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Author/s:

Prathumrat, P;Sbarski, I;Hajizadeh, E;Nikzad, M

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1 A comparative study of force fields for predicting shape memory properties of liquid
2 crystalline elastomers using molecular dynamic simulations

3 P. Prathumrat,¹ I. Sbarski,¹ E. Hajizadeh,² and M. Nikzad^{1,a)}

4 **AFFILIATIONS**

5 ¹Department of Mechanical and Product Design Engineering, Faculty of Science, Engineering and Technology,
6 Swinburne University of Technology, John Street, Hawthorn, VIC 3122, Australia

7 ²Department of Mechanical Engineering, Faculty of Engineering and Information Technology, University of
8 Melbourne, Parkville, VIC 3010, Australia

9 ^{a)}Author to whom correspondence should be addressed: mnikzad@swin.edu.au

10 **ABSTRACT**

11 Molecular dynamic (MD) simulation techniques are increasingly being adopted as efficient computational
12 tools to design novel and exotic classes of materials for which traditional methods of synthesis and prototyping are
13 either too costly, unsafe, and time-consuming in laboratory settings. Of such class of materials are liquid crystalline
14 elastomers (LCEs) with favorable shape memory characteristics. These materials exhibit some distinct properties,
15 including stimuli responsiveness to heat or UV and appropriate molecular structure for shape memory behaviors. In
16 this work, the MD simulations were employed to compare and assess the leading force fields currently available for
17 modeling the behavior of a typical LCE system. Three force fields, including Dreiding, PCFF, and SciPCFF, were
18 separately assigned to model the LCE system, and their suitability was validated through experimental results. Among
19 these selected force fields, the SciPCFF produced the best agreement with the experimentally measured thermal and
20 viscoelastic properties compared to those of the simulated steady-state density, transition temperature, and viscoelastic
21 characteristics. Next, shape fixity (R_f) and shape recovery (R_r) of LCEs were estimated using this force field. A four-
22 step simulated shape memory procedure proceeded under a tensile mode. The changes in molecular conformations
23 were calculated for R_f and R_r after the unloading step and reheating step. The results revealed that the model LCE
24 system exhibit characteristic behaviors of R_f and R_r over the thermomechanical shape memory process, confirming
25 the suitability of selected force field for use in the design and prediction of properties of typical LCE class of polymers.

26 **I. INTRODUCTION**

27 Shape memory elastomers (SMEs) are a significant member of intelligent polymers which can be deformed
28 to another temporary shape and subsequently recovered to their permanent shape again.^{1,2} This process is typically
29 achieved through an applied load and forms of trigger by an external stimulus.³ Currently, a variety of external stimuli
30 are utilized to activate shape memory effects, including heat⁴, pH⁵, water⁶, UV light⁷, or electric and magnetic fields^{8,9}.
31 Among these, heat is the most commonly used stimulus. Furthermore, molecular architecture of these materials,
32 containing net-points (hard phase) and switch units (soft phase), is the crucial determining factor which promotes the
33 shape memory behavior.¹⁰ The net-points responsible for maintaining the permanent shape are generated by covalent

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1 or physical crosslinks.^{11,12} Whereas, the switch units are responsible for maintaining the temporary shape as well as
2 recovering the permanent shape through transition temperature.¹³ Therefore, these smart-functional SMEs can be
3 employed in a broad spectrum of applications such as medical devices^{14,15}, tissue engineering and soft robotics^{16,17},
4 smart actuators¹⁸, scaffold materials¹⁹, and textiles²⁰.

5 Liquid crystalline elastomers (LCEs) serve as a distinct class of stimuli-responsive materials that contain the
6 ability to promote shape deformation by heat or UV activation.²¹⁻²³ These materials are a particular type of polymers
7 that contain the characteristics between solid crystalline materials and disordered liquids over a well-defined
8 temperature range.²⁴ The molecular structure of these materials consists of both hard and soft segments, enabling the
9 shape memory behaviors. Furthermore, transition temperature (T_{tran}) is an important parameter that plays a vital role
10 in the shape memory process. This parameter will serve as the switching point in the shape deformation step as well
11 as the recovery step. The LCEs naturally have several phase transitions, including the change from crystalline solid-
12 to-liquid-crystal (SLC) state followed by liquid-crystal-to-isotropic (LCI) state. Typically, majority of LCE materials
13 show at least two distinct transition phases, manifested through two transition temperatures (T_{tran}), including
14 crystalline-liquid crystal temperature (T_{SCL}) and liquid crystal-isotropic temperature (T_{LCI}). In the liquid crystal state,
15 the orientational order of LCEs can be classified as nematic, smectic, cholesteric, and discotic.²⁵ Among these, the
16 first synthesis of nematic LCEs has been reported by Finkelmann's method.²⁶

17 In the last decade, LCEs have been developed for shape memory function based on variety of polymeric
18 systems, for instance, biphenyl-based epoxy²⁷, polyurethane LCEs (PULCEs)²⁸, as well as reactive mesogens
19 (RM).^{29,30} Among these materials, RM has become an essential nematic LCE member to be utilized as SME due to
20 their ease of processability, excellent thermal, chemical, and mechanical stability.³¹ For example, Traugutt *et al.*³⁰
21 studied the effect of solvent presence on the shape memory characteristics of the LCEs based on 1,4-bis[4-(3-
22 acryloyloxypropylpropyloxy) benzoyl-oxy]-2-methylbenzene (RM257), which were synthesized with 2,2'-
23 (ethylenedioxy)diethanethiol (EDDET) and pentaerythritol tetra (3-mercaptopropionate) (PETMP). The LCE
24 synthesized in the presence of the solvent possessed an R_f of 62.8% and R_r of 99.5%, greater than the case without the
25 solvent. Meanwhile, Barnes and Verduzco³² studied the shape fixity and actuation as well as shape programming
26 behaviors of the RM257 synthesized through a two-step polymerization process in the presence of PETMP. These
27 studies highlight the LCEs based on RM257 as a promising class of polymers with further potential to develop and be
28 utilized for their shape memory functionalities, which can include applications such as artificial muscles for
29 bioengineering and controlled actuations of flaps and wings in aerospace engineering.^{33,34}

30 With recent developments in materials simulation techniques and computational power, we now have a
31 powerful arsenal to tackle troubles associated with the common ad hoc trial-and-error experimental material
32 development approaches. Among these materials simulation methods, the molecular dynamic (MD) simulation
33 techniques offer a robust method that could potentially perform an essential role in predicting the macroscopic
34 behavior of materials from their microscopic structure, including their shape memory characteristics.^{35,36} In the MD
35 simulation process, the force field, which defines the inter- and intramolecular interaction potentials in the materials
36 system, plays a central role in capturing the accurate time and length scales associated with molecular processes

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1 determining the macroscopic behavior of the material.^{35,37,38} Recently, this technique has been used to investigate
2 material properties and reproduce some experiments involving main-chain and side-chain LCEs.^{39,40} Moreover,
3 several computational studies have been performed for the purpose of investigating the shape memory effects, where
4 depending on the polymeric system, different types of force fields have been employed. For instance, Diani and Gall⁴¹
5 implemented full-atomistic MD simulations using COMPASS (Condensed-phase Optimized Molecular Potential for
6 Atomistic Simulation Studies) force field to compare energy changes and strain recovery of natural rubber (cis-
7 polyisoprene) during the shape memory process. Their results revealed that this polymeric material can be fixed after
8 a uniaxial stretch below its T_g and recovered above its T_g . The conformational changes in this model polymer were
9 dictated by changes in entropy. Moon *et al.*⁴² performed an all-atom MD simulation of polystyrene (PS) to investigate
10 the role of its initial orientational order on recovery behaviors, with the adoption of PCFF (Polymer Consistent Force
11 Field). This material indicated excellent R_f of 91.5% and R_r of 48.8% when sample was stretched up to 100% strain.
12 Such a high R_f of this material would be useful in the application of a controllable self-folding material. Yang *et al.*⁴³
13 examined dynamic properties of epoxy networks with Diels-Alder reactions to understand shape memory behaviors
14 in atomistic scale by using the same PCFF potential. This thermosetting model demonstrated a high recovery rate at a
15 temperature of 350 K, which ranges from 0.00013 ps⁻¹ to 0.00026 ps⁻¹, after stretched by 20%. Additionally, Zhang *et*
16 *al.*⁴⁴ also employed PCFF to explore the shape memory properties of amorphous poly(L-lactide) with different
17 molecular weights (M_w). The simulated R_f of PLLA decreased with an increase in M_w and remained in the range of
18 60%. Whereas, the R_r exhibited a value of up to 90%.

19 Nevertheless, very few studies address the suitability of the force field that could accurately capture the
20 structure and dynamics of these material systems. The most robust method to assess the suitability of a given force
21 field is to compare the simulation results of various force fields with the vital experimental characteristics of the same
22 material system. Lately, Wang *et al.*⁴⁵ have optimized the force fields of COMPASS and PCFF for a cellulose model.
23 In their work, steady-state density, the volatility, and repeatability of mechanical properties were the three essential
24 properties explored to compare the accuracy of these force fields. The results confirmed that the predicted properties
25 using COMPASS were in the best agreement with experimental data, resulting in the suitability for MD simulation of
26 this system. Moreover, Sahputra *et al.*⁴⁶ investigated the effects of tacticity, degree of polymerization, and temperature
27 on the elastic properties of poly(methyl methacrylate), (PMMA). The force fields, including Dreiding, AMBER
28 (Assisted Model Building with Energy Refinement), and OPLS (Optimized Potentials for Liquid Simulations), were
29 separately assigned to the model system. Their results indicated that the simulated Young's modulus and T_g by
30 Dreiding were in the closest fit with the experimental value when compared with other force fields. Therefore, to
31 achieve accurate and reliable simulated models of material, it is essential to critically evaluate the suitability of the
32 chosen force field for a particular material system.

33 In this study, given the rapidly evolving nature of the materials simulation techniques and underlying force
34 fields, it is critical that a suitable benchmark is established, and the optimal force field characteristics are identified.
35 Therefore, the MD simulations were utilized to compare the effectiveness of the choices of force fields and their
36 capability to accurately predict the shape memory characteristics of the LCEs through comparison by experimental
37 observations. The LCE based on 1,4-bis[4-(3-acryloyloxypropyl)oxy] benzoyl-oxy]-2-methylbenzene (RM257)

1 was first built in the simulation box and crosslinked with pentaerythritol tetra (3-mercaptopropionate) (PETMP) to
2 form an elastomeric system. The force fields, including Dreiding, PCFF, and SciPCFF, were separately assigned to
3 the simulated models. To conduct the experimental laboratory study, the LCE samples were synthesized to validate
4 the accuracy of the predicted properties.⁴⁷ The material properties for evaluation and validation of the developed
5 models were the steady-state density of the liquid crystalline monomers, the transition temperature of LCEs, and
6 viscoelastic properties of LCEs. The force field, which showed the best agreement with the experimental data, was
7 then adopted to investigate the shape memory characteristics, including R_f and R_r of the elastomeric system.

8 **II. MATERIALS AND METHODS**

9 **A. Materials**

10 The chemicals utilized in this study consisted of a reactive mesogen named 1,4-bis4-(3-
11 acryloyloxypropypropyloxy) benzoyl-oxy] -2-methylbenzene (RM257), which was purchased from Daken Chemical
12 (China). Pentaerythritol tetra (3-mercaptopropionate) (PETMP) based crosslinking agent and dipropyl amine (DPA)
13 based catalyst were purchased from Sigma-Aldrich, Inc. (Australia). Toluene was purchased from Thermo Fisher
14 Scientific Australia PTY LTD (Australia). All materials were used as received without further purification.

15 **B. Synthesis of LCE**

16 The synthesis procedure followed the method of Saed *et al.*⁴⁷ Briefly, powder of RM257 monomer was
17 dissolved in 30 vol% of toluene and heated at 80°C in an oven. The powder was dissolved entirely to be a transparent
18 solution within 5 min. The solution was left to cool down to room temperature before proceeding to the next step. The
19 16 vol% of PETMP was then added and stirred to yield a homogenous mixture. DPA was separately diluted in toluene
20 at a weight ratio of 1:50. Then, the 11 vol% of DPA was added into the monomer mixture, and all the constituents
21 were instantaneously stirred. The solution was subsequently placed in a vacuum oven for 1 min for degassing to
22 remove altogether. The mixture was immediately transferred into the mold and left at room temperature for 24 hrs to
23 cure. After the polymerization was completed, the samples were heated at 80°C for 12 hrs to remove the solvent before
24 characterization.

25 **C. Experimental**

26 A differential scanning calorimeter (DSC) 2960 (TA instruments, USA) was used to characterize the thermal
27 properties, including the transition temperatures of LCEs. The sample mass used was in the range of 5 mg to 10 mg
28 sealed in an aluminum pan. The results were obtained using a heating rate of 5°C/min with temperature ramped up
29 from -40°C to 150°C under a nitrogen flow rate of 110 ml/min.

30 A dynamic mechanical analyzer (DMA) 2980 (TA instruments, USA) with tensile mode was utilized to
31 measure the storage modulus and loss factor (tan delta) of the LCEs. The tests were run at 3°C/min from room
32 temperature to 150°C. The frequency of 1 Hz and an amplitude of 15 μm were assigned for testing.

33

1 **D. MD Simulation Protocol**

2 All MD simulations were performed by using the Materials and Process Simulation (MAPS) software
3 package (Version 4.3.0), developed by Scienomics Inc., France (2018). The simulations were run on the Ozstar High-
4 Performance Cluster (HPC) at the Swinburne University of Technology.

5 The chemical structures of RM257 monomer and PETMP crosslinking agent were built by using the sketching
6 tool on MAPS, as shown in Fig 1. The simulation box of the RM257 monomers was then created by using the
7 Amorphous Builder module. The force fields of Dreiding⁴⁸, PCFF⁴⁹, and SciPCFF (Scienomics Polymer Consistent
8 Force Field) were assigned to separate simulations. The parameters of SciPCFF have been developed by Scienomics
9 Inc. and extended from the PCFF version.^{50,51} A set of equations of molecular interactions of these two force fields
10 are identical, including intramolecular, intermolecular, cross terms as well as quartic expansions of stretch and bend
11 in the potential energy calculations.⁵² The SciPCFF, however, incorporates 9-6 Lennard-Jones (LJ) potentials and the
12 parameters of bond increment of various compounds from COMPASS.⁵³ The model was simulated using LAMMPS⁵⁴
13 and relaxed via stepwise equilibration to conduct geometry minimization. The NVT and NPT ensembles of 1 ns at
14 298 K were then assigned to the system, respectively. The pressure of 1 atm was used in the NPT step. The steady-
15 state density of the liquid crystalline monomer was predicted with different force fields. The simulated density was
16 compared against the experimental density of RM257 monomer reported by the manufacturer, Daken Chemical.

17 The chemical structure of main-chain LCEs was also created using the sketching tool. The four-arm active
18 sites of PETMP (S-H bonds) were sketched to crosslink with the active sites (C=C bonds) at the ends of the RM257
19 structures. These LCE structures were then repeatedly sketched for 10 repeating units. Simulation box was finally then
20 constructed for the LCE structures using the Amorphous Builder module. Prior to calculation, the simulation box
21 included ten chains of the LCE structure were at a temperature of 298K. The final system had the empirical formula
22 of $C_{3810}H_{4040}O_{1240}S_{120}$ with the dimension of $46.642 \times 46.642 \times 46.642 \text{ \AA}^3$. The same simulation protocol, as explained
23 for the monomer model, was carried out for these materials. Briefly, the geometry of the LCE system was optimized
24 by using the steepest descent method for total running steps of 1000. The simulation box was then subjected to a 500
25 ps NVT step at 298 K. Nonbond interactions were conducted with a cutoff distance of 12 \AA . A Nose-Hoover thermostat
26 was required to control the temperature with a damping coefficient of 10 fs. The Ewald summation was set to calculate
27 the Coulomb interactions. Subsequently, the NPT step was run with a dynamic time step of 1 ns. The same time step
28 was used at 298 K under a pressure of 1 atm. The Ewald summation method, and Nose-Hoover thermostat and barostat
29 was used with the same conditions as in the NVT step.

