

# The role of fire in the coevolution of soils and temperate forests

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## Key Points:

- Wildfire strongly influences forest hydro-geomorphology, yet its net effect on coevolution of soil-vegetation systems is not yet constrained
- We used a new numerical model to test the hypothesis that fire is central to coevolution of forest-soil systems in SE Australia
- The hypothesis was supported and the role of fire was found to increase with aridity due to higher fire frequency and less developed soils

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## 15 **Abstract**

16 Climate drives the coevolution of vegetation and the soil that supports it. Wildfire dramatically  
17 affects many key eco-hydro-geomorphic processes but its potential role in coevolution of soil-  
18 forest systems has been largely overlooked. The steep landscapes of southeastern Australia  
19 provide an excellent natural laboratory to study the role of fire in the coevolution of soil and  
20 forests, as they are characterized by temperate forest types, fire frequencies and soil depths that  
21 vary systematically with aridity. The aims of this study were to i) test the hypothesis that in  
22 Southeastern Australia, fire-related processes are critical to explain the variations in coevolved  
23 soil-forest system states across an aridity gradient, and ii) to identify the key processes and iii)  
24 feedbacks, involved. To achieve these aims we developed a numerical model that simulates the  
25 coevolution of soil-forest systems which employ eco-hydro-geomorphic processes that are  
26 typical of the flammable forests of Southeastern Australia. A stepwise model evaluation, using  
27 measurements and published data, confirms the robustness of the model to simulate eco-hydro-  
28 geomorphic processes across the aridity gradient. Simulations that included fire replicated  
29 patterns of observed soil depth and forest cover across an aridity gradient, supporting our  
30 hypothesis. The contribution of fire to coevolution increased in magnitude with aridity, mainly  
31 due to the higher fire frequency and lower post-fire infiltration capacity, increasing the rates of  
32 fire-related surface runoff and erosion. Our results show that critical feedbacks between soil  
33 depth, vegetation and fire frequency dictates the trajectory and pace of the coevolution of  
34 flammable temperate forests and soils.

## 35 **1 Introduction**

36 Interactions and feedbacks between soil and vegetation are key factors in controlling catchment  
37 eco-hydrological behavior (Donohue et al., 2007, 2012; Trancoso et al., 2016; Zhang et al.,  
38 2004). Thus, understanding how soil-vegetation systems coevolve can help explain observed  
39 variations in catchment responses and enable better predictions of change in response to future  
40 climate scenarios (Troch et al., 2015). Coevolution in this context is defined as a climatically-  
41 driven process in which interactions and feedbacks between vegetation and its supporting soil  
42 causes ongoing changes in their properties (Berry et al., 2005; Porder, 2014; Troch et al., 2015;  
43 van Breemen, 1993). Due to its interdisciplinarity, complexity and nonlinearity and because it  
44 operates outside of our observational timescales, studying the coevolution of soil-vegetation  
45 systems require models that couple ecological, hydrological and geomorphological processes and  
46 their drivers under one numerical framework (Istanbulluoglu, 2016).

47 Fire affects both vegetation and soil, and therefore likely to play a role in their coevolution. Fire  
48 changes the hydrological properties of the system by removing the canopy cover and changing  
49 the properties of the soil surface (DeBano, 2000; Inbar et al., 2014; Shakesby & Doerr, 2006),  
50 often making it more conducive to surface runoff (Nyman et al., 2010; Shakesby & Doerr, 2006)  
51 and more erodible (Noske et al., 2016; Nyman et al., 2013). These combined transient effects  
52 often result in a temporary increase in soil erosion of different magnitudes (Lane et al., 2006;  
53 Moody & Martin, 2001; Nyman et al., 2011; Prosser & Williams, 1998). Fire had also been  
54 shown to cause transient changes in the water and energy balance by altering the amount of  
55 water that infiltrates, intercepted and transpired by the local forested systems (e.g., Nolan et al.,  
56 2014).

57 The role of fire in coevolution had been mainly investigated through its geomorphic effect on  
58 landform change (Benda & Dunne, 1997; Gabet & Dunne, 2003; Istanbulluoglu et al., 2004;

59 Istanbuluoglu & Bras, 2005; Orem & Pelletier, 2016; Roering & Gerber, 2005). Here we point  
60 to an important feedback that is indirectly related to the geomorphic effects of fire that might  
61 have been overlooked. Soil depth holds an important role in controlling vegetation water holding  
62 capacity at a point by setting an upper limit to the plant available water capacity (Hahm et al.,  
63 2019). This implies that fire-driven erosion processes could potentially push soil-vegetation  
64 systems towards an alternative coevolved state by affecting its soil depth, if high fire-frequency  
65 is sustained over long timescales. Accounting for the processes that affect fire frequency is  
66 therefore necessary to fully untangle the role of fire in the development of the critical zone and  
67 landscape evolution.

68 In the landscape evolution literature, fire is often regarded as a “disturbance” and is modelled  
69 stochastically (Gabet & Dunne, 2003; Istanbuluoglu et al., 2004; Istanbuluoglu & Bras, 2005).  
70 However, evidence show that long-term fire frequency depends on processes that control the  
71 availability of burnable fuel (Pausas & Bradstock, 2007) and their moisture state (Pausas &  
72 Bradstock, 2007; Taufik et al., 2017), making it a dynamic process that is coupled to the  
73 ecohydrological state of soil-vegetation systems. This implies that fire is tightly coupled within  
74 coevolutionary feedbacks both as a forcing and as a response variable. The modelling of a fire  
75 regime that is coupled to the hydrological state of the modelled systems has been explored in  
76 some dynamics vegetation models (e.g., Gerten et al., 2004; Prentice et al., 2011; Thonicke et al.,  
77 2001, 2010; Yue et al., 2014). These models, however, do not include the geomorphic effect of  
78 fire and its consequences on processes and feedbacks in the coevolution of soil-vegetation  
79 systems. The full range of mechanisms by which fire can drive landscape change and  
80 coevolution is therefore unclear. To address this limitation, a model is required that couples fire  
81 to both ecohydrological and geomorphic processes and enables the complex coevolution of  
82 vegetation and soil to be more robustly investigated.

83 The central highlands in southeastern (SE) Australia provide an ideal natural laboratory to  
84 investigate the role of fire in coevolution of soil-vegetation systems for several reasons: (i) it is  
85 home to some of the most flammable forests on earth; (ii) a gradient in temperate climate had  
86 resulted in a range of forest types with different fire regime (Cheal, 2010); (iii) the lack of active  
87 uplift (Czarnota et al., 2014; Wellman, 1987) and the lack of glaciation below 1200 m elevation  
88 during late Pleistocene (Barrows et al., 2001) narrows down the drivers and possible geomorphic  
89 processes that might have affected coevolution in the area.

90 The aims of this study were to i) test the hypothesis that fire-related processes are critical to  
91 explain the variations in coevolved soil-forest systems across an aridity gradient in SE Australia,  
92 and ii) to identify key processes, and iii) feedbacks, involved the coevolution process. To achieve  
93 the aims we developed a numerical model (COevOLution of FLAMmable Systems -  
94 CoolFlameS) that simulates the coevolution of soil-forest systems, and is underpinned by  
95 equations that couple fundamental ecohydrological, vegetation dynamics and geomorphological  
96 processes. CoolFlameS was formulated, parameterized and calibrated to simulate systems that  
97 are typical to SE Australia. The model was evaluated by comparing model outputs of system  
98 properties and process rates against observations, measurements and published data.

99 This paper:

- 100 1. describes the conceptual framework and model development;
- 101 2. reports the results of model verification with field data;

102 3. evaluates the hypothesis and identifies interactions and feedbacks that are  
103 involved in the coevolution process.

## 104 **2 Regional description and scope**

105 The study focuses on the southern part of the Great Dividing Range, Victoria, Australia, which  
106 consists of a mix of plateaus, ridges and dissected uplands with elevations ranging from 200 to  
107 2,000 m above sea level. Geology is dominated by Paleozoic marine sedimentary rocks, with  
108 some regional igneous plutons (mainly granite and granodiorite). After peaking in late Cenozoic,  
109 uplift is now believed to be limited mainly to isostatic rebound (Czarnota et al., 2014; Wellman,  
110 1987). Climate in the region is temperate, characterized by warm, dry summers, and cool, wet  
111 winters (Stern et al., 2000). Mean seasonal temperatures range from 13.4 and -1.1 °C in winter  
112 and 25.8 to 17.6 °C in summer, for low and high elevations, respectively. Mean annual  
113 precipitation (MAP) range from 600 to 2,500 mm yr<sup>-1</sup> for low and high elevations, respectively.  
114 Interannual variability in rainfall is mainly driven by Southern Annular Mode, El Niño-Southern  
115 Oscillation, Inter-decadal Pacific Oscillation and Indian Ocean Dipole (Timbal et al., 2016).

116 The temperate forests of SE Australia are dominated by *Eucalyptus* spp., most of which are  
117 highly adapted to drought and fire (Specht & Wood, 1972). At low-intermediate elevations (200-  
118 1200m above sea level), forests range from productive, tall eucalyptus forests (Keith et al., 2009)  
119 at locations with a MAP of 1200-2000 mm yr<sup>-1</sup> to less-productive dry eucalyptus forests and  
120 woodlands in areas with a MAP of 600-1000 mm yr<sup>-1</sup> (Cheal, 2010). Across these productive  
121 temperate forests, fuel is abundant and the frequency of medium-high severity fire (ranging from  
122 10-150 years (Cheal, 2010)) is largely controlled by moisture (Bradstock, 2010; Krawchuk &  
123 Moritz, 2011; Nyman et al., 2018) rather than fuel quantity.

124 The effects of wildfire on eco-hydro-geomorphic processes in the region has been the focus of  
125 many studies (e.g., Cawson et al., 2012; Kuczera, 1987; Lane et al., 2004; Nolan et al., 2014;  
126 Noske et al., 2016; Nyman et al., 2011, 2013, 2019; Sheridan et al., 2007, 2015; Van der Sant et  
127 al., 2018; Vertessy et al., 2001). Recent studies identified that the sensitivity of the soil to post-  
128 fire erosion increases nonlinearly with aridity due to the magnitude of post-fire reduction in  
129 hydraulic conductivity at the soil surface (Noske et al., 2016; Sheridan et al., 2015; Van der Sant  
130 et al., 2018). The combined effect of the differences in forest type, fire frequency, soil properties  
131 and post-fire surface runoff response creates a gradient in the severity of erosion events across  
132 the aridity spectrum (Noske et al., 2016; Sheridan et al., 2015), from negligible in the low aridity  
133 forests (Lane et al., 2004; Sheridan et al., 2007) to severe in the more arid ones (Noske et al.,  
134 2016; Nyman et al., 2011).

## 135 **3 Numerical model**

### 136 **3.1 Model description**

137 In systems where nutrient availability is not limiting plant growth, vegetation carrying capacity is  
138 driven by the supply and demand for water and the ability of the critical zone to store it (Hahm et  
139 al., 2019). While water supply and demand are often affected by climate and topography (Nyman  
140 et al., 2014b; Rasmussen et al., 2015), the ability of a system to store water depends on soil  
141 properties, primarily depth, but also texture, porosity, and organic matter content (Clapp &  
142 Hornberger, 1978; Saxton & Rawls, 2006). CoolFlameS is therefore based on the conceptual  
143 model whereby the structure of soil-forest systems at any point in time and space is controlled by

144 the legacy of climatically driven feedbacks between vegetation, fire and the ability of the system  
145 to hold moisture, which is dictated by soil depth (Hahm et al., 2019). In the proposed model  
146 (Figure 1a) soil moisture plays a central role in coevolution by controlling evapotranspiration  
147 and primary productivity (Montaldo et al., 2005; Rodriguez-Iturbe, 2000) and by  
148 ecohydrological control on the flammability of the system (Krueger et al., 2016). Soil water  
149 holding capacity in the model is determined primarily by soil depth, and together with climate  
150 (i.e., aridity), limits evapotranspiration and biomass accumulation (Klein et al., 2015;  
151 Milodowski et al., 2015). Fire removes vegetation and causes changes to soil hydraulic  
152 properties (Certini, 2005; DeBano, 2000), which temporarily increases erosion potential (Nyman  
153 et al., 2013; Wagenbrenner et al., 2010). By this approach, changes in climate and fire frequency  
154 can alter the depth of the soil, its water and biomass holding capacity, and thereby drive  
155 coevolution.

156 In order to investigate the role of fire in the coevolution of soil-vegetation systems, it is  
157 necessary to couple fire with ecological, ecohydrological and geomorphic processes. One of  
158 CoolFlameS major novelty is that it bridges the gap between landscape evolution, land surface  
159 models and flammability through coupling ecohydrology, vegetation dynamics and moisture  
160 deficits with geomorphic processes that control soil depth. This feature is missing from existing  
161 models. For this purpose, we employ a combination of new and well-established generic  
162 equations that represent ecohydrological, geomorphological and forest dynamics processes as  
163 defined in existing literature. Moreover, in order to represent SE Australian systems  
164 appropriately, CoolFlameS was developed from deep ecohydrological and geomorphic  
165 understanding stemming from decades of intensive research and model development. Due to the  
166 long-timescale and multitude of disciplines and processes involved in the coevolution of soil-  
167 vegetation systems, simplicity was prioritized over complexity during model development. To  
168 overcome this potential shortcoming, model components (i.e., ecohydrology, geomorphology  
169 and fire) were evaluated by comparing simulation results with measurements and published  
170 values.

