal of Differential Geometry 65 (2003), no. 1, 61–168.
4. William Jaco and J. Hyam Rubinstein: *Layered-triangulations of 3-manifolds*, available at arXiv:math/0603601.

5. William Jaco, J. Hyam Rubinstein and Stephan Tillmann: *Minimal triangulations for an infinite family of lens spaces*, Journal of Topology 2 (2009) 157-180.
6. William Jaco, J. Hyam Rubinstein and Stephan Tillmann: *Coverings and minimal triangulations of 3-manifolds*, Algebraic and Geometric Topology, 11(3) (2011), 1257–1265.
7. Ensil Kang and J. Hyam Rubinstein: *Ideal triangulations of 3-manifolds I: spun normal surface theory*, Geometry and Topology Monographs, Vol. 7 , Proceedings of the Casson Fest, 235–265 (2004).
8. Bruno Martelli and Carlo Petronio: *Three-Manifolds Having Complexity At Most 9*, Experimental Mathematics 10 (2001), 207-237.
9. Sergei V. Matveev: *Complexity theory of three-dimensional manifolds*, Acta Appl. Math. 19 (1990), no. 2, 101–130.
10. Sergei V. Matveev: *Complexity of three-dimensional manifolds: problems and results*, Siberian Adv. Math. 13 (2003), no. 3, 95–103.
11. Sergei V. Matveev: *Recognition and tabulation of three-dimensional manifolds*, (Russian) Dokl. Akad. Nauk 400 (2005), no. 1, 26–28.
12. Sergei V. Matveev: *Tabulation of three-dimensional manifolds*, Russian Math. Surveys 60 (2005), no. 4, 673–698.
13. Sergei V. Matveev: *Algorithmic topology and classification of 3-manifolds*. Second edition. Algorithms and Computation in Mathematics, 9, Berlin, 2007.
14. Sergei V. Matveev and Ekaterina L. Pervova: *Lower bounds for the complexity of three-dimensional manifolds*, (Russian) Dokl. Akad. Nauk 378 (2001), no. 2, 151–152.
15. Sergei V. Matveev, Carlo Petronio and Andrei Vesnin: *Two-sided asymptotic bounds for the complexity of some closed hyperbolic three-manifolds*, to appear in the Journal of the Australian Mathematical Society, arXiv:math/0602372v1.
16. J. Hyam Rubinstein: *One-sided Heegaard splittings of 3-manifolds*, Pacific J. Math. 76 (1978), no. 1, 185–200.
17. W. Thurston: *A norm for the homology of 3-manifolds*. Mem. Amer. Math. Soc. 59 (1986), no. 339, i–vi and 99–130.
18. Stephan Tillmann: *Normal surfaces in topologically finite 3-manifolds*, L'Enseignement Mathématique (2) 54 (2008), 329–380.
19. Jeffrey L. Tollefson: *Normal surface Q -theory*, Pacific J. of Math. 183 (1998), 359-374.
20. Friedhelm Waldhausen: *Eine Klasse von 3-dimensionalen Mannigfaltigkeiten I, II*, Invent. Math. 3 (1967), 308–333; *ibid.* 4 1967 87–117.

Minerva Access is the Institutional Repository of The University of Melbourne

Author/s:

Jaco, W;Rubinstein, JH;Tillmann, S

Title:

Z(2)-Thurston norm and complexity of 3-manifolds

Date:

2013-05-01

Citation:

Jaco, W., Rubinstein, J. H. & Tillmann, S. (2013). Z(2)-Thurston norm and complexity of 3-manifolds. MATHEMATISCHE ANNALEN, 356 (1), pp.1-22. <https://doi.org/10.1007/s00208-012-0824-y>.

Persistent Link:

<http://hdl.handle.net/11343/282528>