30 After reaching an equilibrium steady-state, transition temperature, and viscoelastic properties for different
31 models were calculated via the MAPS Trajectory Analysis module. The transition temperature was determined as the
32 point where the slope of the plot of fractional free volume (FFV) as a function of temperature changes. Meanwhile,
33 viscoelastic properties of the LCEs, including actual and relative storage moduli, and tan delta, were investigated from
34 components of the stress tensor using Trajectory Analysis module after the further NPT run of 10 ns with an amplitude
35 of 0.4 \AA and period of shear of 5.0 ps.

1 **E. Simulation of shape memory**

2 After the completion of force field comparison and selection, the simulated system with the best-agreed force
3 field, was subjected to the four-step procedure of shape memory process.⁴⁴

4 First, in the loading step, the model was introduced into an NPT ensemble with a temperature of 400 K and
5 pressure of 1 atm. The uni-directional elongation was done in this step by stretching the simulation box with 10%
6 strain in the X direction, resulting in the deformation of the molecular chains. The duration of the run of 5 ns was used.
7 This is followed by a cooling step to freeze the stretched cell under an NVT ensemble for 500 ps at 298 K. Next, the
8 stored energy was released in the unloading step in an NPT ensemble. This step was set respectively under the
9 temperature and pressure of 298 K and 1 atm with a duration of 1 ns. Finally, the reheating step was run under the
10 NPT ensemble at 450 K with a pressure of 1 atm to relax the structure. A duration of 10 ns with a time step of 0.5 fs
11 was set in this step. The R_f and R_r were calculated using the strain data via Equations 1 and 2.

$$12 \qquad R_f = \frac{l_u}{l_m} \times 100\% \qquad (1)$$

$$13 \qquad R_r = \frac{l_m - l_p(N)}{l_m - l_p(N-1)} \times 100\% \qquad (2)$$

14 Where l_u is the fixed strain of the simulation box after stress relaxation, l_m is the maximum strain applied, l_p is the
15 residual strain after the recovery process, and N is the number of the cycles.

16

17 **III. RESULTS AND DISCUSSION**

18 **A. Steady-state density analysis of the monomer model**

19 Fig. 1 illustrates the structural models of RM257 and PETMP monomers, constructed according to Section
20 II. The structure of the crosslinked main-chain LCEs were built through a two-step procedure, i.e., an initial sketch
21 were created using the sketching tool of MAPS and followed by using the amorphous builder module to build the LCE
22 model as shown in Fig 2. The LCE model was then assigned different force fields: Dreiding, PCFF, and SciPCFF. In
23 these simulations, some basic properties of the model materials can be calculated to assess the suitability of the force
24 field. The density of the simulated liquid crystalline monomer was probed to investigate and validate against the
25 experimental density value.

26 Fig. 3 shows the time-evolution of densities of RM257 monomer for different force fields. However, a
27 significant difference is observed for different force fields under ambient conditions. From the diagram, the density
28 from Dreiding, which is the generic or generic force field⁵⁵, exhibited a density of 1.073 g/cm³. As we can see, this
29 applied force field reaches the steady-state slower than the others. It also exhibits a fluctuated behavior until the
30 equilibrium state is introduced after 500 ps of simulation. The density observed for this force field is inconsistent with
31 the reported density of 1.219 g/cm³. This force field under-estimates the density by approximately 12%. In contrast,
32 the densities from the PCFF and SciPCFF, which developed as the second generation, rapidly reaches the equilibrium

1 state within 50 ps and 70 ps, respectively. The results were 1.158 g/cm³ for PCFF and 1.202 g/cm³ for SciPCFF. It
2 can be seen that the overall trends of these two force fields are different from Dreiding. These behaviors could be a
3 result of addition of the cross-terms and quartic terms for bonded and non-bonded interactions in these force fields.
4 Compared with the experimental values, PCFF and SciPCFF under-predicted the density by approximately 5% and
5 2%, respectively. This difference in simulated density by these two force fields is explained by the coefficient
6 variations used in defining the energy functions, indicating the possible best fit in SciPCFF terms used to predict the
7 density of the polymeric systems⁵⁶.

8 The steady-state density data for the liquid crystalline monomer suggests that SciPCFF shows a more
9 accurate prediction of the density of material than those obtained from the Dreiding, and PCFF. Based on this property,
10 SciPCFF would be fit as an appropriate force field for the prediction of the properties of the LCE class of polymers.
11 However, more validation with other material properties is necessary to further investigate its effectiveness.

12 B. Transition temperature of the elastomer model

13 The LCEs based on RM257 generally display nematic order in the liquid crystal phase. In this state, the
14 molecules of LCEs have lost their positional order; however, the long-range orientational order still exists with their
15 long axes, roughly parallel.⁵⁷ This behavior results in partial mobility of the molecules as a liquid while containing the
16 orientational order as a crystalline solid. It is, therefore, called T_{tran} for this phase, which transfers the nematic liquid
17 crystal to isotropic state, as nematic-isotropic temperature (T_{NI}). A measurement of the T_{tran} could be achieved using
18 a variety of methods, including the free volume theory. An increment of the free volume of the material occurs as the
19 temperature is increased. T_{tran} is defined as the temperature where an inflection in the specific volume-temperature
20 curve emerges.

21 In this work, the fractional free volume (FFV) variation of LCE models as a function of temperature was
22 studied as an efficient method for determining the T_{tran} . The ensemble-averaged free volume of the equilibrated LCE
23 models in the NPT step were investigated by the Trajectory Analysis module. In our case, even though the LCEs
24 contain two transition temperatures, including T_g and T_{NI} , we only focused on capturing the T_{NI} since this temperature
25 is higher than ambient temperature. Meanwhile, the T_g of this material, which was measured by DSC, is -6°C.
26 Therefore, the utilization of the T_{NI} can prevent any interference from the surroundings, making it suitable to act as a
27 switching temperature in the shape memory process. Fig. 4 illustrates the FFV of the elastomeric models with three
28 force fields. The computational tests display a similar trend of volume expansion of the models with linear temperature
29 changes. From the diagrams, it can be seen that the model demonstrates the linear response of the volume enhancement
30 with increasing temperature. The increased slope of FFV exhibits weak first-order transition leading to dividing the
31 slope into two lines. This transition behavior occurs due to small discontinuities in enthalpy, specific volume, and the
32 fluctuation effect near the transition point.^{58,59} The intersection of the slopes can be identified as T_{NI} . The predicted
33 T_{NI} by various force fields is included in Table I for comparison against the experimental results.

34 Fig. 5 shows the experimental T_{NI} investigated from tan delta data obtained from DMA test results,
35 summarized in Table I. It is known that the transition temperatures obtained from DMA could be different from those

1 obtained from the free volume data analysis.⁶⁰ Additionally, the T_{NI} obtained from DSC is reported in this table. From
2 this figure, it can be mentioned that the maximum point of a tan delta curve represents the T_{NI} . This behavior agrees
3 with the results reported in Saed *et al.*⁶¹ and Traugutt *et al.*³⁰ Table I shows that the T_{NI} values obtained from SciPCFF
4 are closest to the experimental results compared with those obtained using the other two force fields, with an under-
5 prediction of 12%. However, this discrepancy between simulation and experiment values may be affected by some
6 relevant factors such as the conversion degree of crosslinking reaction, or a heating rate. These parameters could vary
7 depending on the conditions of chemistry, stoichiometry or processing conditions.⁶² Additionally, the T_{NI} value
8 predicted for the PCFF model is consistent with SciPCFF, yielding under-prediction by 17%. In contrast, Dreiding
9 over-predicts T_{NI} by 20%. These data show that SciPCFF results in more accurate values for this transition temperature
10 and shows a relatively good agreement with the experimental values. Consequently, it could confirm the accuracy of
11 this force field to be used for the simulation of LCEs.

12 Table I T_{NI} of LCE from simulations and experiments

	Dreiding	PCFF	SciPCFF	Experiment from DSC	Experiment from DMA (tan delta)
T_{NI} (°C)	106	73	77	88	87

13

14 C. Viscoelastic properties of the LCE model

15 Storage modulus (E') and tan delta were the key viscoelastic properties investigated using MD simulations in
16 this study, which could potentially verify the suitability of the adopted force fields. These two properties were
17 experimentally evaluated in tensile mode and are shown in Fig. 5 as a function of temperature. The E' value at the
18 temperature of 27°C is approximately 7.3 MPa. Moreover, to compare with the simulation results, the experimental E'
19 values at various temperatures of 47°C, 67°C and 87°C are obtained from this figure and compared with the
20 corresponding values obtained from the MD simulations of different force fields in Fig. 6.

21 Fig.6 reveals that the E' data obtained for the SciPCFF model is the only force field that agrees well with the
22 experimental data for the entire temperature range. The E' data for this model shows a decreasing trend with increasing
23 temperature and exhibits values lower than the experimental results. In contrast, the E' data obtained from the PCFF
24 model shows a linear trend within the whole range of studied temperatures. Similar results are acquired from the
25 Dreiding model. This observation lies in the differences between these force fields as mentioned earlier. In particular,
26 the complexity of the force field, for example, Dreiding based generic force field and PCFF/SciPCFF based second
27 generation, has an essential effect on the accuracy of the predicted results. Moreover, differences in the coefficients
28 of the force fields and the functional form of various terms in the force fields result in the consistency of the
29 predictions.⁶³ Having compared all these three force fields, it is clear that only the SciPCFF potential is in good
30 agreement with the experiment. Nevertheless, the discrepancy between the E' values at low temperature compared

1 with the experimental data is still considerable. This inconsistency may occur due to the difference in the numbers of
2 atoms in the simulation box and the actual samples. Thus, further investigation is required; for example, an adaptation
3 of the cutoff distance and long-range interaction terms could reduce the discrepancy of this property. In addition, a
4 relative E' which compared to the reference E' was employed as well as the percentage average absolute relative errors
5 (AARE).⁵⁰

6 The relative change in modulus E'/E'_r is further analyzed to determine the force field accuracy, where E'_r is
7 the reference modulus at 27°C and is illustrated in Fig. 7. E'/E'_r data reveals that SciPCFF is the only force field with
8 good agreement with the experimental results. Furthermore, %AARE was also computed, as presented in Table 2. The
9 %AARE measured in this paper are denoted as β_E and β_t and refer to the %AARE of modulus values and $\tan\delta$ values,
10 respectively. β_E and β_t calculated using Equation 3 and Equation 4. The E'_s and $\tan\delta_s$ are the predicted storage modulus
11 and tan delta by the model, respectively. The E'_{exp} and $\tan\delta_{exp}$ are the experimental storage modulus and tan delta value
12 from DMA, respectively. N is the number of compositions with different temperatures (in this case, $N = 4$).

$$13 \quad \beta_E = \frac{100}{N} \sum_{i=1}^N \left| \frac{E'_s - E'_{exp}}{E'_{exp}} \right| \quad (3)$$

$$14 \quad \beta_t = \frac{100}{N} \sum_{i=1}^N \left| \frac{\tan\delta_s - \tan\delta_{exp}}{\tan\delta_{exp}} \right| \quad (4)$$

15 Table II shows that SciPCFF results in the lowest β_E value of 52% among the three force fields, however, it is a
16 relatively high value compared to the experimental sample. This error analysis indicated that further improvements of
17 the simulated models or parameters of the force fields are required to achieve a greater consistency for the results. In
18 order to ensure that SciPCFF is the appropriate force field for this system, another viscoelastic property such as tan
19 delta was considered further.

20 Tan delta curve of the simulated LCE system is represented in Fig. 8. This property is the ratio of the
21 dissipated energy to the stored energy in various sample deformation processes.⁶⁴ In this figure, it can be seen that the
22 SciPCFF model shows a remarkable agreement with the experimental data. The trend of these two curves is consistent
23 with each other, along with the observed temperatures. In contrast, the trend of simulated tan delta for Dreiding and
24 PCFF potentials discrepant and are less concentrated when compared with the experiment work. The β_t of the
25 simulated tan delta is also reported in Table II. It can also be calculated by using Equation 4. The result confirms the
26 accuracy of SciPCFF, providing the value of 13%, following the experimental data value. This parameter can assist
27 in approaching accurate predictions of the viscoelastic properties. In comparison, SciPCFF again demonstrates an
28 excellent agreement with the experimental data.

29
30
31

1 Table II β_E and β_t value from storage modulus and tan delta obtained for different force fields when compared with
2 the experimental values

Force field	β_E of storage modulus	β_t of tan delta
Dreiding	170	24
PCFF	83	27
SciPCFF	52	13

3

4 Therefore, it is clear that the simulation results with SciPCFF exhibit the best agreement with the
5 experimental data. Particularly, these results emphasize the significance of addition of cross-terms and cubic expansion
6 of intramolecular bonds in the second-generation force fields to better enhance the accuracy of simulated model
7 systems in terms of potential energies, molecular conformation, and vibrational frequency.⁵² In particular, the cross-
8 terms increase the transferability of the diagonal terms, including bond stretching, bond bending, torsion, and improper
9 torsion.⁵² However, the Dreiding as a generic force field, only contains the computation of the squared degree of
10 intramolecular interactions without containing the series of cross-terms. Moreover, PCFF and SciPCFF employ 9-6
11 LJ potential to calculate van der Waals interactions between simple atoms and molecules^{53,65}, while, Dreiding uses
12 12-6 LJ potential⁶⁶, as shown in Equations 4 and 5. The attractive part of LJ potential, at long-range interactions or
13 dispersion force, is indicated by $(1/r)^6$.⁶⁷ Meanwhile, the repulsive part of LJ potential, describing the repulsion at short
14 distances of the interacting particles, can be varied by $(1/r)^{12}$ and $(1/r)^9$ depending on the types of force field. The
15 difference of exponent in the repulsive part of these equations has an essential impact on the accuracy of the predicted
16 properties. In this case, the high steep repulsive term of 12-6 LJ potential could affect an overestimation of the pressure
17 in the model.⁶⁷ This parameter, $(1/r)^{12}$, could lead to the rigor of attractive force between molecules. Therefore, a
18 replacement by $(1/r)^9$ represents a weaker repulsive part⁶⁷, allowing the molecules to move closer. At the same time,
19 an improvement of the second-generation force field, especially torsional potential, could necessarily affect the
20 structural conformation and bonding of liquid crystal materials, adapting the balance of repulsion and conjugation of
21 the polymeric system.⁶⁸ Based on these reasons, the PCFF and SciPCFF can have efficacy on modeling and validation
22 of the simulated LCE system and demonstrate more accurate results than Dreiding.

$$23 \quad U_{LJ} = 4\varepsilon \left[\left(\frac{\sigma}{r} \right)^9 - \left(\frac{\sigma}{r} \right)^6 \right] \quad (4)$$

$$24 \quad U_{LJ} = 4\varepsilon \left[\left(\frac{\sigma}{r} \right)^{12} - \left(\frac{\sigma}{r} \right)^6 \right] \quad (5)$$

25 Where ε is defined as the depth of the potential well, σ stands for distance at which the particle-particle potential
26 energy, and r is the distance between two interacting particles.

27 Furthermore, when comparing the effectiveness between PCFF and SciPCFF, which belong to the same force
28 field generation, these two force fields have the same energy functions for computing all inter- and intramolecular

1 interactions, as well as the cross-terms. However, the coefficients in some functions of SciPCFF are different from the
2 PCFF version, for instance, in quartic bonds and angles, torsion angles, improper angles, and cross-terms. It can be
3 clarified that the different coefficients in force field calculation can play a significant role in the development of
4 accuracy. Thus, the improved version of SciPCFF is the force-field of choice for studying shape memory
5 characteristics of this polymeric system.

6 **D. Prediction of shape memory properties of LCE**

7 After validations, SciPCFF is further utilized for the study of the shape memory properties of LCE. Fig. 9
8 displays a four-step thermomechanical protocol for the simulation of the shape memory process. A relevant loading
9 is applied to the simulation box during a loading step. The temperature is kept constant, and the simulation box is
10 strained with constant stress. Second, the temperature of the system is reduced to room temperature. While the assigned
11 load is still held in the system. In this step, it is clear that the conformation of the model is the same as the previous
12 steps. Third, the temperature is kept the same as the cooling step while the load is removed. The low temperature can
13 prevent the mobility of the polymeric chains and entropy-driven shape recoveries⁴². Eventually, the high temperature
14 at 450K is used to recover the sample to its original shape.