### 171 3.2 Model Formulation

172 In this section, existing generic equations are described in short. Where appropriate, the reader is  
173 directed to the existing literature for additional information. In case new or modification to  
174 generic equations is introduced, more detailed description and reasoning are added. In some  
175 cases, the reader is referred to the Supporting Information supplement for additional information  
176 regarding specific model components. Model parameter values are described in Table 1.

177 CoolFlameS, which is inspired by work of others (eg., Istanbuluoglu & Bras, 2006; Yetemen et  
178 al., 2015; Zhou et al., 2013), couples ecohydrological and geomorphological processes to drive  
179 coevolution by numerically solving a set of ordinary differential equations for surface energy,  
180 soil moisture, biomass and soil depth (Istanbuluoglu, 2016):

Energy: 
$$\frac{dS_h}{dt} = R_{net} - G - H_s - \lambda ET \quad (1)$$

Soil moisture: 
$$nH \frac{ds}{dt} = I - ET - D \quad (2)$$

181 Biomass: 
$$\frac{dB}{dt} = NPP - B(f_F b_{mort} + k_b) \quad (3)$$

182 Soil depth: 
$$\frac{dH}{dt} = \frac{\rho_r}{\rho_s} \varepsilon - (E_F + E_D) \quad (4)$$

183 Change in surface heat storage  $dS_h$  ( $\text{MJ m}^{-2}$ ) with time,  $t$  (day) (Eqn. 1), is the difference  
 184 between net solar radiation ( $R_{net}$ ;  $\text{MJ m}^{-2} \text{d}^{-1}$ ) and ground ( $G$ ;  $\text{MJ m}^{-2} \text{d}^{-1}$ ), sensible ( $H_s$ ;  $\text{MJ m}^{-2}$   
 185  $\text{d}^{-1}$ ) and latent ( $\lambda ET$ ; where  $\lambda$  is latent heat of vaporisation and  $ET$  is evapotranspiration;  $\text{MJ m}^{-2}$   
 186  $\text{d}^{-1}$ ) heat fluxes (Istanbulluoglu, 2016).

187 Daily change in soil moisture ( $\text{mm d}^{-1}$ ; where  $s$  is relative soil saturation;  $n$  is soil porosity; and  
 188  $H$  is soil depth, respectively; Eqn. 2) is the balance between the rate of infiltrated water ( $I$ ;  $\text{mm d}^{-1}$ )  
 189  $ET$  ( $\text{mm d}^{-1}$ ) and deep drainage ( $D$ ;  $\text{mm d}^{-1}$ ).

190 Change in standing biomass density (as dry mass),  $B$ , ( $\text{kg m}^{-2} \text{d}^{-1}$ ; Eqn. 3) is the difference  
 191 between net primary production ( $NPP$ ;  $\text{kg m}^{-2} \text{d}^{-1}$ ) and the processes that remove biomass,  
 192 simplified here as senescence and combustion. In simple terms, combustion is modelled using  
 193 fire frequency ( $f_F$ ;  $\text{d}^{-1}$ ) and the mean proportion of biomass that is removed by each fire,  $b_{mort}$ .  
 194 Similar to other models (Williams & Albertson, 2005; Yetemen et al., 2015; Zhou et al., 2013),  
 195 senescence coefficient ( $k_b$ ) includes within it various ecological processes from self-thinning to  
 196 seasonal  $LAI$  response.  $k_b$  is modelled here as a function of the recovery state of the vegetation  
 197 as will be described below.

198 Change in soil depth,  $H$  ( $\text{m yr}^{-1}$ ; Eqn. 4), is modelled as the balance between the rate of soil  
 199 production ( $\varepsilon$ ) and erosion ( $E$ ;  $\text{m yr}^{-1}$ ). For simplicity, we assume that soil is produced directly  
 200 from bedrock to transportable minerals without intermediate conversion to saprolite (Brantley et  
 201 al., 2017). Downslope transport of sediment includes diffusive- and advective- (or fluvial)  
 202 processes (eg., Dietrich et al., 2003; Tucker & Hancock, 2010) denoted here by the terms  $E_D$  and  
 203  $E_F$ , respectively. While advective processes occur at the soil surface, both  $\varepsilon$  and  $E_D$  depend on  $H$   
 204 to account for the depth to disturbance at the bedrock interface (Heimsath et al., 1997; Roering,  
 205 2008).  $\rho_r$  and  $\rho_s$  in equation 4 are rock and soil densities ( $\text{kg m}^{-3}$ ), respectively.

206 Figure 1b illustrates the way in which ecohydrological and geomorphological processes and fire  
 207 are represented and coupled in the model. Rainfall is partitioned by the canopy and at the soil  
 208 surface. Daily potential evapotranspiration evaporates water from the canopy and soil surface  
 209 and drives the coupled transpiration-primary production process (e.g., Williams & Albertson,  
 210 2005). To represent a dynamically coupled fire cycle, stand flammability is linked to cumulative  
 211 soil moisture deficit (Krueger et al., 2016), which is directly affected by the annual water  
 212 balance. Stochastic fires remove a proportion of the vegetation and change the sediment  
 213 availability and hydrological properties of the soil surface, all of which have been shown to  
 214 cause an increase in overland flow and fluvial erosion (Noske et al., 2016; Van der Sant et al.,  
 215 2018).

### 214 3.2.1 Land surface representation

215 CoolFlameS simulates the evolution of a hypothetical point on a hillslope located 50m  
216 downslope from the ridgetop. This drainage position was chosen in order to avoid modelling the  
217 complex erosion-deposition balance (Patton et al., 2018) and substantial water subsidies further  
218 down in the convergent zone (Western et al., 1999), while still maintaining the potential effect of  
219 topographic aspect on the energy balance (Rasmussen et al., 2015). For simplicity, inflow of  
220 subsurface water from the ridgetop is assumed negligible.

221 Similar to other models (Williams & Albertson, 2005; Yetemen et al., 2015; Zhou et al., 2013),  
222 the modelled land surface is proportionally divided horizontally between vegetated and  
223 unvegetated surface areas (Figure 1c). The horizontal division is computed dynamically using  
224 modelled leaf area index ( $LAI_l$ ) and is used to partition fluxes of energy (expressed here as  $E_p$ )  
225 and rainfall at the canopy level. Partitioning of a given flux by the forest canopy is modelled  
226 using two dynamic variables: vegetation cover,  $V_C$  and the leaf area index ratio of the covered  
227 fraction,  $LAI_r$ . These dynamic variables are calculated using:

$$V_C = \frac{LAI_l}{LAI_{gmax}} \quad (5a)$$

$$LAI_r = \frac{LAI_l}{LAI_{lmax}} \quad (5b)$$

228 where  $LAI_{gmax}$  and  $LAI_{lmax}$  are the maximum potential  $LAI$  in SE Australia and the maximum  
229 potential  $LAI$  for a given set of edaphic and climatic conditions (i.e., long-term aridity and soil  
230 depth), respectively. Using this approach  $V_C$  represents the proportion of area that is covered by  
231 vegetation and  $(1 - V_C)$  represents bare proportion (Williams & Albertson, 2005; Yetemen et al.,  
232 2015; Zhou et al., 2013).  $LAI_r$  represents the recovery state of the  $LAI$  within the vegetated  
233 surface area ( $V_C$ ).  $LAI_r < 1$  indicates that the canopy of the vegetated surface area has not yet  
234 reached its full cover potential.

### 235 3.2.2 Climatic forcing

236 In the model, evapotranspiration, biomass balance and background geomorphic processes  
237 run on daily timesteps. During rainstorms, however, the model is forced with hourly rainfall, and  
238 hydrological and geomorphological processes are simulated on an hourly timestep. This  
239 transition is necessary in order to better represent infiltration excess, runoff generation and soil  
240 erosion processes that are better represented on sub-daily timesteps.

241 In order to simplify the energy balance, interterm changes in  $S_h$  are assumed negligible  
242 ( $dS_h/dt = 0$ ) thus allowing the model to be driven by potential evapotranspiration ( $E_p$ ; mm d<sup>-1</sup>)  
243 (Yetemen et al., 2015). During model simulations, daily  $E_p$  is applied using a cosine function  
244 following Small (2005):

$$E_p(DOY) = \frac{\Delta d}{2} \cos \left[ 2\pi \left( \frac{DOY - L_T - N_d/2}{N_d} \right) \right] + E_{p-daily} \quad (6)$$

245 where  $DOY$  is day of the year;  $\Delta d$  ( $\text{mm d}^{-1}$ ) is the difference between maximum and minimum  
 246 values of daily  $E_p$ ;  $L_T$  is the lag (in days) between peak  $E_p$  and peak solar forcing;  $N_d$  is number  
 247 of days in a year (set to 365 assuming no leap years); and  $E_{p-daily}$  is mean annual daily  $E_p$  ( $\text{mm}$   
 248  $\text{d}^{-1}$ ). Values for  $\Delta d$  and  $E_{p-daily}$  were obtained by calculating monthly  $E_p$  with  $R_{net}$  and  $T_a$  data  
 249 using the Priestly-Taylor equation (Priestley & Taylor, 1972):

$$E_p = 1.26 \frac{\Delta}{(\Delta + \gamma)} (R_{net} - G) \quad (7)$$

250 where  $\Delta$  is the slope of the saturation vapor pressure ( $\text{kPa } ^\circ\text{C}^{-1}$ ), which is a function of  $T_a$ ; and  $\gamma$   
 251 is psychrometric constant ( $\text{kPa } ^\circ\text{C}^{-1}$ ). On daily timesteps,  $G$  from a vegetated surface can be 1-2  
 252 orders of magnitude smaller than the other heat fluxes in the surface energy balance (Brutsaert,  
 253 1982) and was thus neglected in the calculation of  $E_p$  (Eqn. 7).

254 On days with rainfall, a Poisson-shaped hourly rainfall ( $p$ ,  $\text{mm h}^{-1}$ ) is applied using a single-site  
 255 Neyman-Scott Rectangular Pulse (NSRP) model (Cowpertwait et al., 1996). For this purpose,  
 256 NSRP model simulator (Camici et al., 2011; Tarpanelli et al., 2012) was calibrated using existing  
 257 long-term hourly rainfall records, as is described in Text S1.

### 258 3.2.3 Ecohydrology

259 Ecohydrology in CoolFlameS employs an ensemble of new and modified published equations  
 260 and novel approaches to solve equation 2 by partitioning rainfall and energy (represented as  $E_p$ )  
 261 across the land surface on a daily basis. On days with rainfall, however, equation 2 is solved by  
 262 aggregating processes during 24-hours.

### 263 Rainfall interception

264 Rainfall interception is modelled as a simple bucket-type model with a probability distribution  
 265 approach (Kandel et al., 2005) to account for rainfall intensity. Here we use a two-step method to  
 266 model actual interception ( $C_a$ ;  $\text{mm h}^{-1}$ ) and actual throughfall ( $P_{thr}$ ;  $\text{mm h}^{-1}$ ). First, we use we  
 267 use modelled leaf area index ( $LAI_l$ ) to spatially partition the hourly rainfall into the portion that:  
 268 (i) falls directly over the vegetated surface ( $P_V$ ;  $\text{mm h}^{-1}$ ); and (ii) reaches the soil surface by  
 269 passing through the leaves, branches and trees ( $P_B$ ;  $\text{mm h}^{-1}$ )(Figure S1). In the second step  $P_V$  is  
 270 temporally partitioned to account for rainfall intensity on interception.  $P_V$  and  $P_B$  can be then  
 271 calculated using:

$$P_V = p V_C LAI_r \quad (8a)$$

$$P_B = p [1 - V_C LAI_r] \quad (8b)$$

272 CoolFlameS tracks actual canopy moisture storage  $c_o$ , defined as the proportion of the  
 273 canopy water holding capacity ( $C_{cap}$ ; mm) that is occupied by water ( $1 \geq c_o \geq 0$ ).  $C_{cap}$  is  
 274 calculated using  $C_{cap} = S_{LAI} LAI_l$ , where  $S_{LAI}$  (mm LAI<sup>-1</sup>) is the amount of water that the can be  
 275 stored for a given unit leaf area (Table 1).  $S_{LAI}$ , was calibrated using achieving around 20%  
 276 interception loss (as a proportion of rainfall) under the wettest climatic scenario, assuming it  
 277 resembles a mature wet Eucalyptus regnans forest (Vertessy et al., 2001).  $C_a$  and  $P_{thr}$  are then  
 278 calculated using:

$$C_a = c_{prop} P_V \quad (9a)$$

$$P_{thr} = P_B + P_V(1 - c_{prop}) \quad (9b)$$

279 where  $c_{prop}$  (-) is the proportion of the rainfall that is intercepted and remains the canopy (Eqn.  
 280 S2). To account for rainfall intensity in the interception process,  $c_{prop}$  is computed using a  
 281 probability distribution approach, assuming that the hourly rainfall is exponentially distributed  
 282 (Kandel et al., 2005). In the approach,  $c_{prop}$  is calculated by using the Cumulative Distribution  
 283 Function of  $P_V$ , with the available canopy water stores ( $C_f$ ) as a cut-off value ( $P_V$ ; Eqn. 8a). Text  
 284 S2 in the Supplementary information provides additional information with regards to the way the  
 285 probability distribution approach is used to calculate  $c_{prop}$ .