15 Changes in the chain conformation are calculated using Equations 1 and 2, respectively, through the R_f and
16 R_r . After the unloading step, the model exhibited an excellent R_f of about $97.9\% \pm 0.1\%$. This result reveals that the
17 model can be deformed and maintained well under the strain-controlled conditions. However, a small shrinkage
18 occurred rapidly after stress relaxation due to the total energy in the system.⁶⁹ This effect resulted in the unreachable
19 100% of R_f . However, the R_f values lie in the same range as reported in Saed *et al.*⁴⁷ and Martinez-Gomez *et al.*⁷⁰. In
20 addition, the R_r is computed to be approximately $73.8\% \pm 0.3\%$. This result is similar to the reported results of 80.3%
21 by Moon *et al.*⁴² The unrecoverable strain from the heating step could be the result of disentanglement of the physical
22 entanglement of the polymeric chains during the mechanical deformation.^{42,71}

23 Fig. 10 demonstrates the pressure applied in the simulation box for the various steps of the shape memory
24 process. The pressure is initially assigned to enforce the simulated sample to temporary shape deformation. When the
25 sample is cooled down with the constant volume, the pressure dramatically reduces due to a decrement of temperature.
26 The model also slightly recovered under the pressure of 1 atm at room temperature in an unloading step. However,
27 the stretched model maintained its temporary shape in the stretched direction (x dimension) due to the enforced
28 pressure during the cooling. This may also be caused by the lower mobility of the molecular chains in the simulation
29 box at room temperature. Finally, the stored dimension of this material partially disappeared when the temperature is
30 increased to 450 K under the same pressure of 1 atm.

31 The total energy changes during the thermomechanical shape memory process are shown in Fig. 11. The
32 model shows a 73% higher energy (9500 kcal/mol) compared to the following cooling step (2600 kcal/mol). The
33 residual energy stored in this cooling stage could affect conformational changes in this system. Even though the sample
34 is cooled down to room temperature, the molecular chain still shows some mobility possibly owing to this residual
35 energy. Therefore, achieving 100% fixity for this simulated model is not possible. This amount of energy also remains

1 at this level when the stress is removed in an unloading step. Eventually, the total energy rises to a high level at about
2 11200 kcal/mol when the temperature is increased up to 450 K for shape recovery. It can be seen that the total energy
3 of the various stages converges toward an equilibrium state. From these results, SciPCFF proves to be the best force
4 field to predict the shape memory characteristics of LCE-based RM257, and other intensive physiochemical and
5 mechanical properties.

6

7 **IV. CONCLUSION**

8 This research work represents a study on the assessment of appropriate force fields to capture the shape
9 memory properties of LCEs. The critical properties of this material, including steady-state density, transition
10 temperature, and viscoelastic properties, are characterized using both laboratory experiments and MD simulations.
11 The MD simulations of this elastomer are performed by assigning three different types of force fields, namely
12 Dreiding, PCFF, and SciPCFF. By comparing experimentally measured data with those obtained through MD
13 simulations, the accuracy of three force fields is discussed. The results show that the thermomechanical properties of
14 the system modeled by the SciPCFF potential agree well with the corresponding experimental data and are the most
15 accurate representation of the molecular interactions prevalent for the selected liquid crystalline elastomer. This force
16 field is then utilized to predict the shape memory properties of this system, including R_f and R_r , which are $97.9\% \pm$
17 0.1% and $73.8\% \pm 0.3\%$, respectively. Moreover, the total energy of each shape memory step reaches equilibrium
18 throughout the process, confirming that SciPCFF is the most appropriate force field to study the LCEs.

19

20 **ACKNOWLEDGEMENT**

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22 providing access to OzSTAR High Performance Computing (HPC) facility. OzSTAR is funded by Swinburne
23 University of Technology and the National Collaborative Research Infrastructure Strategy (NCRIS).

24

25 **DATA AVAILABILITY**

26 The data that support the findings of this study are available from the corresponding author upon reasonable
27 request.

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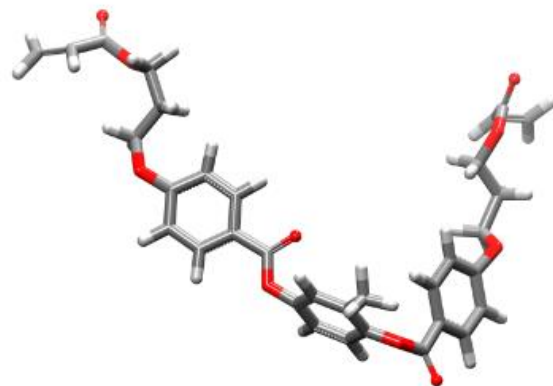
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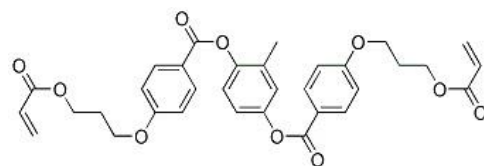
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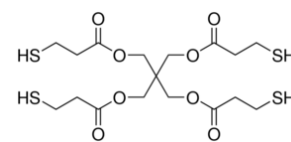
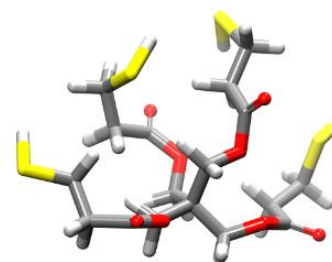


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(a)



(b)

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FIG. 1. Chemical structures used in MD simulations of (a) RM257 monomer (C = grey, H = light grey, O = red), (b)

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PETMP crosslinker (C = grey, O = red, H = light grey, S = yellow).

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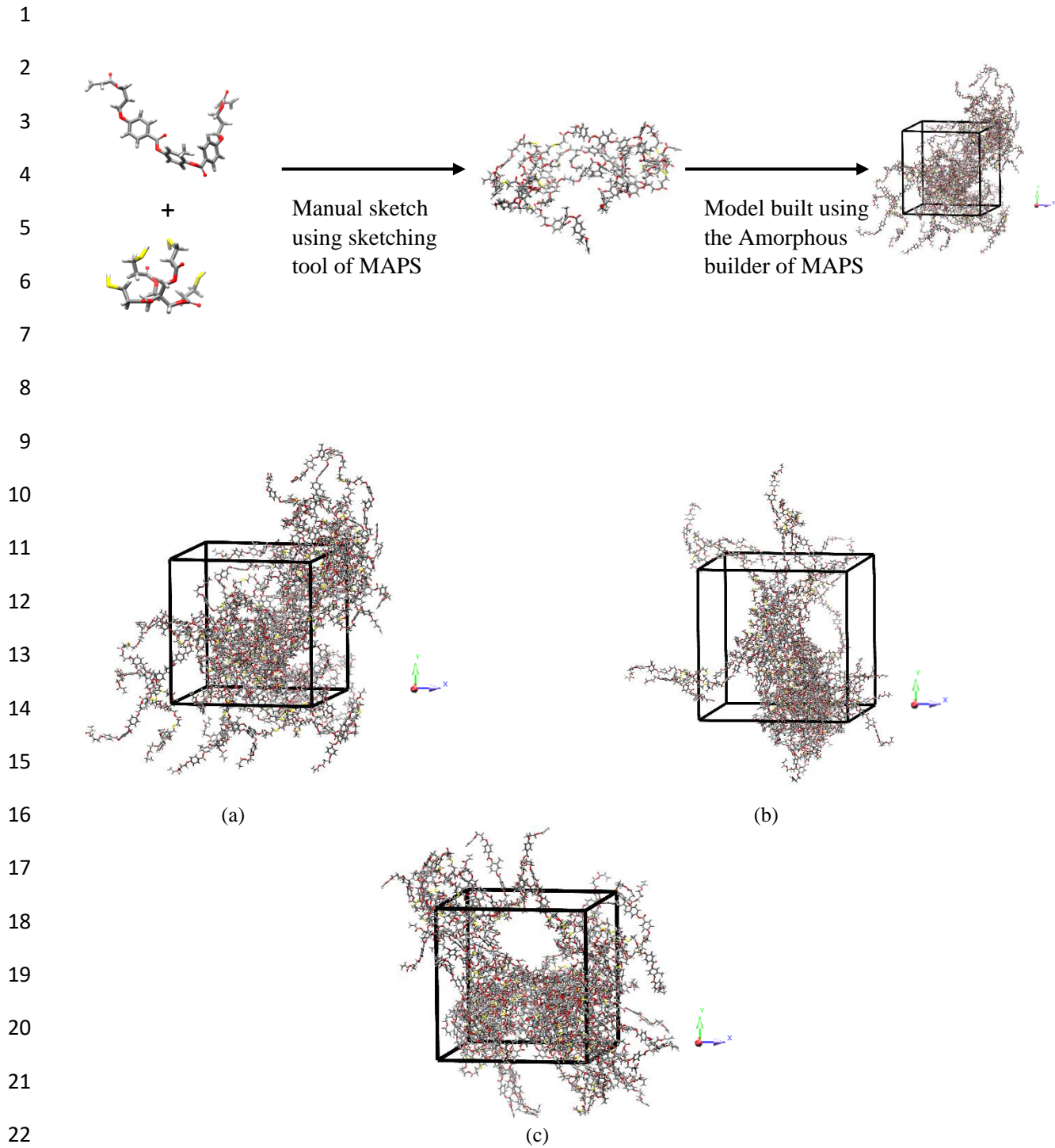
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23 FIG. 2. Sketch of LCE and crosslinking agent for building the main-chain elastomer model. The main-chain LCEs
24 were subjected to three force fields; (a) Dreiding, (b) PCFF and (c) SciPCFF.

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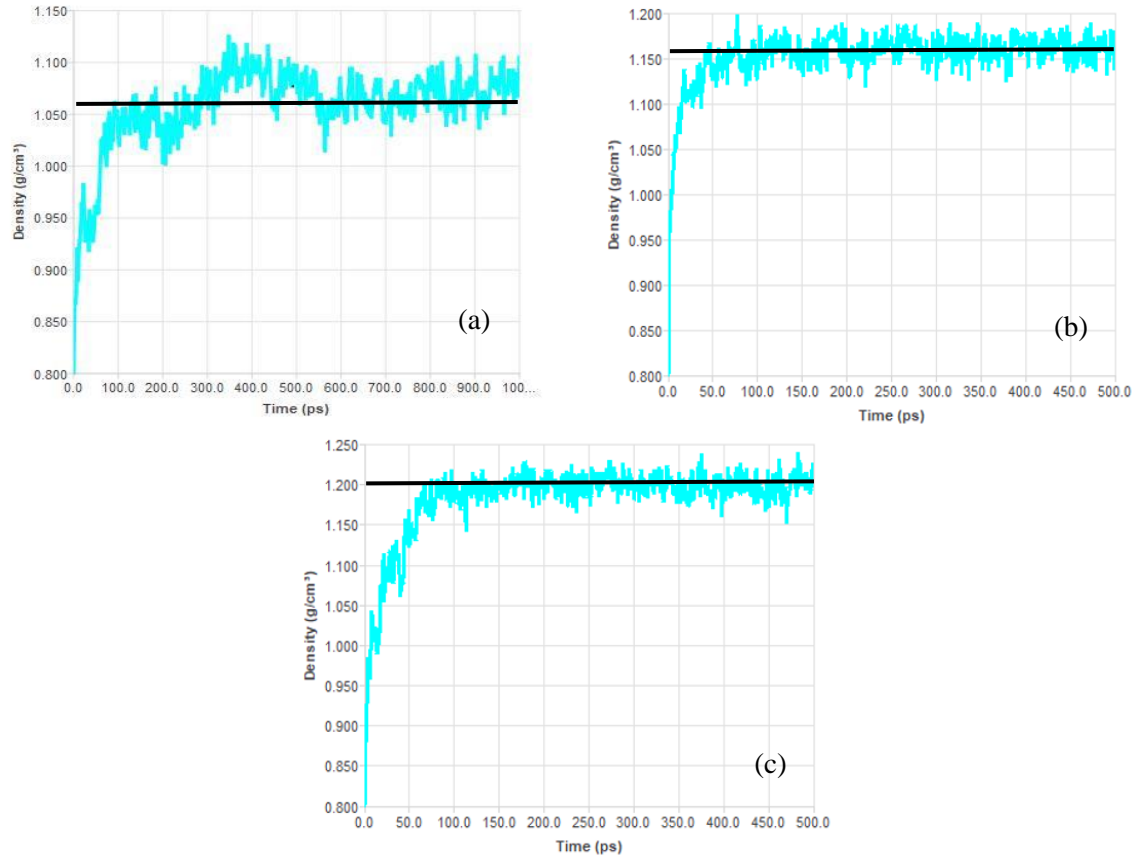


FIG. 3. Steady-state density of liquid crystalline monomers under different force fields (a) Dreiding, (b) PCFF and (c) SciPCFF.

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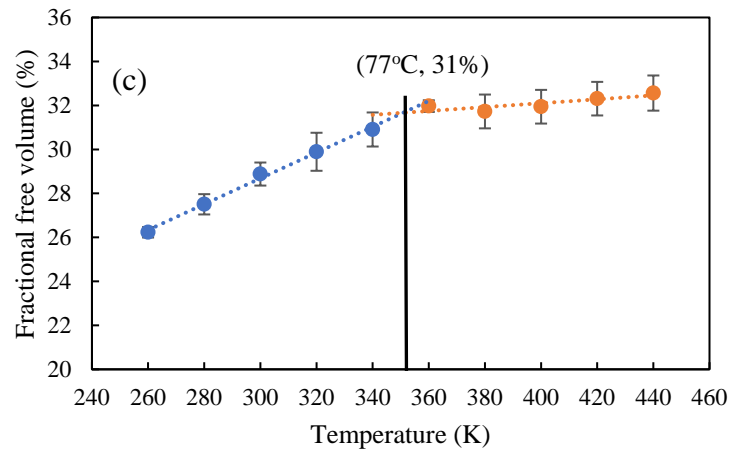
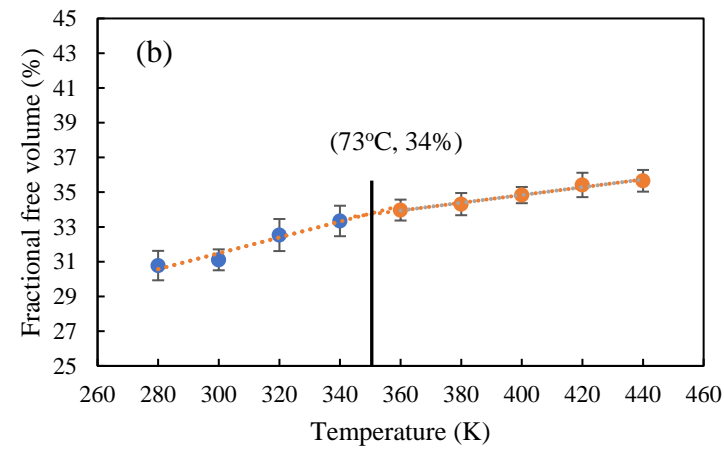
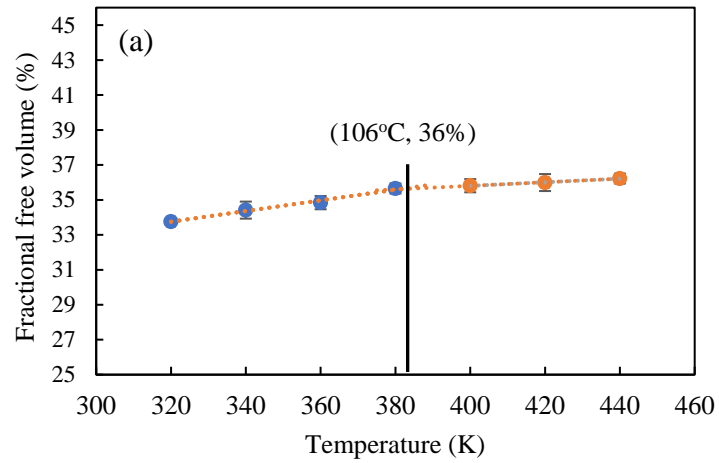
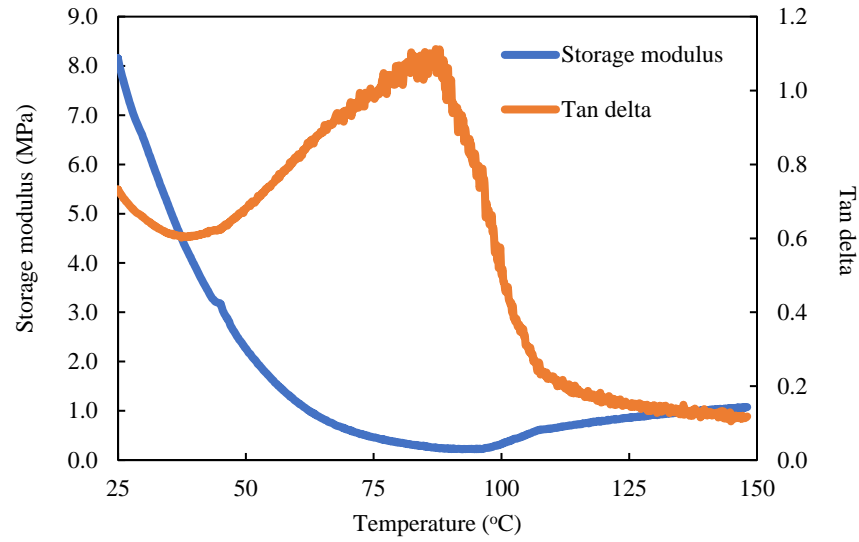


FIG. 4. Fractional free volume versus temperature plot of LCE of three force fields (a) Dreiding, (b) PCFF and (c) SciPCFF.

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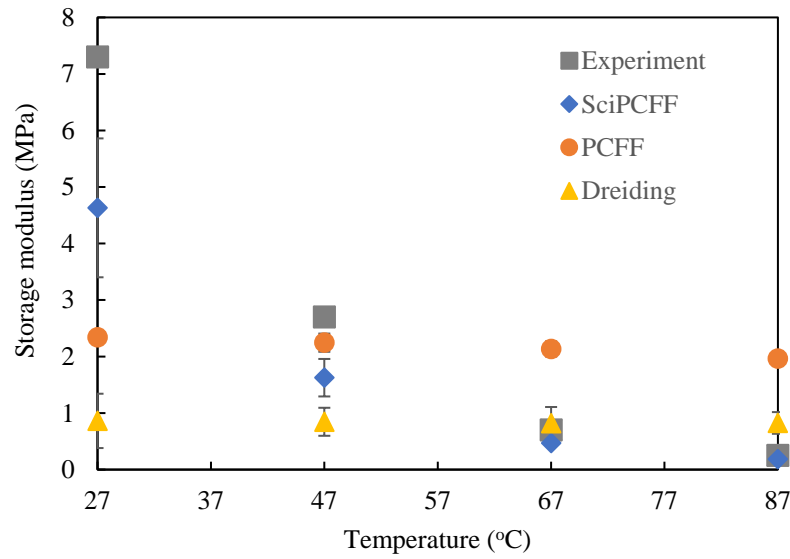


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FIG. 5. Experimental results of storage modulus and tan delta of modelled LCE, with T_{NI} at 87°C (from tan delta).

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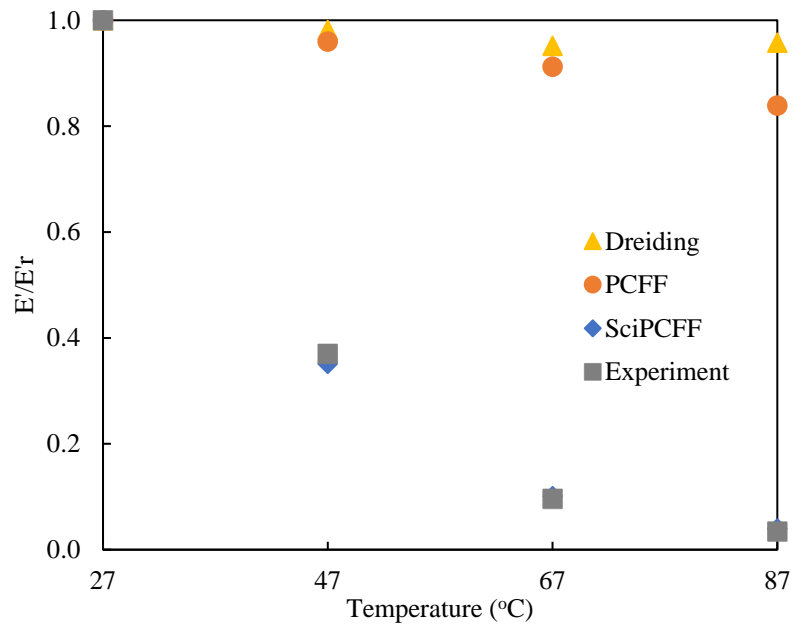
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FIG. 6. Storage modulus at various temperature of the modelled LCE under different force fields compared with experimental result.

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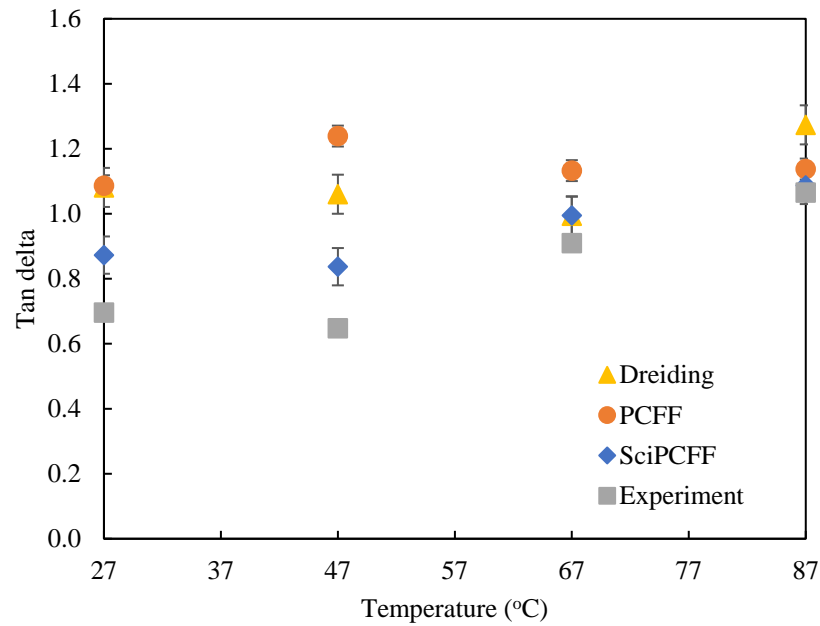
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FIG. 7. Relative storage modulus at various temperature of LCE under different force fields compared with experimental results.

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FIG. 8. A comparison of simulated tan delta of LCE for different force fields with experimental results.

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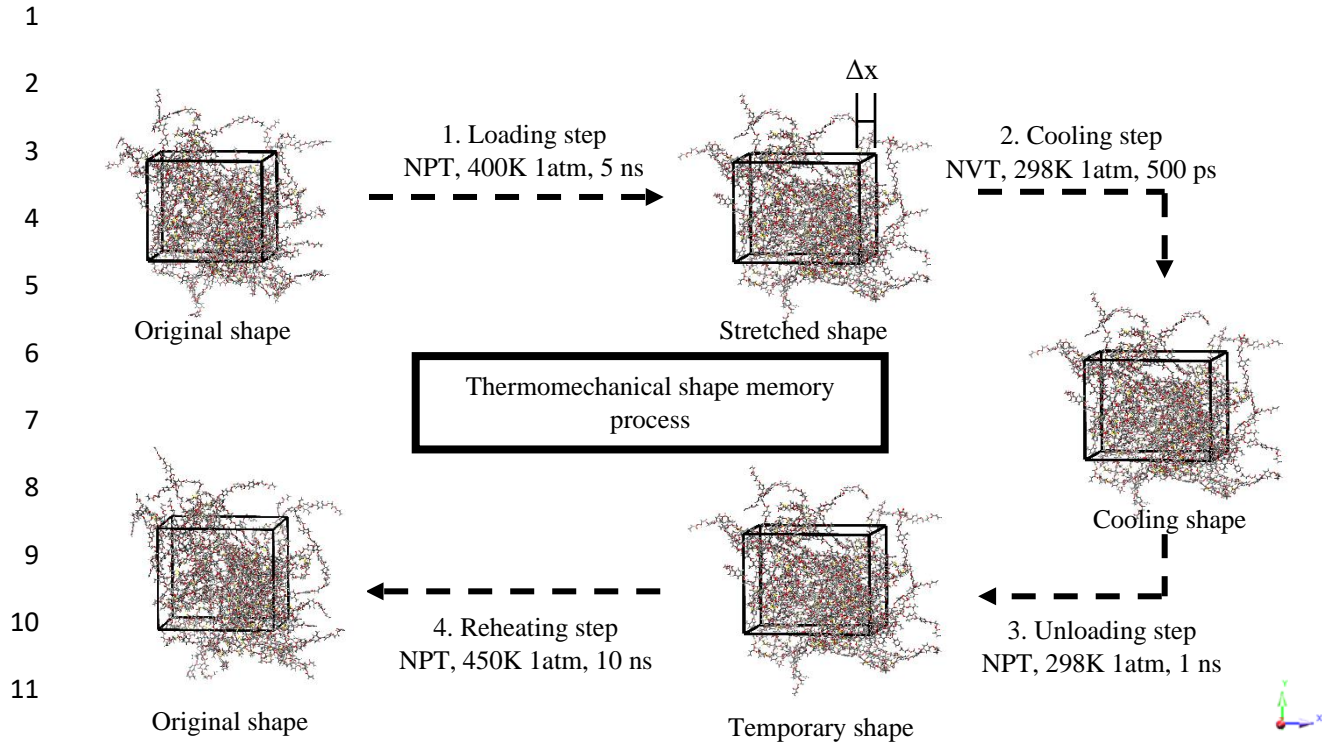
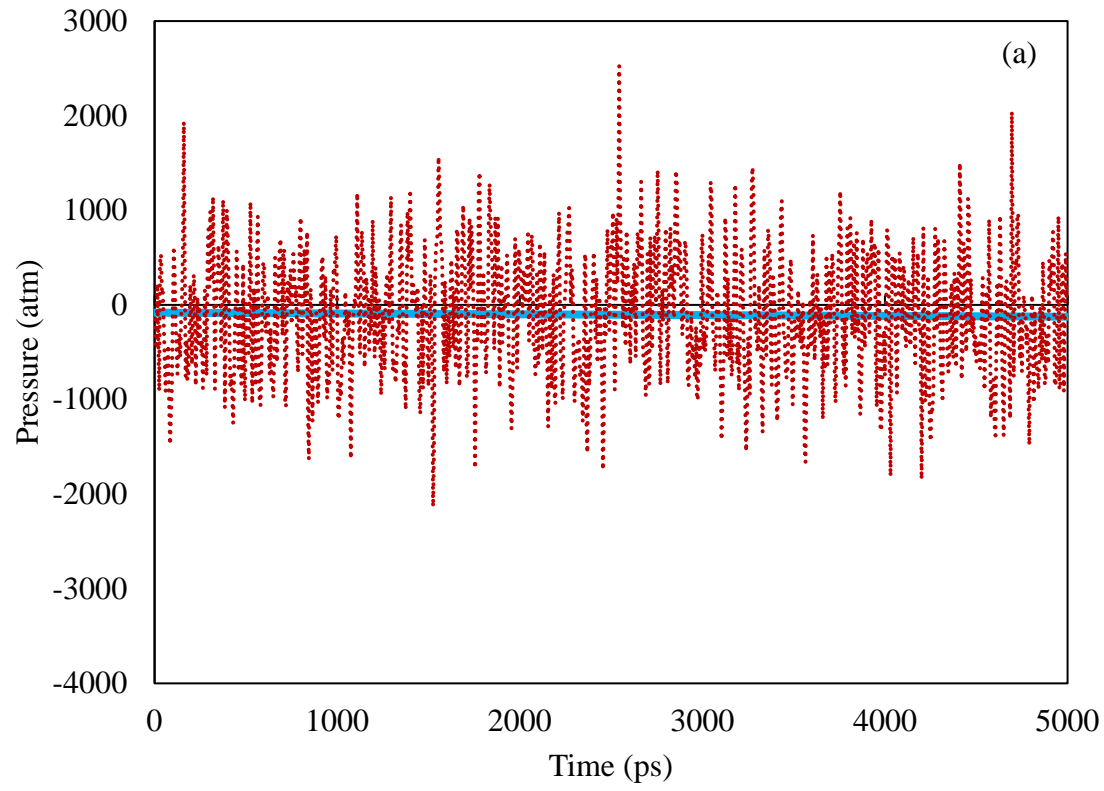


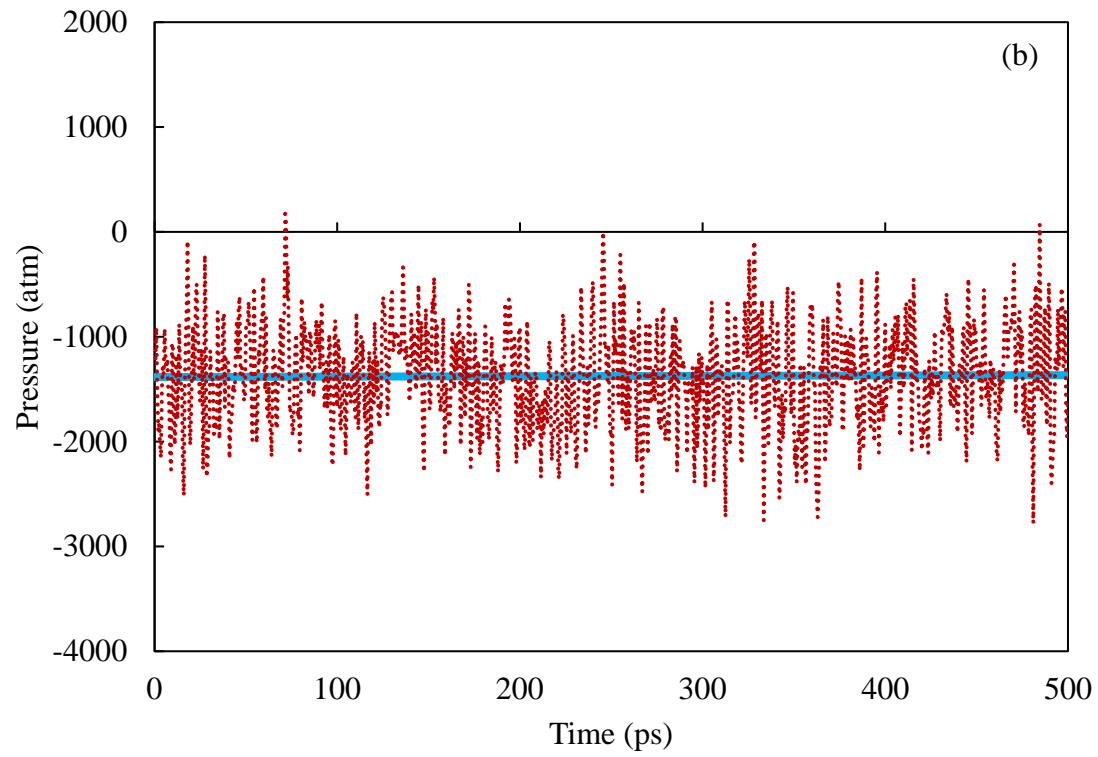
FIG. 9. Scheme of a four-step shape memory process with tensile mode.