### 286 Infiltration and surface runoff

287 A simple conceptual representation of water movement into and within the soil profile is  
 288 employed in order to model the partitioning of throughfall at the soil surface. In this concept, the  
 289 movement of water into the soil is controlled by a competition between its capacity to allow  
 290 infiltration and its ability to allow water movement within it.  $I_p$  is calculated using:

$$I_p = \min(I_c, K_s) \quad (10)$$

291 where  $I_p$  is infiltration potential;  $I_c$  is infiltration capacity; and  $K_s$  is saturated hydraulic  
 292 conductivity (all in mm h<sup>-1</sup>). The partitioning of throughfall ( $P_{thr}$ ) into actual infiltration ( $I_a$ ;  
 293 mm h<sup>-1</sup>) and surface runoff (Q; mm h<sup>-1</sup>) is computed using a probability distribution approach,  
 294 similar to the method used in the partitioning of hourly rainfall in the interception process  
 295 (Kandel et al., 2005).  $I_a$  and Q are calculated using:

$$I_a = \min(i_{inf} P_{thr}, s_E) \quad (11a)$$

$$Q = P_{thr} - I_a \quad (11b)$$

296 where  $i_{inf}$  is the proportion of  $P_{thr}$  that infiltrates through the soil surface; and  $s_E$  (mm) is the  
 297 actual pore volume that is left in the soil profile to accommodate the infiltrating water, calculated  
 298 using:  $s_E = (1 - s)nH$ .  $i_{inf}$  is calculated using the Cumulative Distribution Function of  $P_{thr}$ ,  
 299 with  $I_p$  as a cut-off value (Eqn. S3). Text S2 in the Supplementary information provides

300 additional information with regards to the way the probability distribution approach is used to  
 301 calculate  $i_{inf}$ .

## 302 **Evapotranspiration**

303 Actual evapotranspiration rate ( $ET_a$ ; mm d<sup>-1</sup>) is modelled following Rodriguez-Iturbe et al.  
 304 (1999a) and Laio et al., (2001). A few modifications had been done to the employed approach to  
 305 account for the partitioning of energy across the modelled land surface.

306 In this approach, which was used in several other models (Istanbulluoglu & Bras, 2006; Yetemen  
 307 et al., 2015; Zhou et al., 2013)  $ET_a$  is scaled between zero and maximum possible daily ET  
 308 ( $ET_{max}$ , mm h<sup>-1</sup>) using available soil moisture. We assume that the available energy is first used  
 309 to evaporate water that was intercepted by the canopy.  $ET_{max}$  is therefore modelled by  
 310 partitioning the remainder of the available energy ( $E_p - E_i$ ; where  $E_i$  is the rate of interception  
 311 loss in mm d<sup>-1</sup>) into maximum transpiration ( $T_{max}$ ) and maximum soil evaporation ( $E_{max}$ ) across  
 312 the land surface (using  $V_c$  and  $LAI_r$ ).

313

$$ET_{max} = T_{max} + E_{max} \quad (12a)$$

$$T_{max} = [E_p - E_i] V_c LAI_r \quad (12b)$$

$$E_{max} = E_s [E_p - E_i] [1 - V_c LAI_r] \quad (12c)$$

314 where  $E_s$  reduces  $E_p$  to achieve maximum soil evaporation (Istanbulluoglu et al., 2012; Zhou et  
 315 al., 2013). Evaporation rate of intercepted water,  $E_i$ , is calculated using:

$$E_i = \min(E_p, C_o C_{cap}) \quad (13)$$

316 Once  $ET_{max}$  is calculated, actual evaporation,  $ET_a$ , is then computed using:

$$ET_a = ET_{max} \beta(s) \quad (14a)$$

$$\beta(s) = \begin{cases} 0 & s \leq s_h \\ E_w \frac{s - s_h}{s_w - s_h} & s_h < s \leq s_w \\ \frac{s - s_w}{s_i - s_w} & s_w < s \leq s_i \\ 1 & s > s_i \end{cases} \quad (14b)$$

317 where  $\beta$  is the evapotranspiration efficiency term that scales nonlinearly across the plant  
 318 available water capacity continuum; and  $s_h, s_w, s_{fc}$ , and  $s_i$  are degree of saturation at  
 319 hygroscopic capacity, wilting point, field capacity and incipient stomata closure (defined as the  
 320 degree of saturation value below which vegetation start to close their stomata due to water  
 321 stress), respectively (Laio et al., 2001; Rodriguez-Iturbe et al., 1999b); and  $E_w$  is an evaporation  
 322 scalar for conditions when  $s$  is under wilting point, and has the value of 0.1 (Laio et al., 2001;  
 323 Rodriguez-Iturbe et al., 1999b). Values for  $s_h, s_w$  and  $s_{fc}$  are for clay loam soil (Clapp &  
 324 Hornberger, 1978), which is on average the dominant soil type in the model domain (Rees,  
 325 1982). The value for  $s_i$  was estimated to be between  $s_{fc}$  and  $s_w$  (Table 1).

326 In order to represent and simplify plant available water dynamics in the model, the following  
 327 assumptions were made: (i) soil properties are homogenous throughout the soil profile and  
 328 readily accessible to plant roots (ii) subsurface inflows from upslope are considered negligible;  
 329 (iii); the excess soil moisture drains vertically and is lost via deep drainage, which only occurs  
 330 when  $s$  is above field capacity:  $s_{fc} < s \leq 1$ . By keeping other soil hydrological properties  
 331 constant, plant available water capacity is dictated solely by soil depth.

332 Finally, deep drainage,  $D$  ( $\text{mm h}^{-1}$ ), is modelled as a simple function that incorporates available  
 333 soil moisture and saturated hydraulic conductivity ( $K_s$ ;  $\text{mm h}^{-1}$ ), following Zhou et al. (2013).

$$D(s) = K_s s^{(2b_{ret}+3)} \quad (15)$$

334 where  $b_{ret}$  is a water retention parameter (Table 1).

### 335 3.2.4 Biomass balance

336 Biomass balance is modelled similar to Williams and Albertson (2005) and Zhou et al. (2013). In  
 337 this model, biomass balance (Eqn. 3) is coupled to the energy (Eqn. 1) and soil moisture (Eqn. 2)  
 338 dynamics through the effect of ET on gross primary production (GPP). Some modifications to  
 339 the existing biomass balance model were implemented to account for: (i) the different  
 340 representation of the land surface; (ii) the initiation of post-fire recovery; and (iii) limits of  
 341 biomass accumulation at a point.

342 Daily net primary production ( $\text{kg m}^{-2} \text{d}^{-1}$ ) is coupled to plant transpiration ( $T_a$ ;  $\text{mm h}^{-1}$ ), and is  
 343 modelled as the difference between gross primary production and autotrophic respiration  
 344 Following Zhou et al. (2013):

$$NPP = \mu T_a WUE \rho_w \omega \quad (16)$$

345 where  $\mu$  is the ratio between  $NPP/GPP$  (Waring et al., 1998);  $WUE$  is water use efficiency  
 346 ( $\text{kg}_{CO_2} \text{kg}_{H_2O}^{-1}$ );  $\omega$  is the conversion ratio of  $CO_2$  to dry matter ( $\text{kg}_{DM} \text{kg}_{CO_2}^{-1}$ ) and  $\rho_w$  is  
 347 density of water ( $\text{kg m}^{-3}$ ).  $T_a$  is calculated as a proportion of actual ET using  $T_a =$   
 348  $T_{max}/ET_{max} ET_a$ . For simplicity, all tree functional groups throughout the domain are assumed  
 349 to be comprised from the Eucalyptus genera and share the same carbon assimilation traits.

350 Similar to Williams and Albertson (2005) and Zhou et al. (2013),  $B$  is divided into leaf ( $B_l$ ) and  
 351 structural ( $B_s$ ; which includes stem and root biomass) biomass pools. Using their approach, daily  
 352  $NPP$  (Eqn. 16) is partitioned between  $B_l$  and  $B_s$  using a simple allocation coefficient  $\Phi$ , which  
 353 depends on the state of  $LAI_l$  relative to its maximum potential state (calculated using  $\Phi = [1 -$   
 354  $(LAI_l/LAI_{lmax})]$ ).  $LAI_l$  is calculated daily using  $LAI_l = B_l SLA$ , where  $SLA$  ( $\text{LAI kg}^{-1}$ ) is  
 355 specific leaf area (Table 1).

356 Daily rate of change in  $B_l$  and  $B_s$  are modelled daily using the following ordinary differential  
 357 equations:

$$\frac{dB_l}{dt} = \Phi NPP + k_R B_{lmax} - k_{sl} B_l \quad (17a)$$

$$\frac{dB_s}{dt} = (1 - \Phi) NPP - k_{ss} B_s \quad (17b)$$

358 where  $k_{sl}$  and  $k_{ss}$  are leaf and structural biomass turnover coefficient ( $d^{-1}$ );  $k_R$  is the leaf  
 359 biomass accumulation rate factor that initiates and propagates  $B_l$  recovery during the first year  
 360 after a fire ( $d^{-1}$ ). Forest and vegetation dynamic processes such as self-thinning and wind  
 361 breakage are implicitly represented in the coefficient  $k_{ss}$ .

362 In order to constrain the accumulation of biomass and to prioritize positive biomass  
 363 increments during post-fire recovery, a logistic function for  $k_{ss}$  was introduced:

$$k_{ss} \left( \frac{B_s}{B_{smax}} \right) = \left( \frac{k_{ssmax}}{1 + \exp^{-a_{kss} \left( \frac{B_s}{B_{smax}} - c_{kss} \right)}} \right) \quad (18)$$

364 where  $B_{smax}$  is the maximum structural biomass holding capacity at a point; and  $a_{kss}$  and  
 365  $c_{kss}$  are coefficients that were calibrated to achieve the regeneration of 90% of  $B_{smax}$  within ~200  
 366 years (Keith et al., 2014) under wet climatic scenarios. The variable  $k_{ssmax}$  represents the  
 367 maximum possible value for  $k_{ss}$ , and is calculated using  $k_{ssmax} = NPP(1 - \Phi)/B_{smax}$   
 368 assuming that: (i) maximum turnover is reached when structural biomass had reached steady-  
 369 state conditions (i.e.,  $dB_s/dt = 0$  and  $B_s = B_{smax}$ ; Eqn. 17b); and that (ii)  $LAI_l$  had almost fully  
 370 recovered ( $\Phi \approx 0$ ).

371 In CoolFlameS, biomass density at a point is assumed to be constrained by the supply and  
 372 demand for water and the ability of the coupled soil-vegetation systems to store it. Maximum  
 373 biomass density,  $B_{max}$  ( $kg\ m^{-2}$ ), is therefore defined, assuming it decreases exponentially with  
 374 aridity (i.e., increase in dryness) and increases exponentially with soil depth (i.e., increase in  
 375 water holding capacity):

$$B_{max} = \alpha_b \left( \exp^{-m_1 \overline{AI}_{100}} \right) (1 - \exp^{-m_2 H}) \quad (19)$$

376 where  $\alpha_b$ ,  $m_1$  and  $m_2$  (Table 1) are calibrated parameters; and  $\overline{AI}_{100}$  is a 100-years mean of  
 377 annual aridity index calculated using  $\overline{AI}_{100} = \overline{E_p}/\overline{P}$  (where  $\overline{E_p}$  and  $\overline{P}$  are mean annual potential  
 378 evapotranspiration and rainfall, respectively). The timeframe for calculating  $\overline{AI}_{100}$  was chosen to  
 379 overcome annual fluctuations in climate, which in any case not expected to produce drastic  
 380 changes in maximum biomass values. Maximum potential LAI values for a given  $B_{max}$  is then  
 381 calculated using the empirical relationship:

$$LAI_{lmax} = LAI_{gmax} (1 - \exp^{-m_3 B_{max}}) \quad (20)$$

382 where  $LAI_{gmax}$  and  $m_3$  are calibrated parameters.  $LAI_{gmax}$  represents the maximum possible  
 383 LAI in native Eucalyptus forest.  $LAI_{gmax}$ ,  $LAI_{gmax}$  and  $LAI_l$  are used to partition the modelled  
 384 surface area between the vegetated and bare proportions using Eqn. 5a and 5b.  $B_{max}$  and  
 385  $LAI_{lmax}$  are calculated on daily timesteps. Maximum leaf biomass,  $B_{lmax}$ , is then calculated  
 386 using  $B_{lmax} = LAI_{lmax}/SLA$ , and  $B_{smax}$  using  $B_{smax} = B_{max} - B_{lmax}$ .