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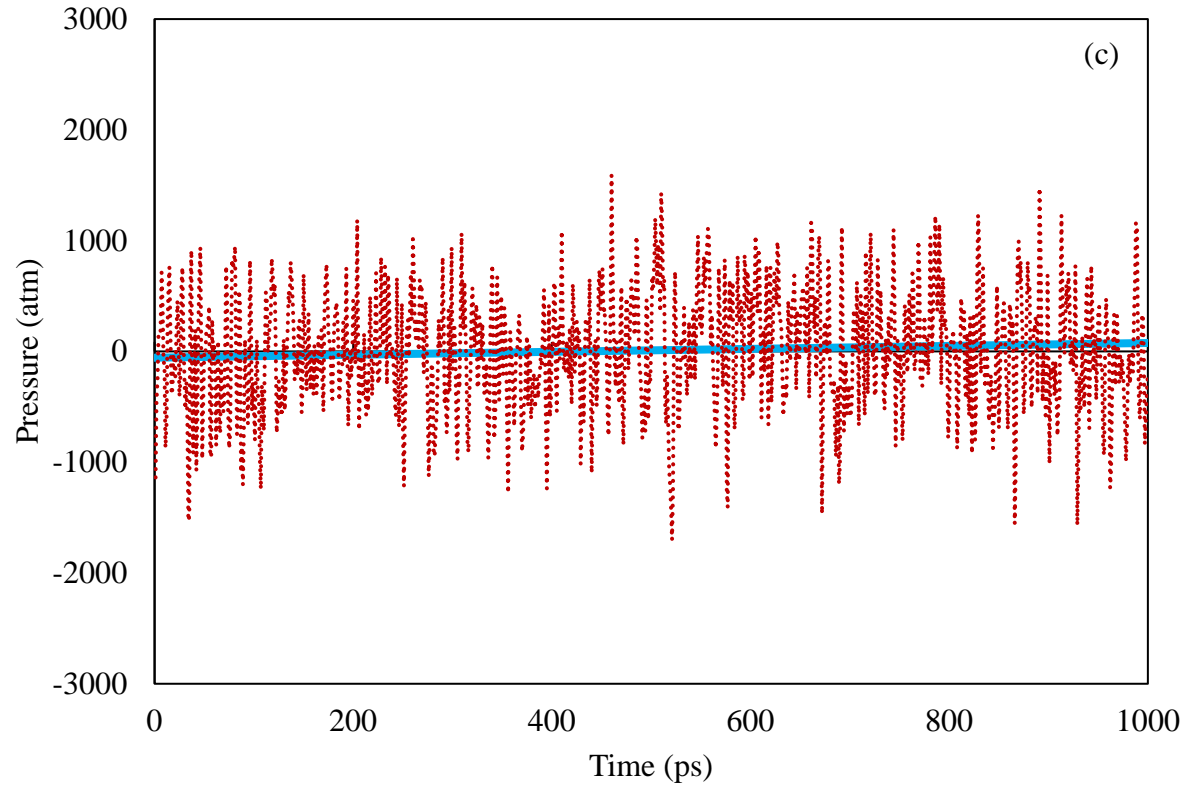


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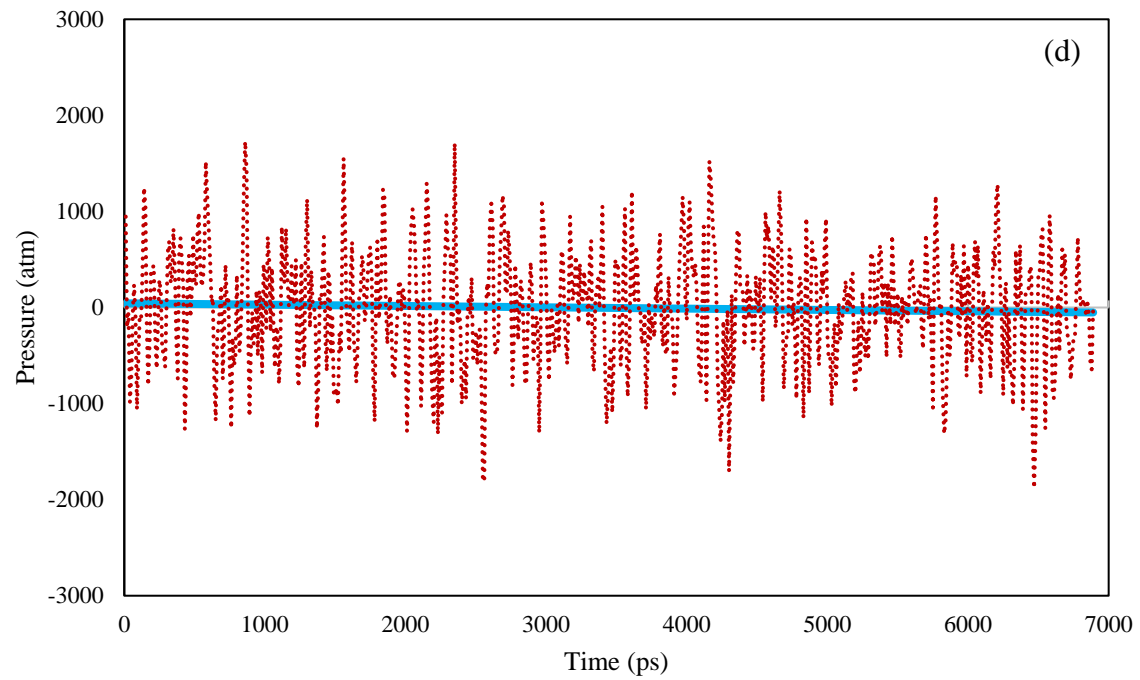


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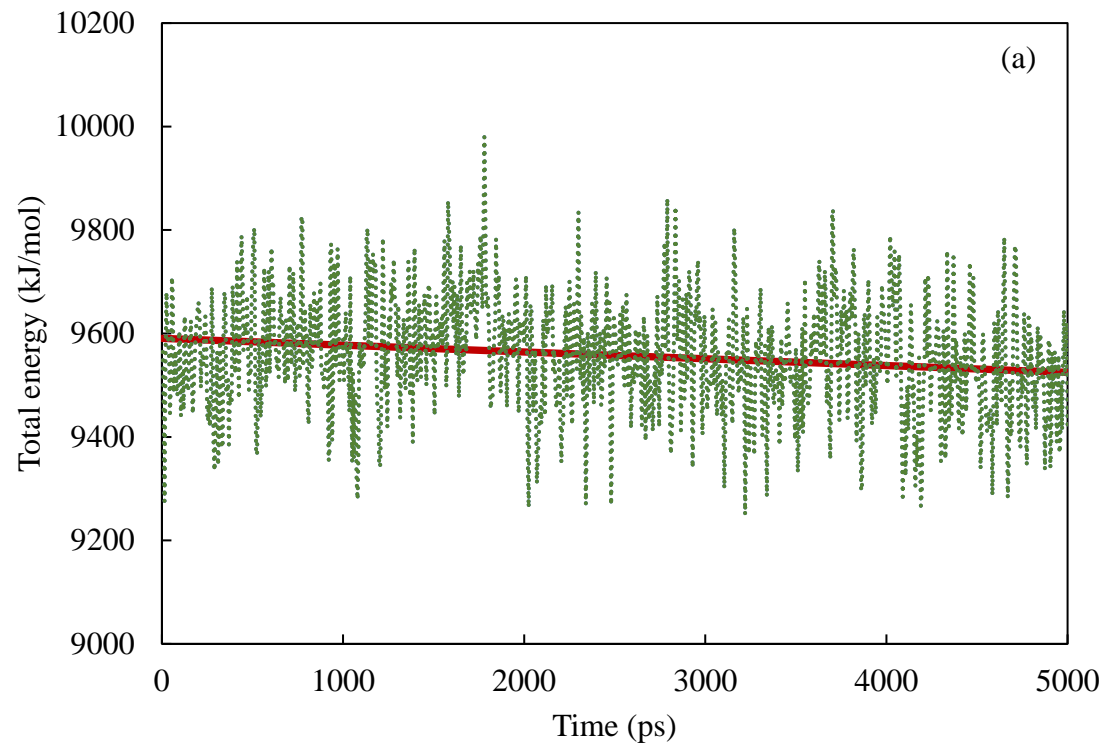
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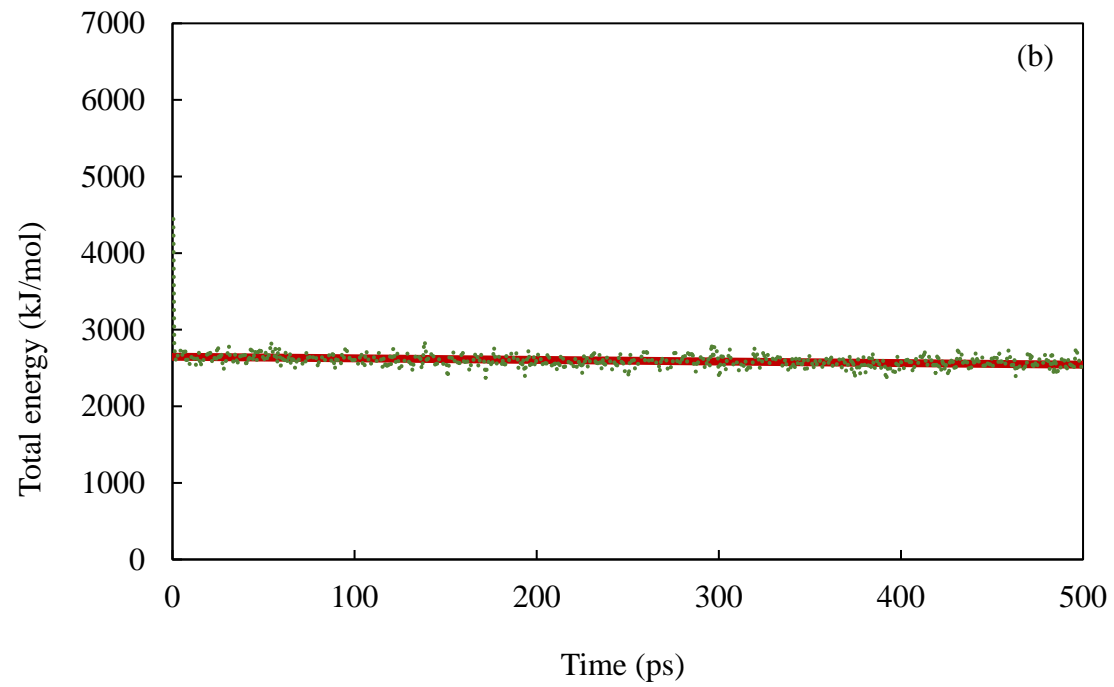
4 FIG. 10. Pressure of the model during the various steps of shape memory process; (a) deforming step, (b) cooling step,
5 (c) unloading step and (d) reheating step.

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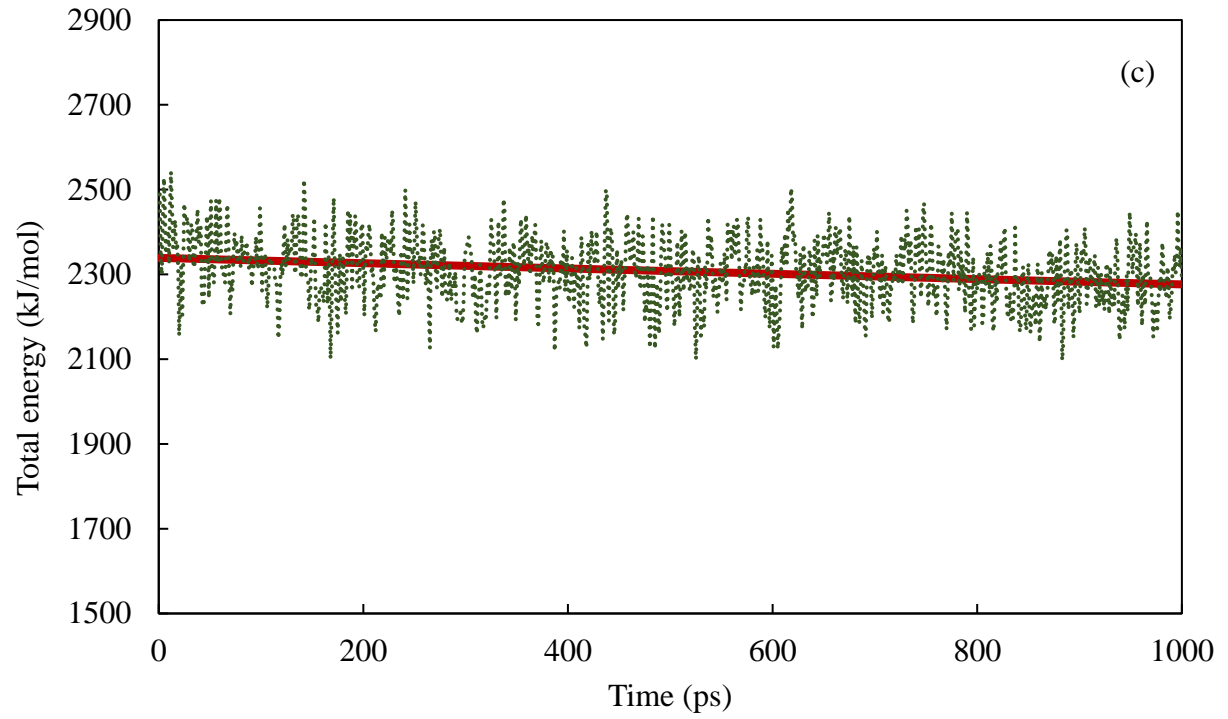
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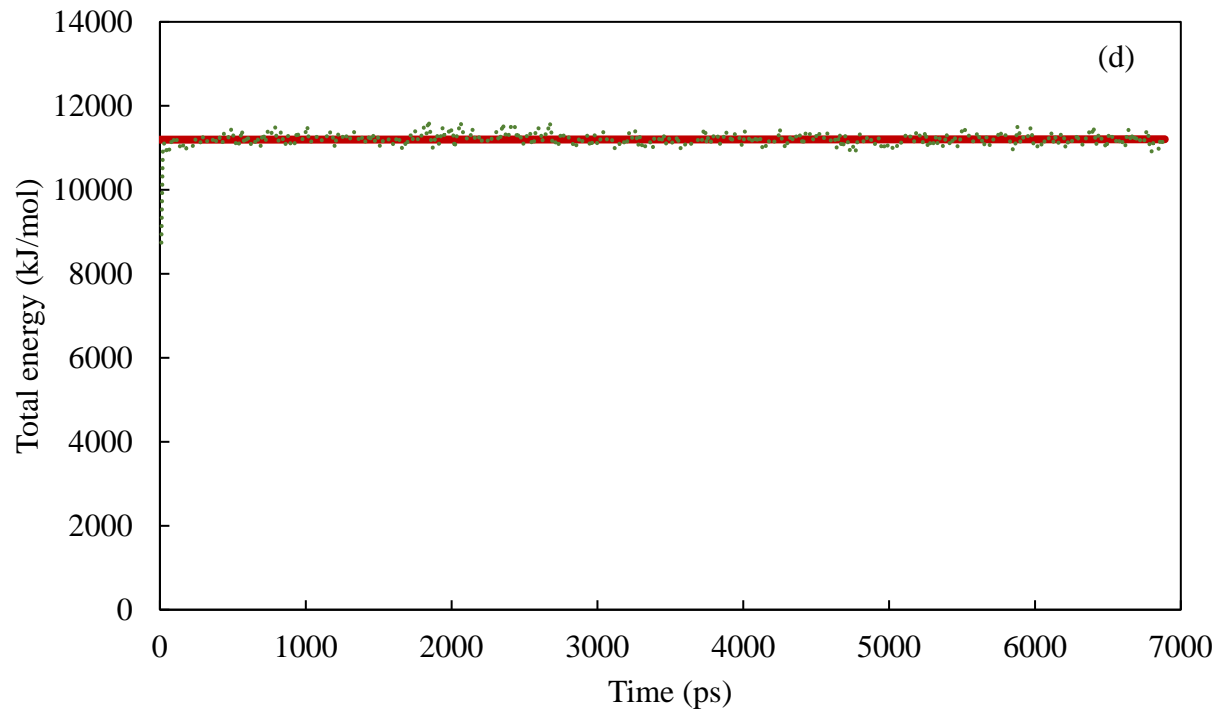


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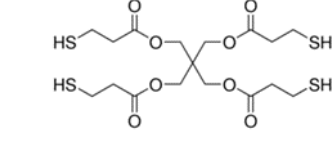
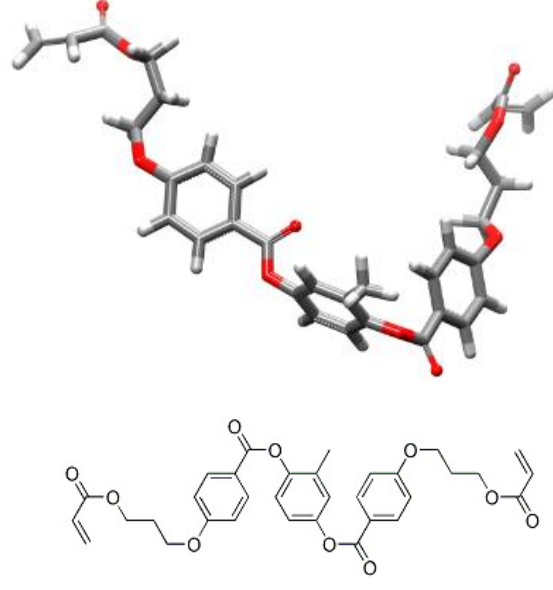
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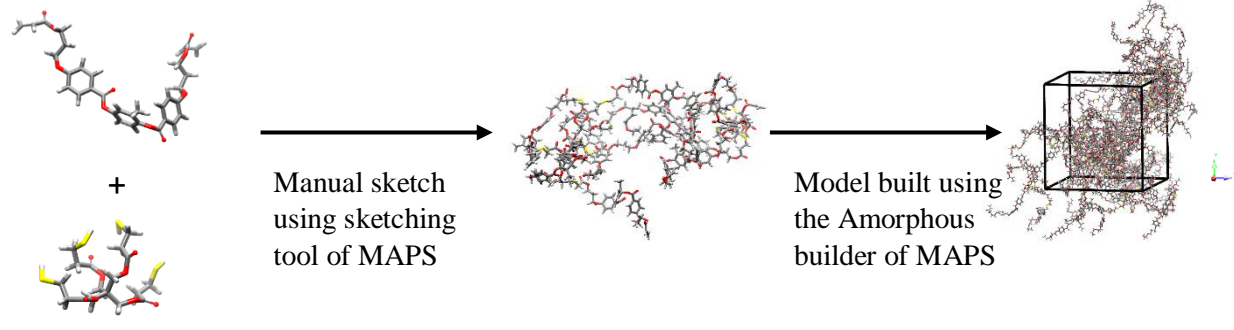
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4 FIG. 11. Total energy of various step of shape memory process; (a) deforming step, (b) cooling step, (c) unloading
5 step and (d) reheating step.

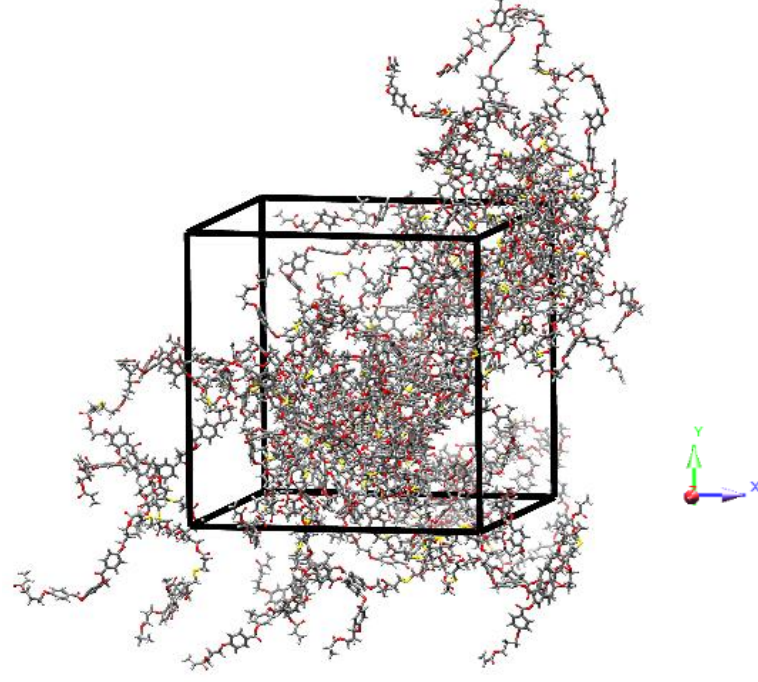
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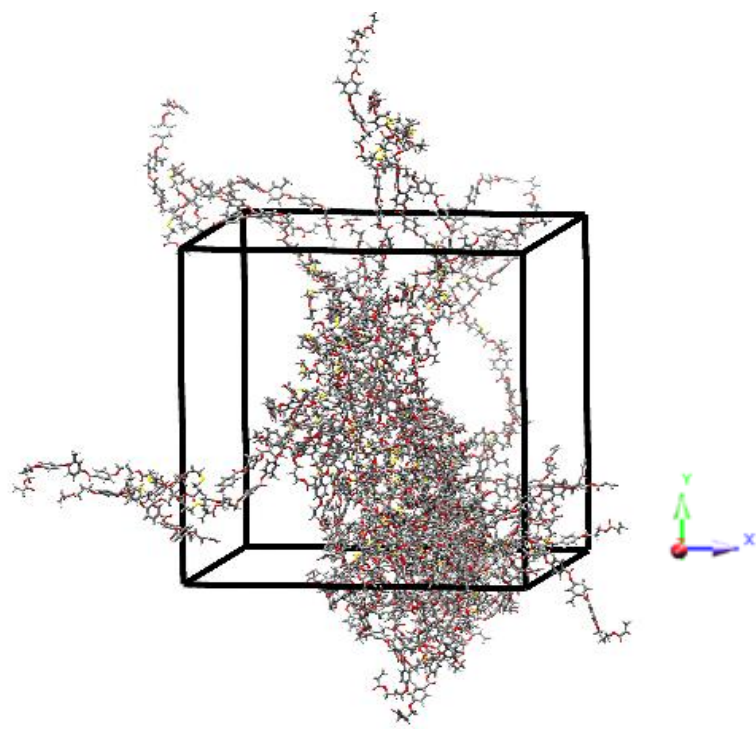
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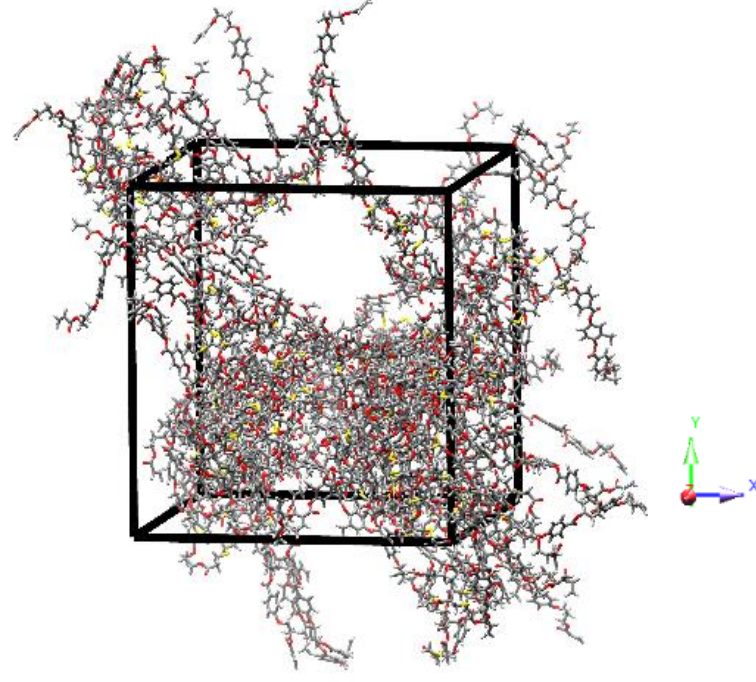
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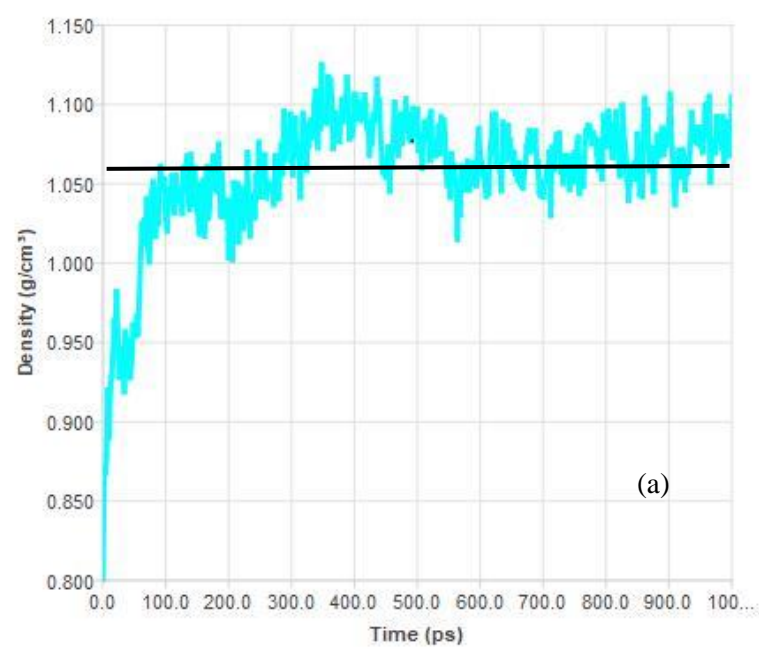
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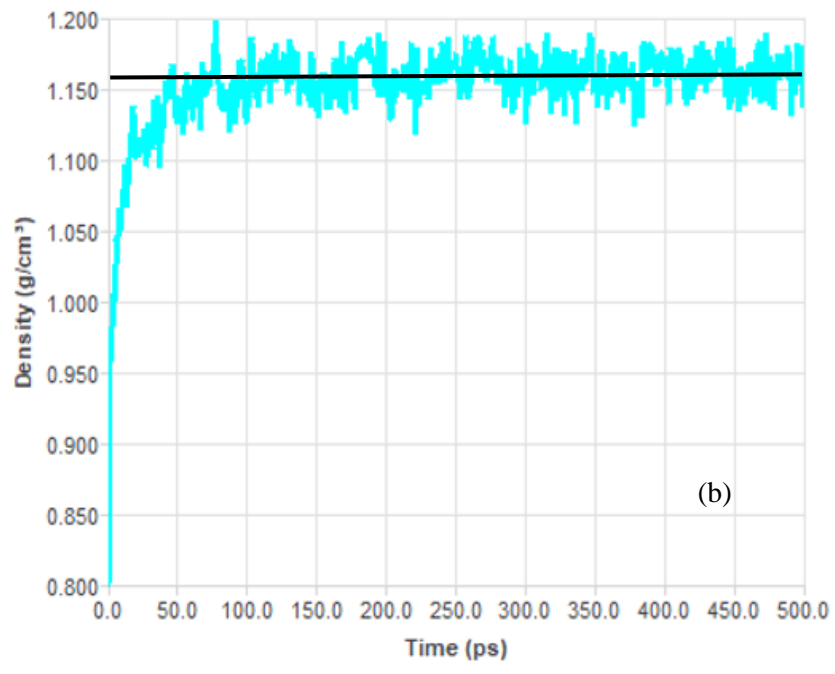
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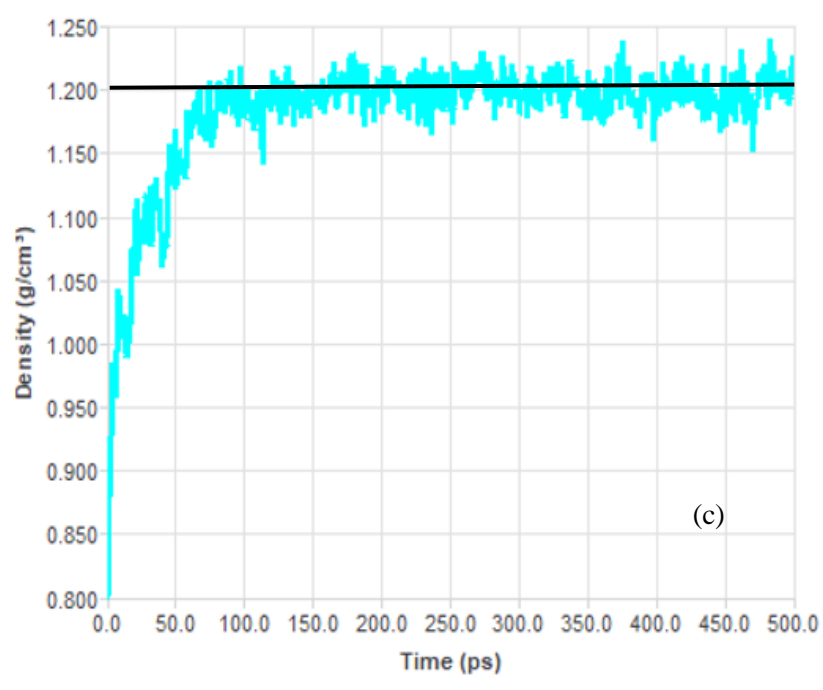
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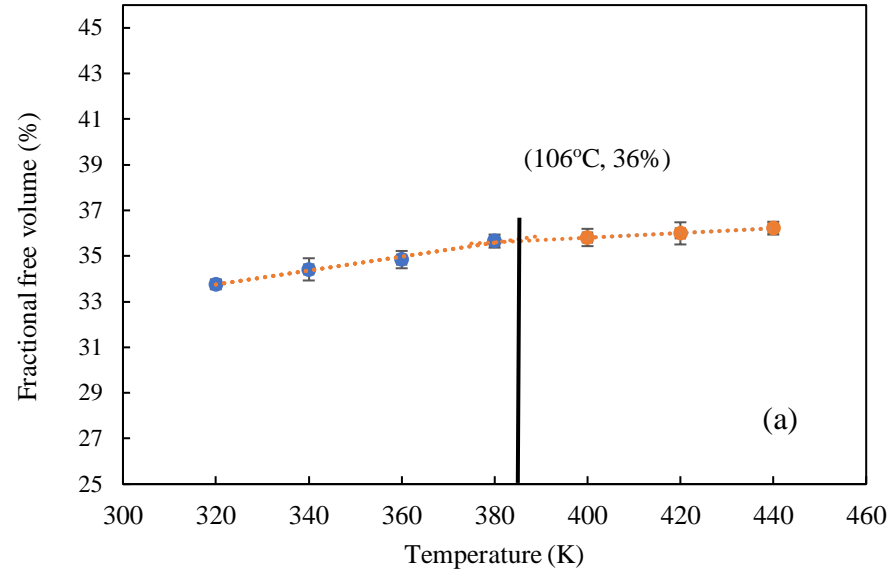
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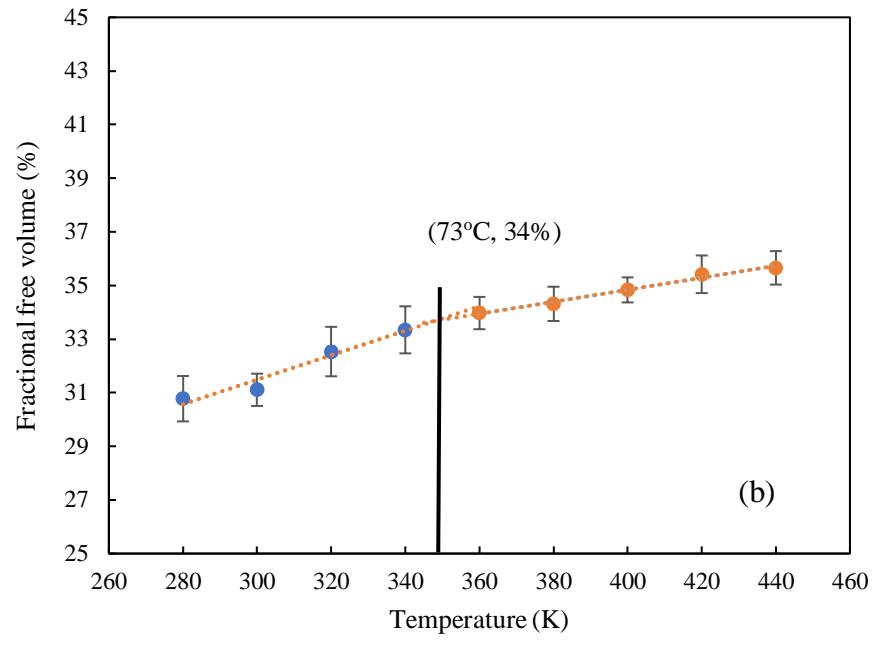
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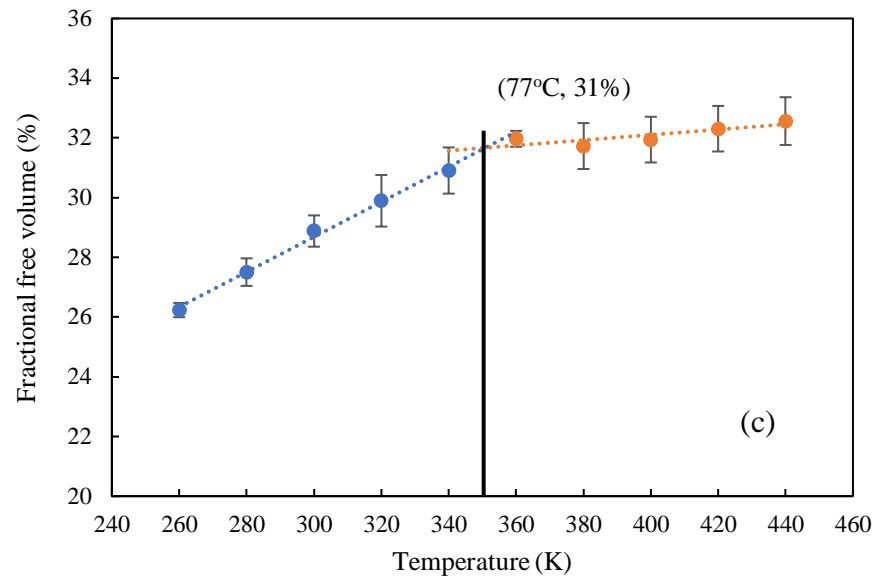
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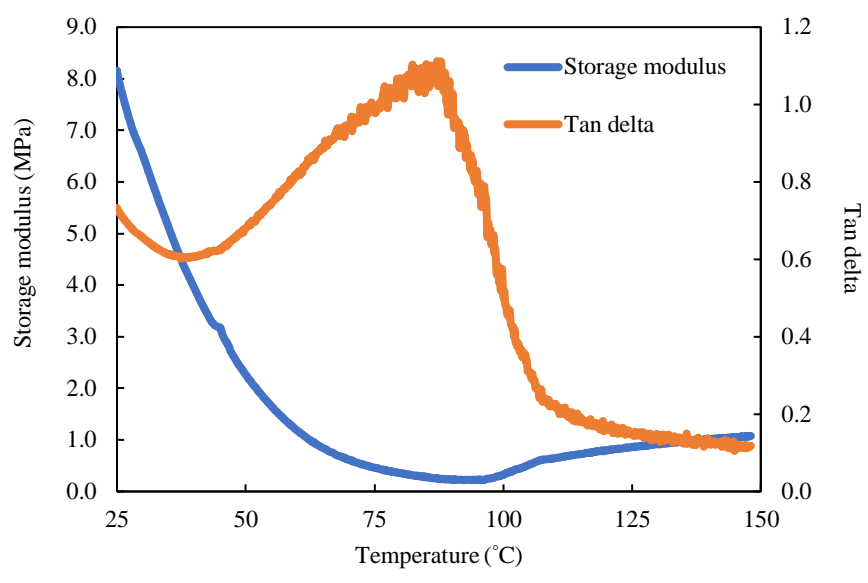