### 387 3.2.5 Soil depth balance

388 We use a combination of generic, modified and new equations to model the daily change  
389 in soil depth (Eqn. 4). The geomorphic processes are represented on a daily timestep, however,  
390 fluvial erosion,  $E_F$ , which depend on hourly rainfall is summed over 24 hours.

### 391 Soil production and hillslope diffusion

392 A generic exponential function (Heimsath et al., 1997) was chosen to express the rate of  
393 soil production,  $\varepsilon$  ( $\text{m d}^{-1}$ ):

$$\varepsilon = \varepsilon_0 \exp^{-H \cos(S_{50})/H^*} \quad (21)$$

394 where  $H \cos(S_{50})$  is soil depth normal to the slope at 50 m from the ridgeline,  $H^*$  is the e-  
395 folding depth of the soil production rate; and  $\varepsilon_0$  is maximum soil production when  $H = 0$ .

396 Erosion due to diffusive processes describe gravity-driven movement of sediments such  
397 as soil creep, wetting-drying cycles, bioturbation, dry ravel etc. (Dietrich et al., 2003; Gabet et  
398 al., 2003; Roering et al., 1999, 2010). Soil erosion due to hillslope diffusion is modelled using a  
399 generic equation that describes the nonlinear, depth-dependent diffusive sediment flux ( $q_d$ ;  $\text{m}^2 \text{d}^{-1}$ ),  
400 following Roering (2008):

$$q_d = -\frac{K_c S}{1 - \left(\frac{S}{S_c}\right)^2} \quad (22)$$

401 where  $S_c$  is the angle of repose;  $S$  is hillslope gradient; and  $K_c$  ( $\text{m}^2 \text{d}^{-1}$ ) is a constant that scales  
402 non-linearly with soil depth, calculated using  $K_c(H) = \eta(1 - \exp^{-\beta_r H})$ , where  $\eta$  and  $\beta_r$  are  
403 calibrated constants (Roering, 2008). Net soil loss from these processes,  $E_D$ , is modelled by  
404 calculating the difference between incoming and outgoing  $q_d$  values for a pixel that its center is  
405 at 50m down from the ridgeline. A Detailed description for calculating  $E_D$  is presented in Text  
406 S3.

### 407 Fluvial processes

408 Fluvial erosion depends on soil erodibility, which in an unburnt state is assumed to be  
409 uniform with depth. Studies from SE Australia have shown that after a severe wildfire the top  
410 part of the soil loses its cohesiveness and immediately becomes highly erodible (Nyman et al.,  
411 2011; Smith et al., 2011b). The loss of cohesiveness was found to be related first and foremost to  
412 the combustion of root biomass close to the soil surface (Nyman et al., 2013). Nyman et al.  
413 (2013) found that the non-cohesive layer (that consists of mixture of gravel, sediment, ash and  
414 wood debris) varies between 7.5-9.1 mm in depth. We therefore conceptually divide soil profile  
415 into two distinct layers. We define that all the soil profile is considered cohesive (CO) in its  
416 unburnt state. During the first year after a fire, only the top-most layer of soil becomes non-  
417 cohesive (NC) overlying a cohesive mantle. Fluvial erosion from CO and NC soil layers are  
418 treated differently.

419 In CoolFlameS fluvial erosion is driven by infiltration excess overland flow ( $Q$ ) and  
420 hence modelled on an hourly basis. We assume that erosion from the CO layer is limited by its  
421 erodibility ( $K_e$ ,  $\text{h m}^{-1}$ ), and therefore classify it as detachment-limited.

422 Hourly detachment limited fluvial erosion rate ( $E_{FDL}$ ,  $\text{m h}^{-1}$ ) is modelled using a generic  
 423 equation for calculating the difference between excess and critical shear stress ( $\tau$  and  $\tau_{crit}$ ,  
 424 respectively; Eqn. 23). Detachment limited erosion ( $E_{FDL}$ ,  $\text{m h}^{-1}$ ) is computed using the excess  
 425 shear stress equation, which is widely used in the geomorphic literature (Istanbulluoglu, 2016;  
 426 Tucker & Hancock, 2010; Wagenbrenner et al., 2010):

$$E_{FDL} = \frac{K_e[\tau - \tau_{crit}]}{\rho_s} \quad (23)$$

427 where  $\tau$  and  $\tau_{crit}$  (Pa) are boundary and critical shear stress, respectively.  $\tau$  is calculated using  
 428 Manning's equation:  $\tau = \rho_w g n_T^{n_{st}} q_{60}^{m_{st}} (\sin S_{50})^{m_{st}}$ , where  $Q_{60}$  ( $\text{m}^3\text{h}^{-1}\text{m}^{-1}$ ) is discharge at  
 429 50 m down the slope;  $n_{st}$  and  $m_{st}$  are 0.6 and 0.7, respectively; and  $n_T$  is Manning's roughness  
 430 (Table 1). Due to lack of empirical evidence from unburnt hillslopes in SE Australia,  $K_e$  and  
 431  $\tau_{crit}$  (Table 1) were obtained from values published by Wagenbrenner et al. (2010) from  
 432 Northwestern United States. The authors reported negative  $\tau_{crit}$  values in an unburnt state,  
 433 pointing to little-to-no threshold for the initiation of detachment from unburnt hillslopes during  
 434 overland flow experiments. Therefore,  $\tau_{crit}$  value was set to zero (Table 1) for overland flow,  
 435 making detachment limited erosion solely a function of discharge and the erodibility of the CO  
 436 soil mantle.

437 Erosion from the NC layer is assumed to be transport limited (Nyman et al., 2013),  
 438 depending on the transport capacity of the overland flow and the quantity of available sediment.  
 439 Post-fire availability of transportable material on hillslopes is not unique to SE Australia  
 440 (Cannon et al., 2001). Here, however, in order to model transport limited erosion ( $E_{FTL}$ ,  $\text{m h}^{-1}$ ),  
 441 we use a combination of generic equations for stream power ( $\Omega$ ;  $\text{kg m}^{-1}\text{h}^{-3}$ ) with equations that  
 442 are more specific to what had been observed in SE Australia (Nyman et al., 2013). The basic  
 443 equations are presented below. The reader is encouraged to seek additional details in the  
 444 supplementary information (Text S4).

445 Transport limited erosion is calculated using ( $E_{FTL}$ ,  $\text{m h}^{-1}$ ): -

$$E_{FTL} = H_{NC_o} h_{pNC} \Omega \quad (24)$$

446 where  $H_{NC_o}$  is the depth (m) of the NC layer;  $h_{pNC}$  is the proportion of the NC layer that is  
 447 eroded per unit time (Eqn. S6); and  $\Omega$  is the stream-power ( $\text{kg m}^{-1}\text{h}^{-3}$ ), calculated using  
 448 Manning's equation (Text S4). Nyman et al. (2013) found that the removal of the NC layer  
 449 occurs during short-duration high-intensity rainstorms. We therefore model  $\Omega$  using the peak 15-  
 450 minute surface runoff ( $Q_{15}$ ;  $\text{mm h}^{-1}$ ) by assuming that hourly rainfall is exponentially distributed  
 451 and that  $Q_{15}$  (which is calculated using the 3rd quartile of the hourly runoff) is the result of the  
 452 most intense 15-minute rainfall within the hour (Text S4; Eqn. S5). For simplicity, we assume  
 453 that the NC layer prevents detachment limited erosion from occurring until all of it is removed.  
 454 After the first year following wildfire, all the soil profile regains its cohesiveness and erosion  
 455 returns to be detachment limited (Nyman et al., 2013).

## 456 3.2.6 Wildfire and its effects

### 457 Flammability

458 Only high severity wildfires are considered in CoolFlameS due to the minor effects of  
459 fires of lower severity on the woody vegetation and soil processes (Prosser & Williams, 1998).  
460 Fire occurrence is often modelled as a Poisson or Bernoulli process with either an equal  
461 probability of occurring each year (Istanbulluoglu et al., 2004; Istanbulluoglu & Bras, 2005) or  
462 as a function of time since last fire (Gabet & Dunne, 2003). Wildfire in Australia's temperate  
463 forests is highly correlated with fuel moisture (Bradstock, 2010; Nolan et al., 2016). A simple  
464 fire model was therefore developed by coupling the probability of fire to the flammability of the  
465 modelled system, which is in turn linked to its annual soil moisture deficit. We consider annual  
466 soil moisture deficit to be a reliable indicator for flammability of the system as it represents its  
467 long-term cumulative moisture deficit and plant stress (Krueger et al., 2016). Flammability ( $F_p$ )  
468 is modelled using:

$$F_p = \kappa_f s_{pdef} + \delta \quad (25)$$

469 where  $s_{pdef}$  is the cumulative number of days during the previous year that soil moisture was  
470 below a certain moisture deficit (or flammability) threshold ( $s_{cut}$ ); and  $\kappa_f$  and  $\delta$  are calibration  
471 parameters.  $s_{cut}$  (Table 1) is calibrated using Average Fire Cycle estimates of typical SE  
472 Australian forests based on previous work (Cheal, 2010; Kennedy & Jamieson, 2007). Details of  
473 the fire modelling approach and calibration process are given in Text S5.  $F_p$  is calculated in  
474 summer for every year of simulations whereby a fire occurs whenever it is higher than a random  
475 number generated from a uniform distribution.

### 476 Post-fire change in infiltration capacity

477 Aside from changing the cohesiveness of the soil surface (section 3.2.5), fire alters the  
478 infiltration capacity of the soil by increasing water repellency (DeBano, 2000). Infiltration  
479 capacity,  $I_c$  ( $\text{mm h}^{-1}$ ), is calculated annually as a function of long-term aridity ( $\overline{AI}_{100}$ ) and time  
480 since fire (Langhans et al., 2016):

$$\ln(I_c) = r_{a_{y=i}} \overline{AI}_{100} + r_{b_{y=i}} \quad (26)$$

481 where  $r_{a_{y=i}}$  and  $r_{b_{y=i}}$  are constants which change depending on the number of years ( $y = i$ )  
482 since the last fire (i.e., first year, second year and unburnt). During model simulations  $\overline{AI}_{100}$  is  
483 calculated daily and combined with time since fire to calculate  $I_c$ . Mean 100-year aridity index is  
484 considered here arbitrarily assuming an estimated lag between changes in climate to significant  
485 changes in vegetation and soil hydraulic properties. Values for  $r_{a_{y=i}}$  and  $r_{b_{y=i}}$  parameters were  
486 calibrated using a published data from the study area for burnt (Table 2 in Langhans et al., 2016)  
487 and unburnt forests as described in Text S6.

### 488 Tree mortality and post-fire regeneration

489 The response of SE Australian temperate forest vegetation to fire can be divided into two  
490 main strategies: (i) "Fire Sensitive" Species, or "Obligate seeders", that die and regenerate from

491 seed, which dominates forests under damp-wet rainfall regime; and (ii) “*Fire Tolerant*” *Species*,  
 492 or “resprouters” that regenerate through resprouting of epicormics shoots, and dominate forests  
 493 under lower-intermediate rainfall regime (eg., Clarke et al., 2015; Fairman et al., 2016). The two  
 494 recovery strategies in these forests control the effect of fire and the rate of recovery. Applying a  
 495 simple approach, it is assumed that the proportion of tree species that are hosted in a given  
 496 location varies non-linearly with aridity. Using this assumption, every modelled site, depending  
 497 on its aridity, has different proportions of these two types strategies, which determines the  
 498 vegetation response to fire (Clarke et al., 2015).

499 In the model, leaf biomass ( $B_s$ ) is reset to zero immediately after every fire (assuming all  
 500 fires are severe) regardless of the type of response. In order to account for fire effects on tree  
 501 mortality, structural biomass ( $B_s$ ; Eqn. 17b) is scaled down after each fire using a mortality  
 502 factor ( $b_{mort}$ ), which is modelled using:

$$b_{mort} = \begin{cases} 1 & \overline{AI} < 1 \\ \alpha_{mort} \overline{AI}^{-\beta_{mort}} & \overline{AI} \geq 1 \end{cases} \quad (27)$$

503 where  $\alpha_{mort}$  and  $\beta_{mort}$  are calibration parameters (Table 1). The function was parameterized  
 504 based on local observations and expert opinion depending on estimates of the proportion of fire  
 505 tolerant species and fire sensitive species across the domain.

506 In order to initiate recovery, we assume that leave biomass,  $B_l$ , is the first to regenerate.  
 507 Leaf biomass accumulation factor ( $k_R$ ; Eqn. 17a) is used in this case to initiate the recovery and  
 508 propagate the rate in which  $B_l$  accumulates during the first year after a fire:

$$k_R = f_c \Phi k_{lp} \theta_m \quad (28)$$

509 where  $f_c$  is a Boolean variable that gets the value of 1 only in a year after a fire to activate leaf  
 510 recovery from seeds or resprout;  $k_{lp}$  is leaf production rate ( $d^{-1}$ ) which is a calibration parameter  
 511 (Table 1); and  $\theta_m$  is a modifier that depends on soil moisture, calculated using :

$$\theta_m = \begin{cases} 1 & s \geq s_i \\ \left\{ \frac{s - s_w}{s_i - s_w} \right\}^M & s_i > s \geq s_w, \\ 0 & s < s_w \end{cases} \quad (29)$$

512 where  $M$  is a calibrated coefficient (Table 1). Using  $\theta_m$  in equation 28 allows the leaf biomass  
 513 regeneration to occur maximum rates when there is sufficient soil moisture, and in lower rates  
 514 when soil moisture is limited.

### 515 3.3 Parametrization and calibration

516 In order to constrain the model to our defined climo-spatial domain, some of its  
 517 components were parameterized and calibrated using observations and data from representative  
 518 field data sites (Inbar et al., 2018; Nyman et al., 2018; Walsh et al., 2017) that vary in rainfall  
 519 (940-1748 mm yr<sup>-1</sup>) and aspect orientation (paired north and south facing hillslopes; Figure 2).  
 520 Details of these sites are elaborated in Text S7 and Table S5 in the supporting information.

521 In each site, soil depth was measured from soil pits approximately 50m downslope from the  
 522 ridgeline. Biomass values were estimated by matching observed forest type and structure with

523 corresponding published values (Grierson et al., 1992; Volkova et al., 2015). These values of  
524 biomass and soil depth, combined with several anchoring points (i.e., assuming that zero soil  
525 depth holds zero biomass, regardless of aridity) were then plotted with aridity for each of the 10  
526 sites in order to acquire coefficients for equation 19 for calculating  $B_{max}$ . Biomass values for  
527 each site were paired with measured Plant Area Index (PAI) (reported in Walsh et al., 2017) to  
528 calculate coefficients for equation 20 in calculating  $LAI_{lmax}$ .

### 529 3.4 Numerical implementations

530 The numerical model solves for soil depth ( $H$ ), soil moisture ( $s$ ), canopy water store ( $c_o$ ) and  
531 biomass (structural and leaf pools:  $B_s$  and  $B_l$ ) for a hypothetical point 50 m down from the  
532 ridgeline. A single simulation starts with a predefined soil depth and prescribed climatic forcing  
533 depending on rainfall regime and aspect (Table 2). When the simulations start, structural and leaf  
534 biomass are initialized by calculating their maximum values using prescribed edaphic and  
535 climatic conditions using equation 19.

536 Slope gradient of 0.52 at 50 m ( $S_{50}$ ) was defined to roughly represent the steep hillslopes across  
537 the central highlands.  $S_{50}$  remain constant across all model simulations in order to obtain  
538 uniformity while varying only climatically driven eco-hydro-geomorphic processes. Results are  
539 discussed in context of this limitation. Mean slope from the three steepest sites (i.e., Eildon,  
540 Reefton and Frenchman's Spur (Table S5; Figure 2) was assumed to be representative of the  
541 steep hillslopes across the study area.  $S_{50}$  was then calculated by: (i) generating a combined  
542 gradient and distance-from-ridgetop curve from digital elevation model covering the three sites:  
543 and (ii) solving a third-order polynomial function fitted to the hillslope fraction of the data (i.e.,  
544 the distance below the first slope-gradient inflection point) for distance value of 50 m (Text  
545 S8). Hillslope aspect, which is associated with variable incoming solar radiation and potential  
546 evapotranspiration ( $E_p$ ), is defined as either north (equatorial) or south (polar) facing, to  
547 maximize the differences in climatic forcing for a given rainfall regime.

548 Model simulations alternate between daily and hourly timesteps for a pre-defined number of  
549 years (see flow chart in Figure S6). Evapotranspiration, biomass production and soil depth  
550 balance are calculated on a daily basis. On rainy days, however, processes that are driven by  
551 rainfall (such as: rainfall interception, infiltration, runoff and fluvial erosion) are modelled on an  
552 hourly basis for 24 hours. Using hourly rainfall allows the model to better represent inter-storm  
553 hourly variations in intensity which is critical for capturing post-fire geomorphic response. This  
554 means that some state variables (such as  $s$ ,  $c_o$  and  $H$ ) are updated both daily and hourly. Updates  
555 in state variables are computed using Euler's method for processes that operate both on a daily  
556 and hourly basis as detailed in Text S9.

557 Eight climatic scenarios that create a gradient of aridity were defined by a combination of four  
558 possible mean annual precipitation over two potential evapotranspiration ( $E_p$ ) regimes for north  
559 and south facing aspects (Table 2). The eight climatic scenarios (Table 2) were used in  
560 simulations designated for model evaluation and for running numerical experiments. Single-site  
561 NSRP model was used to simulate hourly rainfall according to a prescribed rainfall regime  
562 before the start of each simulation. Four sites, representing rainfall gradient (ranging from MAP  
563 of  $\sim 721$  mm  $yr^{-1}$  to  $\sim 1610$  mm  $yr^{-1}$ ; Figure 2), were chosen to calibrate the NSRP model  
564 simulator (Camici et al., 2011; Tarpanelli et al., 2012) and simulate hourly rainfall (refer to Text  
565 S1 in the supporting information for more details).

566 The model takes a simple approach for simulating  $E_p$  (Eqn. 5) typical for north and south facing  
567 hillslopes. Typical means for  $E_{p-daily}$  and  $\Delta d$  at 50 m down the slope were calculated by  
568 averaging their values across the three steepest sites for either north- or south-facing aspects (i.e.,  
569 Eildon, Reefton and Frenchman's Spur; Table S5; Figure 2). These calculations were made using  
570 monthly data for net radiation ( $R_{net}$ ) and temperature ( $T_s$ ) for each site from an available  
571 downscaled gridded resource which take into account slope and aspect, and include both direct  
572 and diffuse shortwave and net long wave radiation (Nyman et al., 2014b), and based on long  
573 term data from Australian Bureau of Meteorology (Australian Bureau of Meteorology, 2017).  
574 With this approach we assume that  $E_p$  does not vary significantly within each aspect as long as  
575 the hillslope gradient is similar (Table S5). Mean values used for  $E_{p-daily}$  were 5.15 mm d<sup>-1</sup> and  
576 3.62 mm d<sup>-1</sup>; and for  $\Delta d$  were 5.78 mm d<sup>-1</sup> and 6.48 mm d<sup>-1</sup> for north and south facing hillslopes,  
577 respectively.

578 Fire is treated in the model as a stochastic event that depends on annual soil moisture deficit as a  
579 proxy for flammability (Text S5). Once a year (arbitrarily chosen to be the 1st of January to be  
580 aligned with summer in the southern hemisphere), fire occurs whenever a random number  
581 (generated from a uniform distribution) is lower than the  $P_f$ . After fire,  $B_l$  (and  $LAI$ ) resets to  
582 zero, exposing the soil to the direct rainfall impact;  $B_s$  is reduced by a pre-defined proportion  
583 (Eqn. 27);  $I_c$  reduces (Eqn. 26) and the surface soil becomes NC, all with a potential positive  
584 impact on fluvial erosion rates and soil depth. The model distinguishes between detachment-  
585 limited and transport-limited erosion (which is a particular post-fire case observed in SE  
586 Australia, and may not apply everywhere). We argue that post-fire sediment availability is  
587 limited both by time and quantity, which is better represented when these two types of erosion  
588 are separated.

589

### 590 **3.5 Model evaluation**

591 We framed the model evaluation in a stepwise manner, whereby components that are essential  
592 for the coevolution of soil depth and vegetation (i.e., ecohydrology, fire frequency distribution,  
593 surface processes) are evaluated independently. The model evaluation is performed by  
594 comparing model fluxes and state variables with published and unpublished data (Table S7 and  
595 S6).

#### 596 **3.5.1 Ecohydrology**

##### 597 **Soil moisture**

598 We examined whether CoolFlameS could reproduce observed trends in soil moisture under  
599 different climatic conditions by comparing the annual number of days that relative soil saturation  
600 ( $s$ ) was above or below thresholds of plant water stress ( $s_i$ ) and below threshold of flammability  
601 ( $s_{cut}$ ) with similar metrics calculated for soil moisture measurements from six field sites (Table  
602 S5). For this step in the evaluation, model simulations were run for 1 kyr under different climatic  
603 scenarios (Table 2) with no fire and no change in soil depth.

604 Soil moisture measurements that were used for model evaluation (Table S6) were collected over  
605 one year (12/2015-12/2016) on north and south facing hillslopes in CH, RT and TT (Table S5;  
606 Figure 2). Depending on soil depth, between three to five soil moisture sensors (EC5; Decagon

607 Devices) were installed at different depths in soil pits at each site, from the soil surface to the  
608 bedrock-soil interface. Sensors were connected to a Campbell Scientific CR-1000 logger and  
609 each one was individually calibrated in the lab using soils packed at bulk densities corresponding  
610 to field measurements. Depth-integrated soil moisture at each site was calculated by integrating a  
611 linear function that was fitted to volumetric water content values at each sensor depth. Soils were  
612 assumed to be clay loam (as it is a typical soil across in the area (Rees, 1982)) and porosity value  
613 of 0.5 was used to calculate degree of saturation from both modelled and measured soil moisture.

### 614 **Ecohydrological partitioning**

615 Ecohydrological partitioning was evaluated by comparing the modelled outputs with published  
616 values from three local studies. Note that the locations of these studies (Figure 2) were different  
617 than our data collection sites that were used for grounding the model to local systems (Figure 2).  
618 The evaluation of the ecohydrological partitioning was done by using climate scenarios (i.e.,  
619 rainfall/aspect combinations; Table 2) that are similar to those in the published studies in order to  
620 obtain matching model simulations. Average values for ET components (interception loss,  
621 transpiration and soil evaporation) were calculated from 1 kyr-long model simulations under  
622 each climatic scenario, with fire turned “off” to avoid disturbance effects that are not  
623 representative of the field measurements of ET that are used in the evaluation. Results from  
624 simulations under “south-facing wet” climate (i.e., aridity 0.82; Table 2) were compared with  
625 data from Vertessy et al.(2001), which represents Eucalyptus regnans with a typical average  
626 MAP of 1800 mm yr<sup>-1</sup>. Results from simulations under “north-facing wet” climatic scenario (i.e.,  
627 aridity 1.17; Table 2) were compared with Nolan et al. (2014), representing wet-mixed species  
628 forest on a north-west facing hillslope with MAP of ~1550 mm yr<sup>-1</sup>. Results from simulations  
629 under “north-facing damp” (i.e., aridity 1.49; Table 2) climatic scenario were compared with  
630 data reported in Mitchell et al. (2012), representing a north-east facing hillslope with ~1200 mm  
631 yr<sup>-1</sup> (averaged over 4 years), which is dominated by a mixed species sclerophyll forest.

### 632 **3.5.2 Fire frequency**

633 The fire model was evaluated by comparing distribution of modelled fire frequency under  
634 different climatic and edaphic conditions with what is known and described in relevant literature.  
635 Modelled fire frequency was calculated using outputs from a set of 100 kyr simulations driven  
636 by wet, dry and damp climatic scenarios (aridity of 0.83, 1.05 and 1.49, respectively; Table 2)  
637 under steady state soil depth conditions for each.

### 638 **3.5.3 Surface processes**

#### 639 **Surface runoff and peak discharge**

640 We compared modelled surface runoff ratio (SRR) with independent measurements by Van der  
641 Sant et al. (2018), who quantified SRR using 8 m plots on five sites across an aridity gradient  
642 (Figure 2). Modelled SRR were calculated for 8 difference climate scenarios (Table 2) over 10  
643 kyr simulations, while only SRR for the first-year post-fire were averaged. Surface runoff in the  
644 model is being produced on an hourly basis. In this analysis simulated surface runoff generated  
645 from all rainstorms below 5 mm h<sup>-1</sup> were excluded because experimental error in the field  
646 measurement can be relatively large for these small rainfall events.

647 Modelled peak discharge was compared to measured values in order to evaluate the model's  
648 ability to simulate high-magnitude surface runoff events. Measured discharge data was obtained  
649 from a study that monitored two small (0.29 ha) and relatively dry (mean aridity of 2.2) north  
650 and south facing headwater catchments at Stoney Gully Catchment, Victoria (SE Australia),  
651 starting approximately six months after it was severely burnt on February 2009 (Noske et al.,  
652 2016)(Figure 2). A detailed description of the experimental setting is described in Noske et al.  
653 (2016). Modelled values were calculated using  $Q_{15}$  (Eqn. S5) from all first years after each fire  
654 after running the model driven by a dry climatic scenario (aridity 2.61 Table 2).

### 655 **Erosion and denudation**

656 Modelled erosion rates were compared to erosion measurements from local studies (Cawson et  
657 al., 2013; Lane et al., 2006; Noske et al., 2016; Smith et al., 2011a). Modelled mean sediment  
658 yield was obtained by calculating cumulative erosion rates from 100 kyr simulations for each of  
659 the climatic scenarios described in Table 2. Denudation rates ( $\text{mm kyr}^{-1}$ ) were calculated using  
660 cumulative erosion rates (both from fluvial and diffusive processes) across the length of each  
661 simulation. From the total of 100 kyr of each simulation, modelled post fire sediment yield was  
662 calculated from the first years after each fire, while background (unburnt) values were calculated  
663 from the rest (i.e., from all the years excluding the first year after fire).