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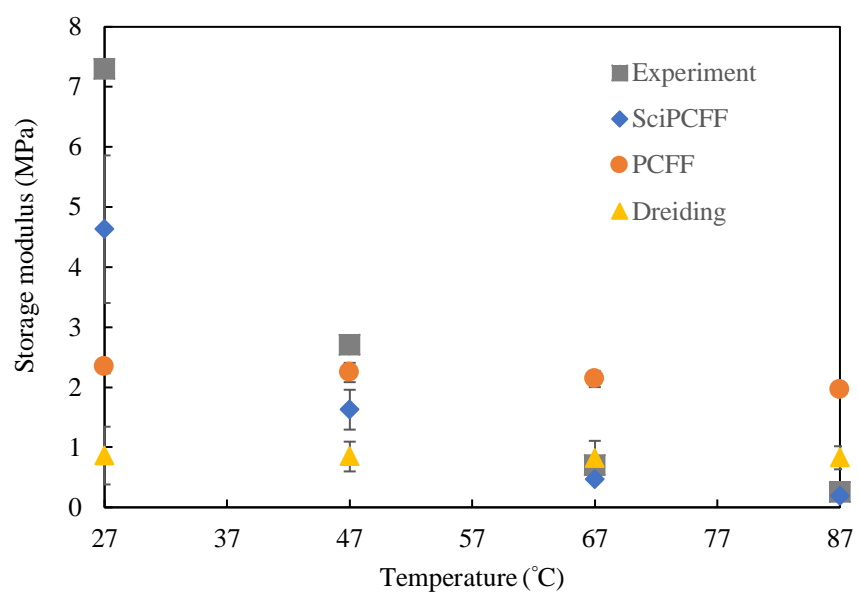