### 664 **3.6 Numerical experiments**

665 Numerical experiments were developed to;

- 666 i) test the hypothesis that in SE Australia, fire-related processes are critical to explain the  
667 variations in coevolved soil-forest system states across an aridity gradient,
- 668 ii) identify the key fire-related processes that are important for coevolution
- 669 iii) identify any important fire-related feedbacks involved in the coevolution of soil-  
670 vegetation systems.

671 One of the caveats in testing soil development models is that it is often uncertain whether the  
672 observed soil had reached a steady state depth (Phillips, 2010). A steady-state in this respect  
673 means that long-term erosion rates equals long-term soil production which results in minimal  
674 long-term change in its depth ( $dH/dt = 0$ ). Output variables that were used for testing the  
675 hypothesis, for testing model sensitivity to the effects of fire and for evaluating feedbacks in the  
676 coevolution process were soil depth and projected vegetation cover at steady-state soil depth ( $H_{ss}$   
677 and  $V_{c-ss}$ , respectively). Even though we compare these output variables with observations, we  
678 do not make any assumptions that the systems we compare them with had reached steady-state.  
679 We can, however, use the model to assess whether current systems are likely to have reached  
680 steady state by comparing them to the output variables. Preliminary analysis showed that soil in  
681 simulations driven by the wettest climatic conditions took  $\sim 150$  kyr to reach steady state depth  
682 (compared to  $\sim 30$  kyr when driven by the driest climate) starting with 0.5m deep soil.

#### 683 **3.6.1 Testing the hypothesis**

684 The hypothesis was tested by comparing the ability of simulations with and without fire to  
685 predict observed, contemporary system states. In experiment 1, model simulations were allowed  
686 to run with (+*Fire*) and without (*-Fire*) fire for the duration of 200 kyr in order to ensure that  
687 steady-state in the output variables had been reached. For each treatment, a set of eight

688 simulations were conducted with an initial soil depth of 0.5 m using the climatic scenarios  
689 detailed in Table 2. After each simulation,  $H_{SS}$  and  $V_{C-SS}$  were calculated by the mean of the last  
690 10 kyr. To test the hypothesis, modelled  $H_{SS}$  values were compared with soil depth  
691 measurements across an aridity gradient, taken from Inbar et al. (2018). In addition, the modelled  
692  $V_{C-SS}$  values were compared with gridded remotely sensed woody vegetation cover from TERN  
693 Auscover (2017). Woody vegetation cover data was extracted for 5 km square polygons near the  
694 three steepest sites (Eildon, Reefton and Frenchmen's Spur; Table S5). TERN woody vegetation  
695 cover was retrieved using long-term LANDSAT data at 30 m resolution (Gill et al., 2017). To  
696 stay constrained to the upper part of hillslopes (whereby soil depth and water availability are  
697 assumed to limit productivity) remotely sensed woody vegetation cover was extracted from grid  
698 cells that have contributing area lower than 0.1 ha. Model skill was evaluated by comparing root  
699 mean square error (RMSE) for  $H_{SS}$  and  $V_{C-SS}$  from  $+Fire$  and  $-Fire$  with observations (Table  
700 S8).

### 701 3.6.2 Identifying key fire-related processes that are important for coevolution

702 CoolFlameS incorporates two well studied mechanisms by which fire affect soil erosion: the  
703 effect of fire on soil surface properties (which incorporates both changes in infiltration capacity  
704 and soil cohesiveness) and vegetation cover. In experiment 2, each simulation was designed to  
705 run with fire, but with one of its effects turned "off". Simulations were:

- 706 (i)  $-\Delta I_c$ : Simulations with fire ( $+Fire$ ) excluding post-fire reduction in infiltration  
707 capacity.
- 708 (ii)  $-\Delta CO$ : Simulations with fire ( $+Fire$ ) excluding post-fire change in soil surface  
709 cohesiveness.
- 710 (iii)  $-\Delta LAI$ : Simulations with fire ( $+Fire$ ) excluding the effect of fire on forest cover  
711 ( $LAI$  not initialized after every fire).

712 Similar to experiment 1, eight simulations were conducted using the climatic scenarios detailed  
713 in Table 2, each starting with 0.5 m deep soil. The relative role of the effect of fire on  $I_c$ , soil  
714 cohesiveness and forest cover was evaluated by ranking RMSE values calculated by comparing  
715 the output variables from  $-\Delta I_c$ ,  $-\Delta CO$  and  $-\Delta LAI$  to those from  $-fire$  and  $+fire$  (Table S9).  
716 Results are interpreted as such: the lower (higher) the RMSE of one of the treatments when  
717 compared to  $-fire$  the higher (lower) its relative role in the effect of fire on coevolution.

### 718 3.6.3 Identifying fire-related feedbacks in coevolution

719 Simulations with abrupt changes in rainfall were conducted in order to explore the interactions  
720 and feedbacks throughout the evolution of a hypothetical soil-forest system. Temporal changes  
721 in soil depth ( $H$ ) and projected vegetation cover ( $V_c$ ) were explored by running simulations under  
722 "dry" (MAP of 720 mm yr<sup>-1</sup>) north facing hillslope with 0.2 m deep soil, which was interrupted  
723 by a 150 kyr long wet period (which was achieved by increasing rainfall to MAP 1610 mm yr<sup>-1</sup>).  
724 To single out the effect of fire on coevolution, results from simulations with fire were compared  
725 to those from simulations without. We note that this experiment is not intended to simulate real  
726 climatic fluctuations and that its purpose is for analysis of feedbacks in the coevolution process.  
727 The extreme changes in rainfall were chosen in order to maximize the impact of climate on  
728 coevolution, whilst observing how soil depth, biomass and fire regime coevolve from one  
729 steady-state to another.

## 730 4 Results

### 731 4.1 Model evaluation results

#### 732 4.1.1 Ecohydrology, flammability and fire frequency

733 Results show that, overall, CoolFlameS reproduces the observed trends in all threshold metrics  
734 with respect to aridity and MAP and gives reasonably good predictions of hydrological  
735 partitioning when compared to published data (Figure 4). The trend in modelled water stress,  
736 expressed as the proportion of days above and below incipient stomatal closure ( $s_i$ ; Figure 3a-  
737 3d), correspond well with the inverse correlation between primary productivity, biomass and  
738 canopy cover with aridity that is observed across SE Australian temperate forests (Givnish et al.,  
739 2014; Inbar et al., 2018; Keith et al., 2010).

740 Mean fire return interval (FRI) from the 100 kyr-long simulations were 18.3, 32.6 and 87.3 years  
741 for the “dry” (aridity 1.49), “damp” (aridity 1.05) and “wet” (aridity 0.83) climate scenarios,  
742 respectively (Figure 5a), which is in line with the systematic increase in the number of days  
743 above the flammability threshold at higher aridity scenarios (Figure 3e). Mean number of days in  
744 which soil moisture ( $s$ ) was equal or lower than the flammability threshold ( $s_{cut}$ ) were 139, 71  
745 and 24 days for simulations under the “dry”, “damp” and “wet” climatic scenarios. Similar trend  
746 with respect to the flammability of leaf litter across similar forest types has been identified in  
747 local field studies (Nyman et al., 2015, 2018).

748 FRI distributions from the three simulations as a function of forest age (Figure 5a-5c) resembles  
749 the “Olson” model (Olson, 1963) proposed by McCarthy et al. (2001) which describes situations  
750 by which flammability increases with forest age up to an asymptote and is typical to some  
751 Eucalyptus forests (Walker, 1981). This was verified by the plotting number of days that the  
752 modelled system was below flammability threshold (as a proxy for flammability) as a function of  
753 forest age (Figure 5d), which indeed points to such flammability behavior. The slightly higher  
754 flammability in the first two years under dry climate (Figure 5d) can be explained by the very  
755 low infiltration capacity under this climatic forcings (Table S6). This indicates that the low  
756 infiltration capacity during the first couple of years after a fire has an ecohydrological  
757 consequence, slowing vegetation recovery by reducing plant available water.

758 Several studies have shown that flammability can decrease immediately after a fire due to lack of  
759 available fuels (eg., Hurteau et al., 2019; Parks et al., 2016). According to the way that the fire  
760 model was calibrated (Text S5), flammability should not have changed with time since fire, as it  
761 was not restricted by fuel availability. The fact that flammability in the model depends on the  
762 number of days that  $s \leq s_{cut}$  causes fire probability to be lower in the first years during  
763 vegetation recovery (Figure 5d). This emergent self-limiting behavior suggests that it might be  
764 unnecessary to explicitly account for availability and moisture of burnable fuel within a  
765 coevolutionary framework.

#### 766 4.1.2 Surface runoff and geomorphic processes

767 CoolFlameS reproduces the observed trend in surface runoff ratio (SRR) with aridity (Figure 6a)  
768 and of peak discharge as a function of rainfall depth (Figure 6b). The increasing trend in runoff  
769 ratio with aridity that emerge from model simulations (Figure 6a), are consistent with published  
770 literature (Lane et al., 2006; Noske et al., 2016; Sheridan et al., 2015; Van der Sant et al., 2018),  
771 and stem from the inverse correlation between infiltration capacity and aridity (Eqn. 27). We also

772 note that the results in Figure 6 should be interpreted in context of differences in spatial scale and  
773 hillslope gradient between model and field measurements.

774 Published and modelled erosion rates for burnt (first year post-fire) and unburnt conditions are  
775 summarized in Table 3 and 4, respectively. The increasing trend in runoff ratio and peak  
776 discharge (Figure 6) is translated to a similar trend in post-fire erosion rates (Table 4). Combined  
777 with higher fire frequency, these results point to rates of long-term erosion that increase with  
778 increasing aridity, similar to what had been hypothesized (Inbar et al., 2018) and observed (Table  
779 3) in SE Australia. Published post-fire sediment yields increase with decreasing rainfall (Table  
780 3), with 1-3 order of magnitude difference compared with unburnt state with highest difference  
781 in mid-rainfall range (Cawson et al., 2013). Similarly, the difference in modelled erosion rates  
782 between burnt and unburnt states are 1-3 orders of magnitude, with 2-3 orders of magnitude  
783 between aridity 1.05-1.49 (Table 4). Modelled post-fire erosion rates from simulations under the  
784 driest climatic conditions (aridity 2.61) is  $8.51 \text{ t ha}^{-1} \text{ yr}^{-1}$ , which is similar to what had been  
785 measured by Noske et al. (2016)(Table 3).

786 Modelled denudation rates from the 8 different climatic scenarios were between 13.8-83.4 mm  
787  $\text{kyr}^{-1}$  (Table 4), which is within a similar range compared to published values. For example,  
788 Bishop (1985) suggested denudation rates in south eastern Australia during the last 15-20 Myr to  
789 be  $10 \text{ mm kyr}^{-1}$ . The author ascribed the low denudation rates to forest cover and the continent's  
790 tectonic stability. Heimsath et al. (2009) estimated denudation rate from a basin at a retreating  
791 escarpment in Northern Territory to be  $10\text{-}40 \text{ mm kyr}^{-1}$ , while Smith et al. (2012) estimated these  
792 rates to be  $27 \text{ mm kyr}^{-1}$  from a first order catchment in Victoria, SE Australia. In a recent study,  
793 Hancock et al. (2017) summarized a long term monitoring experiment of several steep  
794 catchments in New South Wales. The authors estimated denudation rates from two undisturbed  
795 forested catchments to be around  $70 \text{ mm kyr}^{-1}$ . The steepness of the catchments (mean slope of  
796  $\sim 22$  degrees) was suggested as a plausible reason for the relatively high denudation values  
797 compared to background values in the literature (such as in Fifield et al. (2010) and Bishop  
798 (1985)). The differences in scale and slope of the modelled unit could potentially explain the  
799 overprediction of denudation rate at the dry end of the aridity gradient (Table 4).

800 Model results indicate that hillslope aspect has a very significant effect on erosion and  
801 denudation rates (Table 4). In all model simulations, north (equatorial) facing aspect yielded  
802 more erosion than its south (polar) facing counterpart. Such differences are caused solely by  
803 different insolation which had been shown to cause hillslope asymmetry over geological  
804 timescales (e.g., Istanbuluoglu et al., 2008; McGuire et al., 2014; Pelletier et al., 2018; Yetemen  
805 et al., 2015). Differences in erosion rates between equatorial and polar facing hillslopes during  
806 the first year after the fire seems to decrease with aridity, but peak in aridity 1.05-1.49 in an  
807 unburnt state. Difference in denudation rates (which also includes the effect of fire frequency)  
808 between the aspects, however, peak between aridity 1.05-2 (Table 4). Over longer timescales,  
809 these results are in line with what have been reported by Inbar et al., (2018), who found a peak in  
810 hillslope asymmetry at similar aridity values.

811 Overall, soil moisture, ecohydrological partitioning, distributions of fire return interval, surface  
812 runoff ratio, peak discharge, erosion and denudation rates are predicted reasonably well across  
813 the climate scenario compared to observations and published data. This provides a satisfactory  
814 outcome of model performance despite its relative simplicity and the different environmental  
815 conditions (i.e., slope, fire severity, soil type etc.) and scale (i.e., plot-catchment) that the model  
816 outputs were compared with.