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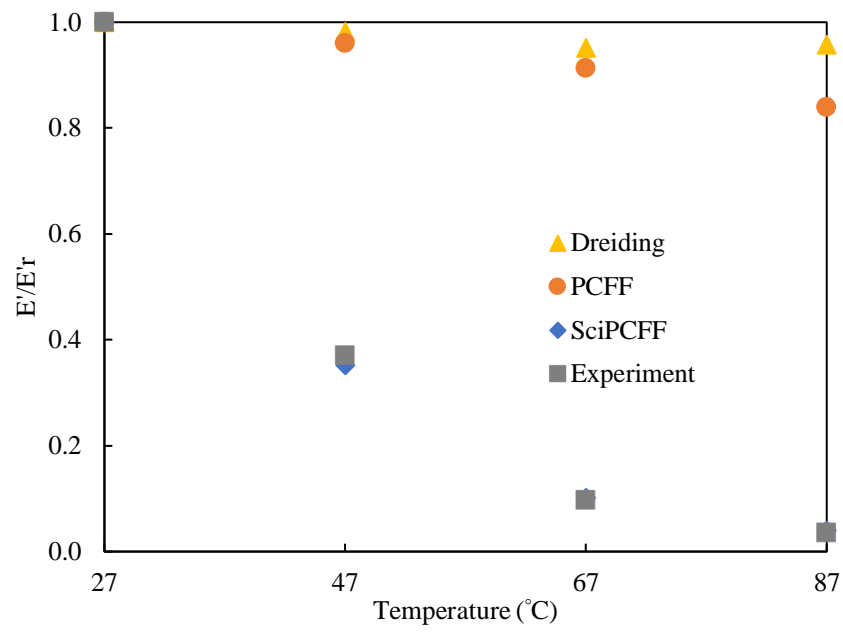
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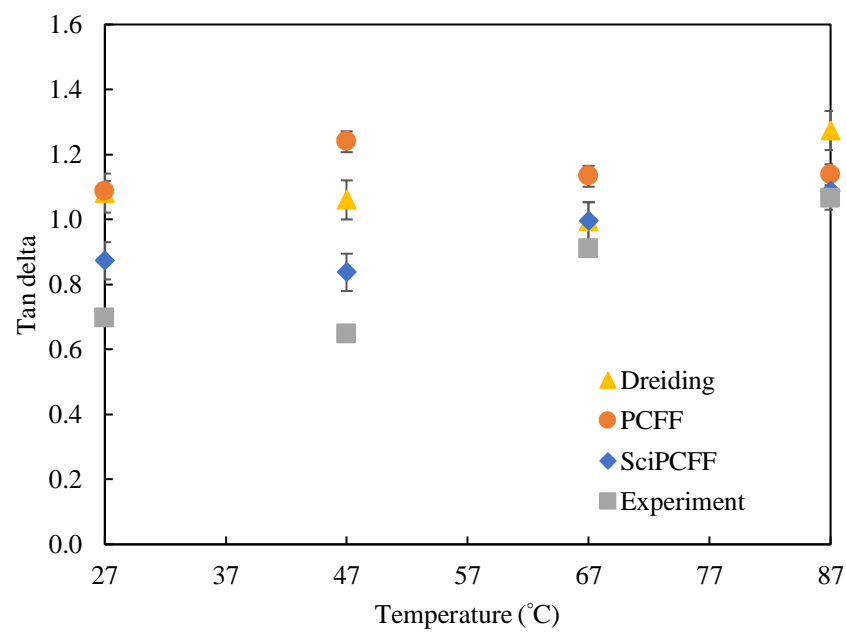
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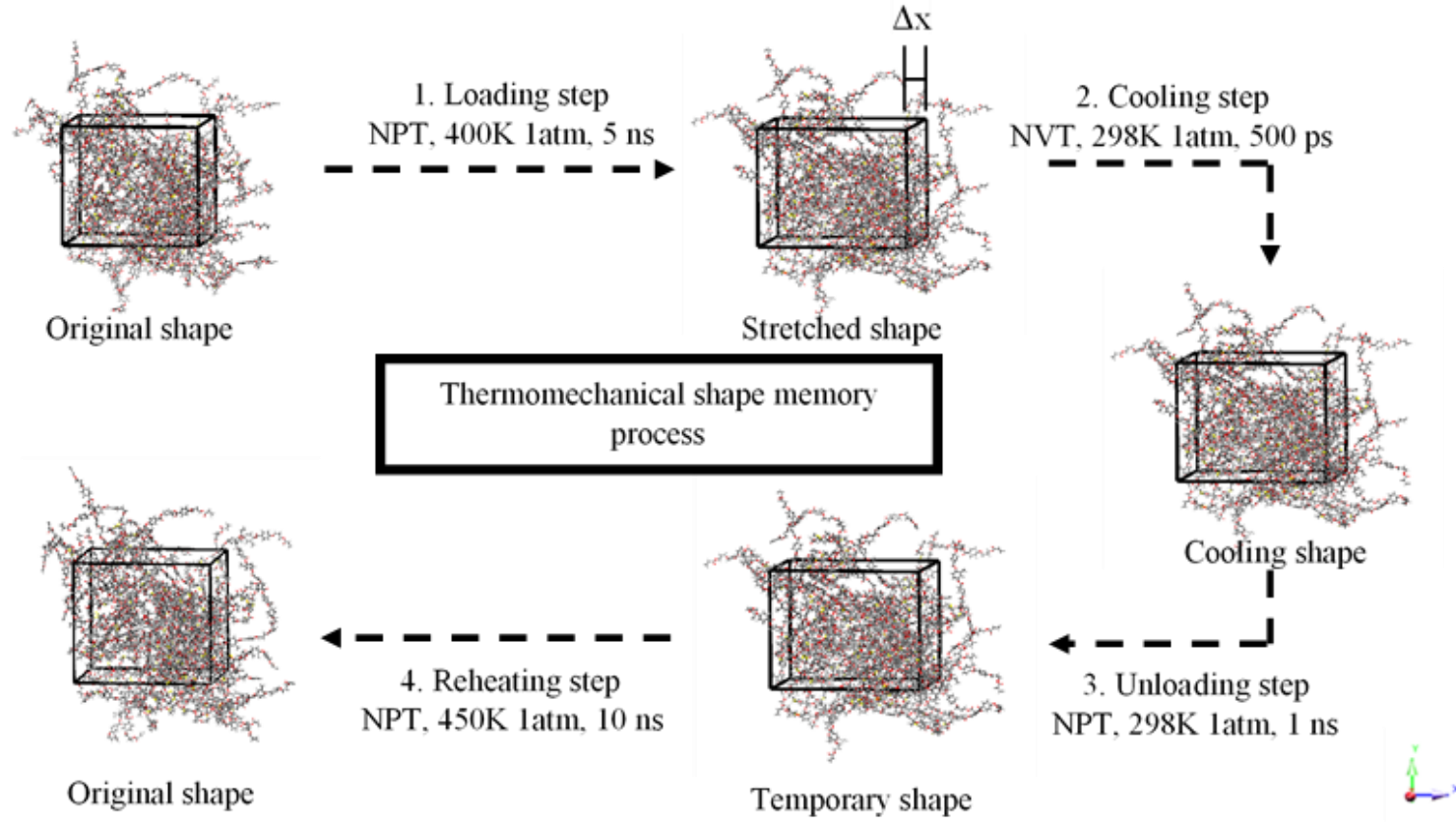
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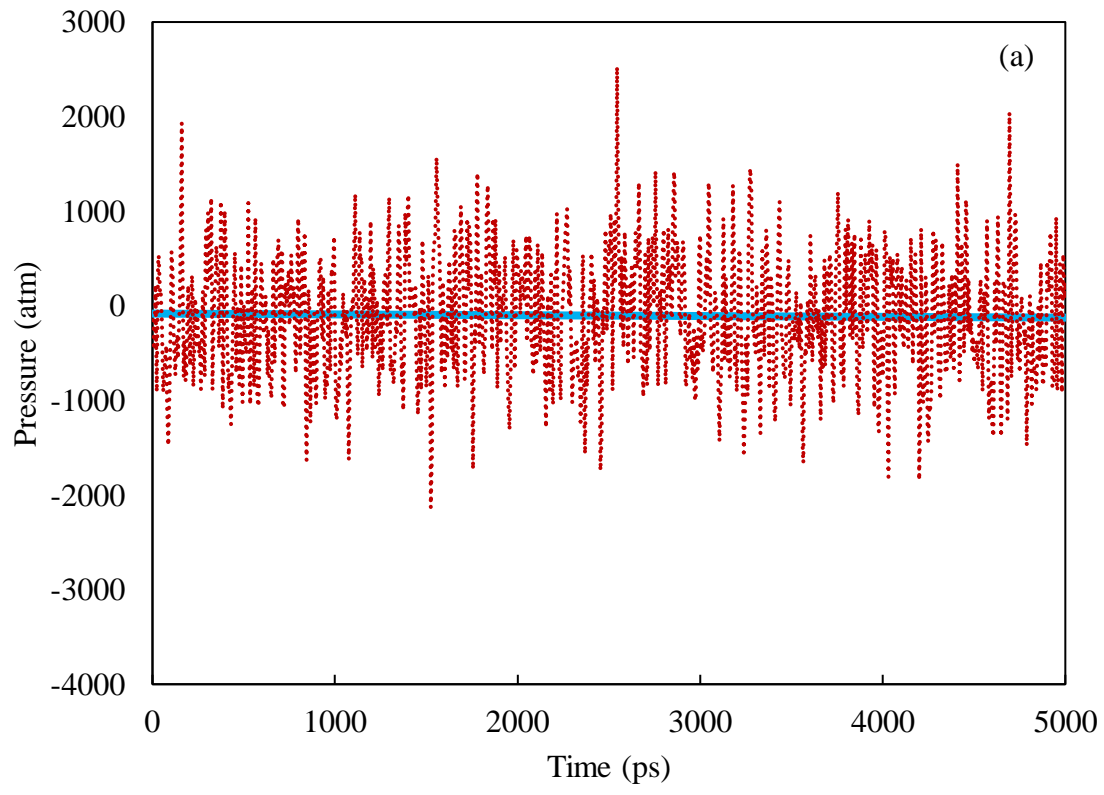
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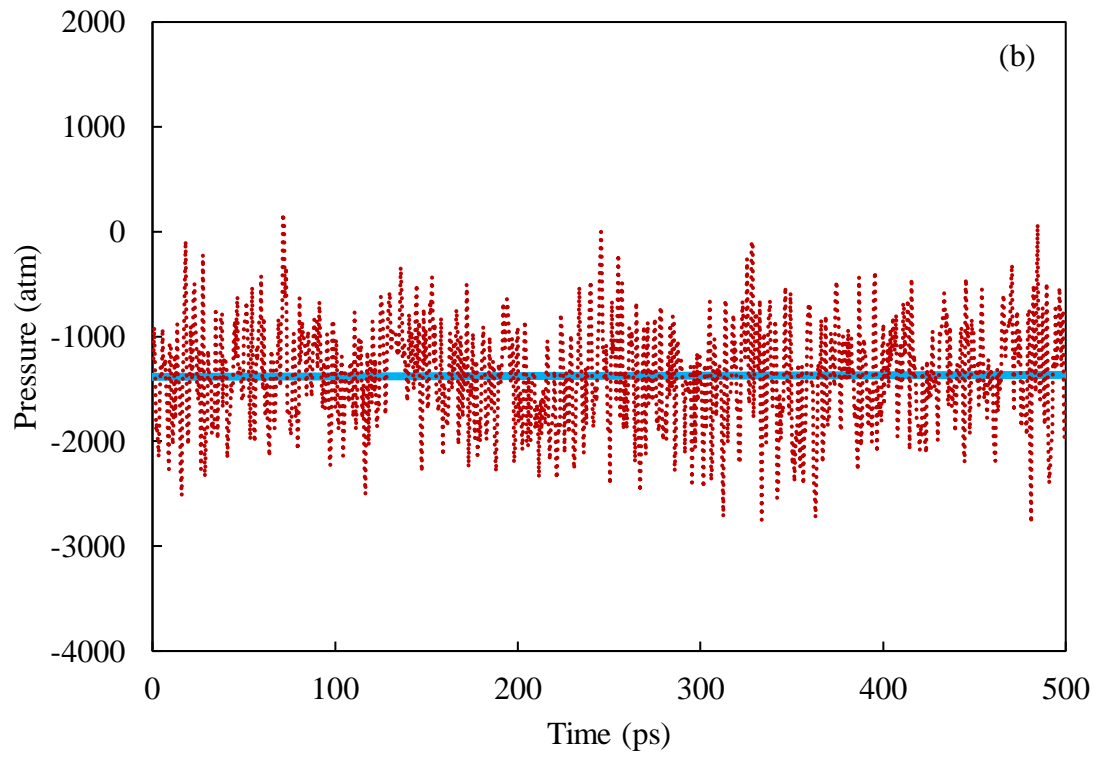
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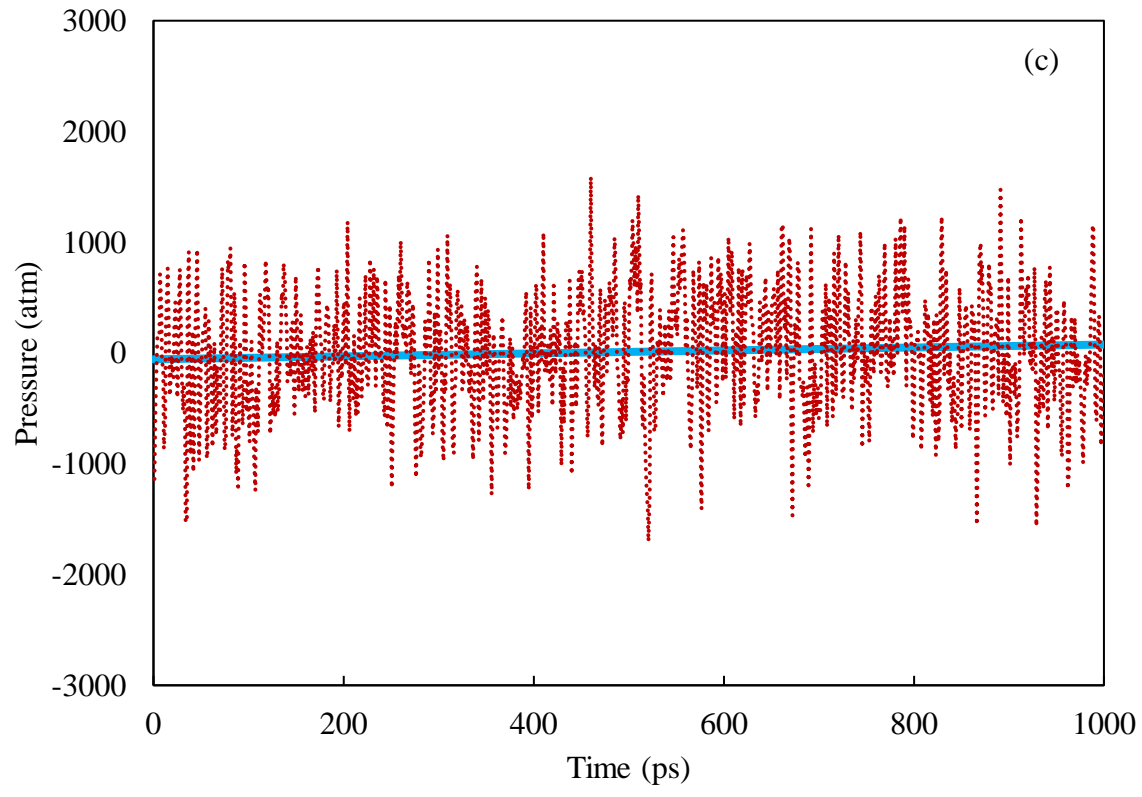
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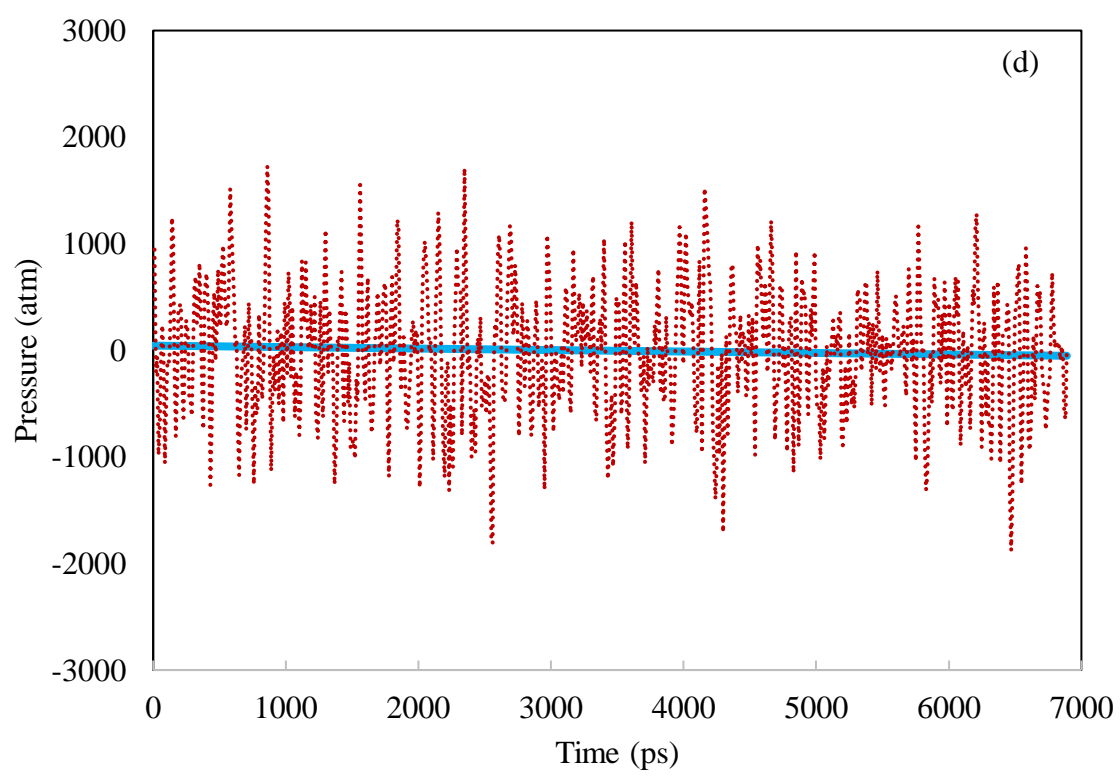
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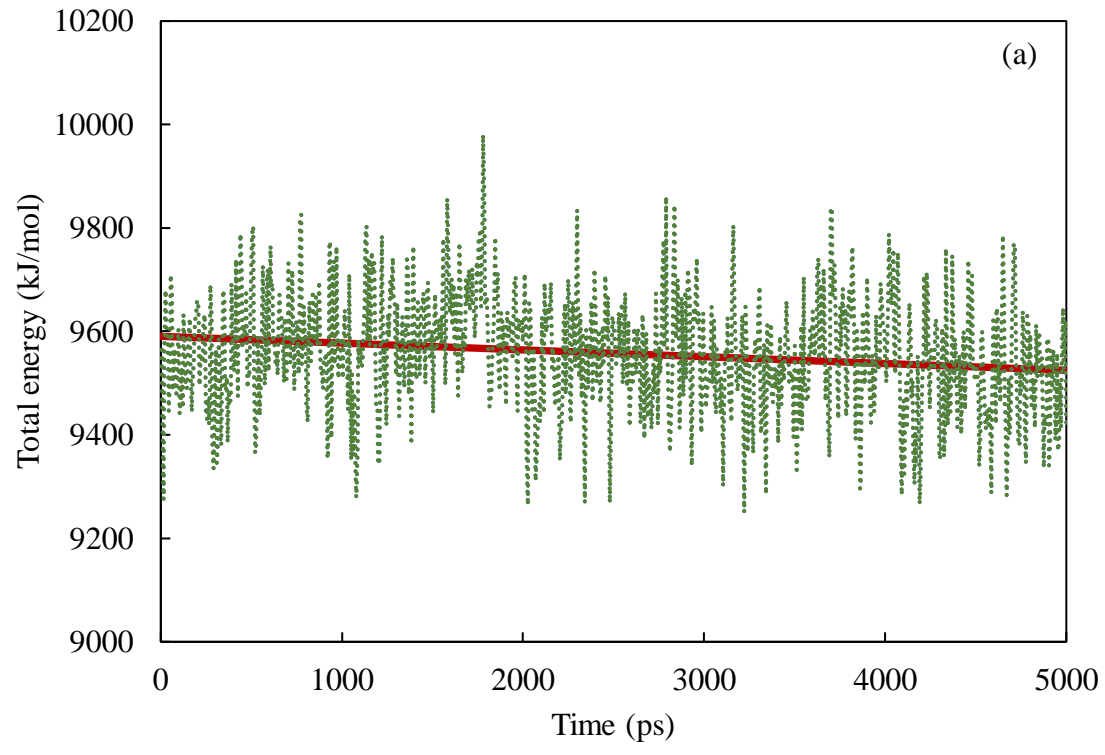
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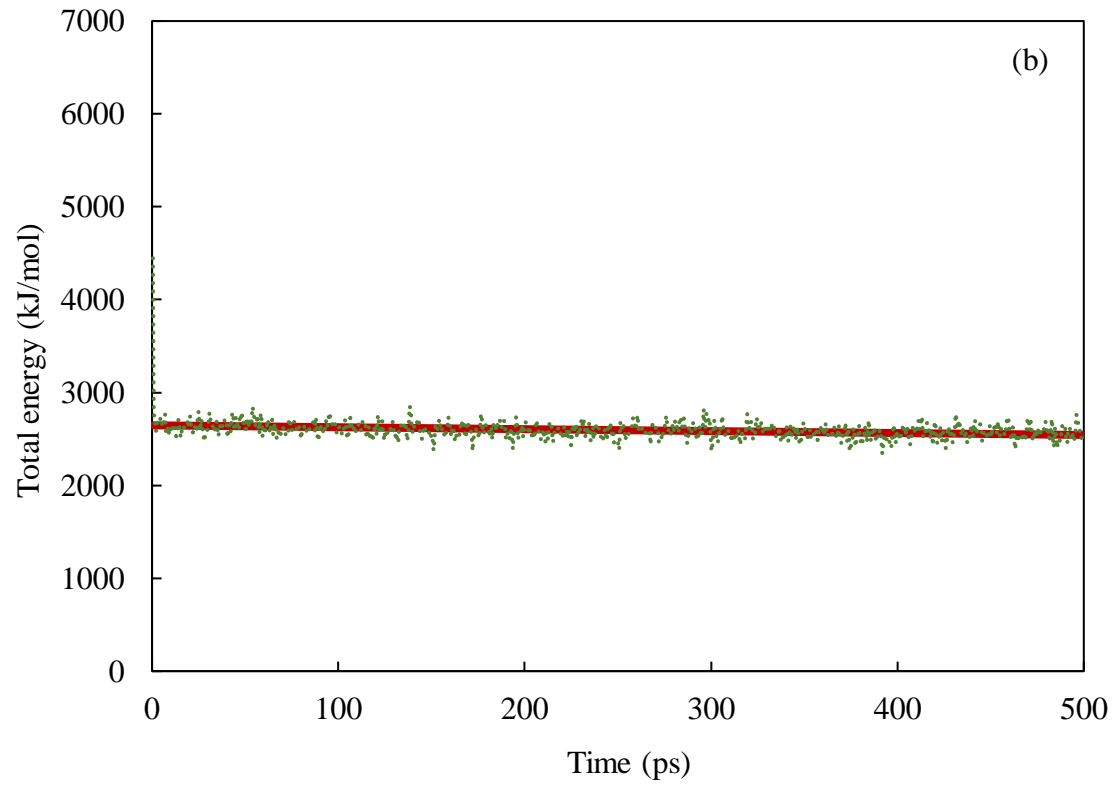
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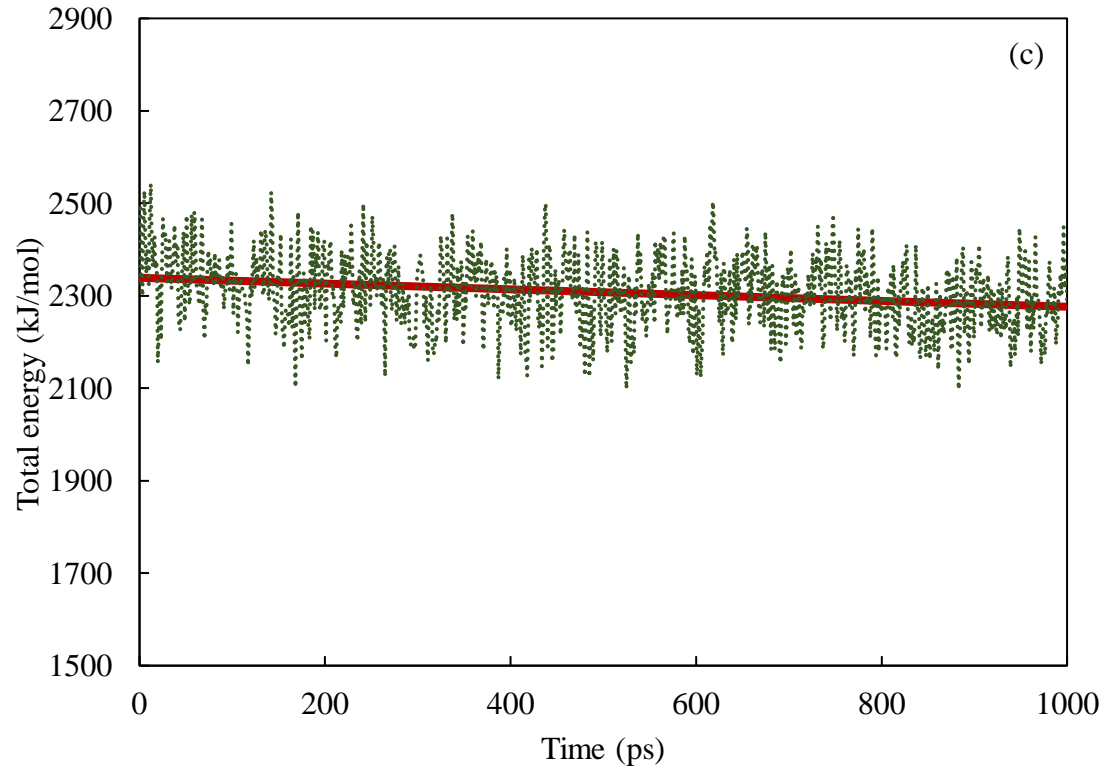
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