## 817 4.2 Testing the hypothesis

818 Modelled soil depth ( $H_{SS}$ ) and projected vegetation cover ( $V_{C-SS}$ ) with respect to aridity were  
819 compared to logistic functions that best fitted to measured values (Figure 7).  $H_{SS}$  and  $V_{C-SS}$   
820 predicted by model simulations with fire (+fire) replicate the observed trends and mostly sit  
821 within the 95% confidence interval calculated using observed values (Figure 7a and 7b).  
822 Simulations without fire (-fire) predict a similar trend in  $H_{SS}$  and  $V_{C-SS}$ , however they  
823 overestimate both state variables with increasing aridity when compared to observations and to  
824 model simulations with fire. Overall, model simulations with fire performed better in predicting  
825  $H_{SS}$  and  $V_{C-SS}$  (RMSE 0.27 m and 0.06, respectively) when compared to simulations without fire  
826 (RMSE 0.79 m and 0.47, respectively).

### 827 4.2.1 Identifying key fire-related processes that are important for coevolution

828 The results are used to evaluate the relative contribution to coevolution of several potentially  
829 important fire-related processes. When comparing all treatments to published and observed data,  
830 model simulations with fire (+fire) performed better in predicting the soil depth and forest cover  
831 when compared to the simulations where one of the fire-related processes was turned “off”  
832 (Table S8). Results show that the variability in the output variables from simulations when one  
833 of the fire-related processes was turned “off” increases with aridity (Figure 7c-h). RMSE values  
834 that compare these simulations with -fire and +fire are presented in Table S9. Compared to  
835  $-\Delta\text{LAI}$ , and  $-\Delta\text{CO}$ , both state variables predicted by  $-\Delta I_C$  showed the closest resemblance to  
836 those predicted by -fire. In contrast, compared to  $-\Delta I_C$  and  $-\Delta\text{CO}$ , soil depths predicted by  
837  $-\Delta\text{LAI}$  showed the highest resemblance to those predicted by +fire. The effect of  $-\Delta\text{LAI}$   
838 seemed to have lower impact on  $H_{SS}$  compared to  $V_{C-SS}$ .

### 839 4.2.2 Identifying fire-related feedbacks in coevolution

840 The results reveal some important fire-related feedbacks in the coevolution of soils and forests.  
841 The temporal evolution of soil depth ( $H$ ), projected vegetation cover ( $V_C$ ) and fire return interval  
842 (FRI) for simulations with and without fire are presented in Figure 8a-8c. Figure 8d illustrates  
843 the coevolution of soil depth, vegetation cover and fire frequency within a 2D space. In this  
844 figure, each marker represents the mean value of  $H$  and  $V_C$  within a 1 kyr-long bin. Bin size and  
845 color represent the FRI. Simulations start with a dry climate. For simulations with fire, the arrival  
846 of the wet phase after 10 kyr result in a steep increase in  $V_C$  within a 1 kyr period with only a  
847 small increase in  $H$  (Figure 7d). It takes about 50 kyr for  $V_C$  to reach steady-state and >120 kyr  
848 for  $H$  (Figure 8a-8b). FRI increase dramatically immediately after the climate changes and  
849 continues increase more gradually throughout the wet phase. A rapid decline in FRI towards its  
850 “background” state occurs as the climate switches back to a dry phase after 150 kyr, followed by  
851 a decline in  $H$  and  $V_C$ , which end up with steady-state values similar to their initial  
852 conditions (Figure 8a-8b).

853 A similar type of response to climatic changes is observed for simulations without fire (dashed  
854 green line in Figure 8a and 8b). However, both state variables increase immediately during the  
855 first dry period, probably towards their steady state values for dry climate without fire (Figure 7a  
856 and 7b). Similar to simulations with fire, the arrival of the wet phase at 10 kyr mark causes a  
857 sharp increase in  $V_C$  with only a gradual increase in  $H$  (Figure 8d). By the end of the wet phase,  $H$   
858 and  $V_C$  had already reached higher values compared to simulations with fire. The decline in  $H$

859 and  $V_c$  in simulations with fire is more gradual during the wet-to-dry transition than during the  
860 initial dry-to-wet transition (Figure 8a-8b).

861 During the coevolution without fire, both  $H$  and  $V_c$  values are consistently higher than their  
862 values from simulations with fire (Figure 8a and 8b). Overall, adjustment time in  $V_c$  as a  
863 response to climate change seems to be faster than the adjustments in  $H$ . Time to steady-state soil  
864 depth from dry-to-wet transition takes longer compared to the time it takes in the wet-to-dry  
865 transition. This behavior is less clear for the evolution of  $V_c$ .

866 The coevolution of  $V_c$ ,  $H$  shows a hysteresis pattern as a response to changes in rainfall both for  
867 simulations with and without the effect of fire (Figure 8d). However, there is a difference in the  
868 pattern between the two simulations. FRI increases as soil becomes deeper and vegetation  
869 becomes denser and seems to peak around end of the wet period. A similar decline in  $V_c$  occurs at  
870 the same time for simulation without fire. The increase in density of the 1 kyr-long bins indicates  
871 that both  $H$  and  $V_c$  had reached their steady-state values by the end of the wet period (~120-160  
872 kyr) and the second dry period (~190-200 kyr).

## 873 **5 Discussion**

### 874 **5.1 Experiment 1 - the role of fire in coevolution (Evaluating the hypothesis)**

875 Our initial hypothesis that fire-related processes are critical to explain the variations in coevolved  
876 soil-forest system states across an aridity gradient is supported by the results (Fig 7a and 7b)  
877 showing that simulation with fire are more consistent with contemporary observation that  
878 simulations without fire. Model results show that the relative role of fire increase with aridity  
879 (Figure 7a and 7b). This can be explained by the more frequent fires and higher erosion rates  
880 (Table 4) as aridity increases. As aridity increases beyond aridity 1, so does the relative  
881 contribution of fluvial erosion rates. This effect is further amplified by fire, as seen in Figure S8.

882 The fact that the predicted projected canopy cover ( $V_{c-ss}$ ) trends in a similar manner as soil depth  
883 ( $H_{ss}$ ) with respect to aridity can be explained by the change in biomass holding capacity of the  
884 soil, caused by the interaction between climate, fire and the balance between soil production and  
885 erosion on soil depth (Hahm et al., 2019). The phenomenon that erosion controls vegetation  
886 patterns was observed by Milodowski et al. (2015) in the Northern-Californian Sierra Nevada,  
887 USA, where mean basin slope, a proxy of long term erosion rate, explained 32% of variance in  
888 above ground biomass, outweighing the effect of other factors, such as mean annual  
889 precipitation, temperature and lithology. The authors ascribed this effect to the reduction in water  
890 holding capacity due to the limitation dictated by thinner saprolite.

### 891 **5.2 Experiment 2 - The role of fire-related processes in coevolution**

892 Results indicates that among the three possible effects of fire that were explored, the role of post-  
893 fire reduction in  $I_c$  on  $H_{ss}$  and  $V_{c-ss}$  was the largest (Figures 7c-7d and S7b-S7c). Post-fire  
894 reduction in  $I_c$  can explain the increasing dominance of fluvial processes at aridity values  $>1$  (as  
895 seen in Figure S8), which result in shallower soils from simulations with fire beyond that point  
896 (Figure 7a and 7b). For aridity values  $<1$ , post-fire reduction in  $I_c$  is not sufficiently large to  
897 affect surface runoff. Consequently, on slopes supporting wet forest types, the relative role of  
898 diffusive processes is higher compared to fluvial processes (Figure S8).

899 Post-fire erosion is often associated with loss of cover, increased hydrophobicity and reduction in  
900 root cohesion (Istanbulluoglu & Bras, 2005). The latter process was not implemented explicitly  
901 in CoolFlameS but is implicit within the surface cohesiveness term. Our results indicate that  
902 long-term erosion is more sensitive to reduction in  $I_c$  (and consequential increase in surface  
903 runoff) than to the amount of sediment that is available to be transported ( $-\Delta CO$ ; Figures 7e-7h  
904 and S8b-S8c). This can be explained by the interplay between the transport limited nature of the  
905 NC material and the time it is available for transport (Nyman et al., 2013).

906 The relative role of post-fire reduction in forest cover ( $-\Delta LAI$ ) was found to be lower than the  
907 two other processes examined (Figures 7 and S8b-S8c). This result can be explained by the effect  
908 of the interaction between forest cover and infiltration capacity on fluvial erosion across the  
909 aridity gradient. At higher aridity values, background forest cover is always relatively low  
910 (Figure 7b), and the effect of the short-lived post-fire removal of vegetation cover on fluvial  
911 erosion is insignificant compared to the reduction in infiltration capacity during the same period.  
912 In wetter climates, vegetation density is higher and the effect of the temporary loss of cover on  
913 fluvial erosion rates can be significant. However, this effect is balanced by the high infiltration  
914 capacity, which keeps surface runoff rates low even after fire (Noske et al., 2016). These results  
915 indirectly suggest that the time to forest canopy recovery that explicitly depend on forest  
916 recovery trait has little impact on long-term coevolution of soil depth and vegetation in  
917 southeastern Australia.

918 In a study aggregating hundreds of post fire infiltration and runoff measurements, Sheridan et al  
919 (2015) found that post-fire runoff generation was highly correlated with aridity, such that more  
920 arid hillslopes, that often have younger and less developed soils, were associated with higher  
921 post fire sediment yields. Our results indicate that the trend of  $H_{ss}$  with aridity (Figure 7a) is  
922 determined mainly by the amount of surface runoff that is generated (which is controlled by the  
923 infiltration capacity) and how it affects post-fire fluvial erosion rates (Figure S8). Our model  
924 suggests that in a world without fire, the differences in soil depth and vegetation cover between  
925 dry and wet systems would have been significantly smaller to what is currently observed (Figure  
926 7a and 7b). Other theoretical experiments had shown a significant increase in forest cover on the  
927 expense of grasslands in a world without fire (Bond et al., 2005). Our results highlights the  
928 possible role of fire-related changes in soil depth on global distribution of vegetation.

### 929 **5.3 Experiment 3 - The role of interactions and feedbacks in coevolution**

930 Modelled interactions and feedbacks between climate, soil depth, vegetation and fire in the  
931 coevolution process (experiment 3) can be deciphered from Figure 8. Simulation with fire start  
932 when the system is under a dry phase and the shallow soil and low forest cover are in steady-  
933 state with the dry climate and frequent fires (Figure 8a and b). The increase in rainfall after 10  
934 kyr has three consequences. First, after climate becomes wetter, soils are now able to support  
935 more vegetation for a given depth, resulting in higher  $V_c$  which in turn reduces the amount of  
936 rainfall reaching the soil surface. Second, as climate becomes wetter, soil moisture increases,  
937 pushing fires to be further apart (Figure 8c). Third, the transition to wetter climate results in  
938 higher infiltration capacity allowing more throughfall to infiltrate, preventing surface runoff  
939 (Figure 6a) and fluvial erosion (Table 4). This, in turn, causes a buildup of soil depth, as the soil  
940 is produced faster than it is eroded, which feeds back to the its ability to hold more moisture and  
941 more vegetation.

942 Unlike the simulation with fire, soil depth and vegetation are not in steady state when the  
943 simulation without fire starts (Figure 8a and 8b). The lack of fire and the lower erosion rates  
944 causes the soil profile to build up and forest cover to increase as a consequence. When rainfall  
945 increases,  $H$  and  $V_c$  values start to increase from higher values compared to simulations with fire.  
946 The deeper soils in simulation without fire is the result of infiltration capacity being higher for  
947 longer proportion of time. This causes soil to be produced even faster than it is eroded, which  
948 also translates to slightly higher vegetation carrying capacity.

949 The differences in the response of the system to changes in climate between simulations with and  
950 without fire is exaggerated when the climate becomes drier after 150 kyr (Figure 8a-8c). After  
951 the climate changes, soils can no longer support the same amount of vegetation, which results in  
952 an opening of the canopy (Figure 8b). In simulations with fire, the dry climate results in drier  
953 soils, higher flammability (Figure 3f) and more frequent fires (Figure 8c). The increase in fire  
954 frequency, in turn, results in the canopy being open for a longer period of time, which coincides  
955 with the reduction in infiltration capacity and in soil cohesiveness and result in increased surface  
956 runoff (Figure 6a) and higher fluvial erosion rates (Table 4). Without fire, however, canopy  
957 cover and infiltration capacity stay higher for longer, resulting in lower surface runoff and fluvial  
958 erosion compared to simulation with fire. In both cases, the rate of soil produced is lower than  
959 the rates in which it is eroded, resulting in a decrease in soil depth. The differences in of erosion  
960 rates with and without fire (Table 4) after the wet-to-dry transition result in a completely  
961 different system for the same climate, where soil depth is almost three times as deep and  
962 vegetation cover two times as high in the absence of fire (Figure 8a and 8b). These simulations  
963 present an alternative reality to the state that these temperate systems might have been in the  
964 absence of fire.

965 Our results show that the response time of  $V_c$  to changes in climate is generally faster than that of  
966  $H$  and takes between thousands of years (without fire) to tens of thousands of years (with fire)  
967 between two alternative equilibrium states. On a similar note, Blonder et al. (2018) found that the  
968 prediction of contemporary distribution of vegetation can be improved by taking into account  
969 paleoclimate as well as contemporary climate predictors. The longer adjustment time of soils had  
970 been reported in the literature (eg., Cohen et al., 2013; Temme & Veldkamp, 2009). For  
971 example, Cohen et al. (2013) used a numerical model to study the soil-landscape response to  
972 Quaternary climate fluctuations. The authors found that it takes tens of thousands of years for  
973 soils to adjust to fluctuations in climate.

974 There is evidence from SE Australia that climatically driven change in fire activity can push  
975 systems towards different states (eg., Bowman, 2000; Fletcher et al., 2014a; b). Using a multi-  
976 proxy paleo-ecological analysis from Tasmania, Fletcher et al. (2014a) showed that an increase  
977 in fire activity over the past 6,500 yr resulted in the transition between a fire-intolerant rainforest  
978 to a drier fire-tolerant Eucalyptus forest, which also coincided with evidence of elevated erosion  
979 and nutrient loss. CoolFlameS does not model change between different forest types. However,  
980 our results align with the findings of Fletcher et al. (2014a) as they show that the transition  
981 between states as a response to climate change are intensified with the presence of fire. This can  
982 be seen by the bigger drop in forest cover after the wet-to-dry transition (Figure 8b).

983 Two separate hysteresis behavior-patterns can be identified from Figure 8d. The two hysteresis  
984 are related to the different  $V_c$  and FRI values for a given climatic forcing (wetting and then  
985 drying) and soil depth and can be explained by the effect of the interaction between climate and  
986 soil water holding capacity on productivity and flammability. At the start of the wet period,  $V_c$

987 and FRI increase gradually with soil depth despite the abrupt change to a wetter climate. Under  
988 these circumstances, productivity and flammability are limited only by soil water holding  
989 capacity.  $V_c$  and FRI decrease abruptly as rainfall declines by the end of the wet period and stay  
990 constantly low even when the soil is still deep. Under these conditions, productivity and  
991 flammability are mainly driven by the supply of water and not by that water holding capacity of  
992 the soil. These results indicate that under wet climatic conditions, soil depth can potentially  
993 control fire frequency. As far as the authors are aware, this relationship had never been identified  
994 before, and certainly requires to be tested empirically.

995 Results from experiment 3 point to a climatically driven eco-hydro-geomorphic feedback  
996 between soil moisture, fire and fluvial erosion that drive the trajectory, rate and magnitude of  
997 change in the coevolution of soil-vegetation systems. In this feedback (Figure 9), climate drives  
998 long-term fire frequency and fluvial erosion rates that affect soil depth. This, in turn, changes the  
999 water holding capacity of the soil, which feeds back to productivity and fire frequency. For  
1000 example, under a drying climate, higher fluvial erosion rates and higher fire frequency might  
1001 lead to more erosion and more fire. In contrast, under a wetting climate, lower erosion rates due  
1002 to lower fire frequency might lead to lower erosion and less frequent fire. This fire related eco-  
1003 hydro-geomorphic feedback eventually stops when there is no soil left or when climate,  
1004 vegetation, soil and fire regime reach a new equilibrium state.

#### 1005 **5.4 Limitations, implications and opportunities**

1006 The results indicate that the coevolution of soil depth and vegetation is highly dependent on the  
1007 properties of the soil surface. In nature, long-term weathering of bedrock, gravel and soil  
1008 particles, driven by climate (Riebe et al., 2004) and vegetation (Brantley et al., 2017), make  
1009 changes in soil properties that control plant available water capacity and its permeability (Clapp  
1010 & Hornberger, 1978; Saxton & Rawls, 2006). The development of soil properties in CoolFlameS  
1011 is modelled implicitly as a function of aridity, however, a more explicit representation is  
1012 suggested for further model development. We propose that effect of changes in soil properties on  
1013 coevolution of soils-vegetation systems is nonlinear and can increase the difference in system  
1014 states even further. In this proposed climatically-driven soil development-vegetation-fire  
1015 feedback higher water holding capacity of a soil for a given soil depth increases its biomass  
1016 holding capacity, which can indirectly decrease flammability and fire frequency. Future efforts in  
1017 this direction are encouraged to include soil development, to represent the climate-controlled  
1018 development of soil hydraulic properties and particle size distribution (Cohen et al., 2009;  
1019 Temme & Vanwalleghem, 2016).

1020 Over geological timescales, the rate of soil production and erosion dictates the rate of change in  
1021 hillslope gradient, which in turn affect the insolation regime and water balance at any point on  
1022 the landscape in a self-regulating feedback (Yetemen et al., 2015). By excluding possible  
1023 changes in hillslope gradient in the zero spatial dimension approach - simplicity was achieved at  
1024 the expense of including a factor that may explain variations in soil depths and vegetation cover  
1025 across the landscape (Inbar et al., 2018). For example, the decrease in hillslope gradient with  
1026 aridity in SE Australia (Inbar et al., 2018) can potentially explain why modelled soil depth was  
1027 underestimated between aridity 1 to 1.5 (Figure 7a). We argue that the large difference in erosion  
1028 and denudation between the wettest and driest simulations (Table 4) would have been smaller  
1029 had hillslope gradient been allowed to change. In this case, long-term fluvial erosion would  
1030 flatten hillslopes in drier climatic conditions, similar to the what had been observed by Inbar et

1031 al. (2018). Another potential avenue of research could be to expand this modelling framework  
1032 into a 3D landscape evolution space, which will allow investigating the feedbacks and  
1033 interactions within the coevolution of fire, vegetation, soils and landscapes more generally  
1034 (Pelletier et al., 2013).

1035 The modelling approach implemented in CoolFlameS implies that rates and trajectory of change  
1036 of soil-vegetation systems are caused by a climatically-driven eco-hydro-geomorphic feedback  
1037 between soils, vegetation and fire. By including contemporary eco-hydro-geomorphic processes  
1038 our results support the conceptual model proposed by Inbar et al. (2018), where they attributed  
1039 observed trends in the soil depth with aridity (Figure 7a) to climatically-driven variations in  
1040 productivity, fire and soil hydraulic properties. The threshold in soil depth across the water-  
1041 energy limited boundary (where aridity  $\approx 1$ ) found in both observed and modelled domains  
1042 highlight the effect of climate and fire in driving rates of coevolution.

1043 Our results indicate that including fire-related processes and feedbacks is essential if one intends  
1044 to study critical zone and landscape evolution in fire prone landscapes. Our results further  
1045 indicate that in these systems, fire can be regarded to be a central part of the coevolution process,  
1046 hence should be modelled dynamically depending on climate and the state of the system. In  
1047 Southeastern Australia, fire-related processes and feedbacks are found to drive the coevolution of  
1048 soil-forest systems and are responsible for the magnitude of differences in soil depth and  
1049 vegetation cover across contemporary climatic gradient.

1050 **6 Conclusions**

1051 We used the flammable landscapes of SE Australia to evaluate the role of fire in the coevolution  
1052 of soil-forest systems. Using a new numerical model (CoolFlameS) that represents the eco-  
1053 hydro-geomorphic processes that are typical to SE Australian forests, we: (i) tested the  
1054 hypothesis that fire-related processes are critical to explain the variations in coevolved systems  
1055 states across an aridity gradient; (ii) identified the dominant fire related processes involved in  
1056 coevolution; and (iii) identified any fire related feedbacks involved. CoolFlameS showed good  
1057 skill in predicting patterns of soil moisture thresholds, ecohydrological partitioning, fire  
1058 frequency distribution, surface runoff and erosion and denudation rates across a gradient of  
1059 aridity when compared to local measurements and published data. The validated model was then  
1060 used to conduct numerical experiments to address the three aims. The results showed that:(i) the  
1061 hypothesis was supported, and that the relative role of fire in coevolution of soil depth and  
1062 forests increased with aridity in the study area; (ii) amongst the three effects of fire examined,  
1063 the relative role of post-fire reduction in infiltration capacity (and its effects of surface runoff and  
1064 fluvial erosion rates) on coevolution of soil-vegetation systems was the largest, followed by post-  
1065 fire reduction in soil cohesiveness and in canopy cover. (iii) the trajectory and magnitude of the  
1066 coevolution of soil-vegetation systems is driven by a climatically driven feedback between soil,  
1067 vegetation and fire. For example, under a drying climate, long-term increase in post-fire erosion  
1068 might contribute to more frequent fires and more erosion. We conclude that incorporating fire-related  
1069 processes and feedbacks is essential when using models to investigate the critical zone and landscape  
1070 evolution in fire-prone landscapes.

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1563

1564 **Tables**

1565

1566 Table 1 – Model parameters

Notation	Description	Units	Value	Source
<b>Topography</b>				
$S$	Slope gradient	m m <sup>-1</sup>	0.52	Text S8 in supporting information
$S_{50}, S_{30}$	Slope gradient at 50 and 30 m down the slope, respectively	m m <sup>-1</sup>	0.52, 0.48	Supporting information (Text S8)
<b>Climate</b>				
$E_s$	$E_s$ is a factor reducing $E_p$ to achieve maximum soil evaporation	-	0.7	(Zhou et al., 2013)
$L_T$	The lag between peak $E_p$ and peak solar forcing	days	30	Estimated
$\alpha_{PT}$	Priestley & Taylor scalar	-	1.26	(Priestley & Taylor, 1972)
<b>Soil properties and soil depth balance</b>				
$a_{NC}$	Constant for calculating the proportion of the NC material transported	-	1.16	(Nyman et al., 2013)
$b_{NC}$	Constant for calculating the proportion of the NC material transported	-	0.34	(Nyman et al., 2013)
$b_{ret}$	Water retention parameter	-	4.9	(Zhou et al., 2013)
$E_w$	Scalar for evaporation rate form soil under wilting point	-	0.1	(Laio et al., 2006)
$H_{NCmax}$	Maximum depth of the NC layer	mm	8	(Nyman et al., 2013)
$H^*$	Exponential folding depth of the soil production rate	m <sup>-1</sup>	0.5	(Amundson et al., 2015)
$K_e$	Detachment limited erosivity	h m <sup>-1</sup>	5.4e <sup>-3</sup>	(Wagenbrenner et al., 2010)
$K_s$	Saturated hydraulic conductivity	mm h <sup>-1</sup>	200	Estimated for porous soil

$m_{st}$	Empirical constant in manning's equation	-	0.7	(Istanbulluoglu & Bras, 2005; Willgoose et al., 1991)
$n$	Porosity (for clay loam)	-	0.5	(Clapp & Hornberger, 1978)
$n_{st}$	Empirical constant in manning's equation	-	0.6	(Istanbulluoglu & Bras, 2005; Willgoose et al., 1991)
$n_T$	Manning's roughness coefficient	-	0.022	Estimated as cohesive river bed (Table 3 in Coon, 1998)
$s_h$	Soil saturation ratio at hygroscopic capacity	-	0.1	(Clapp & Hornberger, 1978)
$S_c$	Critical gradient above which hillslope diffusion becomes infinite	m m <sup>-1</sup>	1.25	(Roering, 2008)
$s_{cut}$	Soil moisture deficit flammability threshold value	-	0.39	Calibrated; Text S5 in supporting information
$s_{fc}$	Soil saturation ratio at field capacity	-	0.64	(Clapp & Hornberger, 1978)
$s_h$	Soil saturation ratio at hygroscopic capacity	-	0.1	(Caracciolo et al., 2014)
$s_i$	Soil saturation ratio at incipient stomata closure	-	0.5	Estimated
$s_w$	Soil saturation ratio at wilting point	-	0.36	(Clapp & Hornberger, 1978)
$\beta_r$	Root density exponential decay term	m <sup>-1</sup>	2.6	(Roering, 2008)
$\epsilon_o$	Maximum soil production rate at zero soil depth	m d <sup>-1</sup>	1.85e <sup>-7</sup>	(Heimsath et al., 2001)
$\eta$	Maximum transport coefficient	m <sup>2</sup> d <sup>-1</sup>	4.5e <sup>-3</sup>	(Roering, 2008)
$\rho_r$	Density of bedrock	kg m <sup>-3</sup>	2650	
$\rho_s$	Density of soil	kg m <sup>-3</sup>	1325	
$\tau_{crit}$	Critical shear stress	Pa	0	(Wagenbrenner et al., 2010)

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**Vegetation properties and biomass balance**

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$a_{kss}$	Exponent for structural biomass turnover coefficient	-	20	Calibrated
$c_{kss}$	Exponent for structural biomass turnover coefficient	-	0.55	Calibrated
$k_{lp}$	leaf production rate	$d^{-1}$	0.001	Calibrated
$k_{sl}$	Leaf senescence coefficient	1	$5e^{-5}$	Calibrated
$LAI_{gmax}$	Maximum LAI for the domain	$m\ m^{-1}$	4.17	Calibrated
$M$	coefficient for leaf biomass recovery	-	4	Calibrated
$m_1$	Exponent for maximum biomass	-	0.43	Calibrated
$m_2$	Exponent for maximum biomass	-	1.79	Calibrated
$m_3$	Exponent for maximum LAI	-	$4.4e^{-5}$	Calibrated
$S_{LAI}$	Volume storage per unit LAI	$mm\ LAI^{-1}$	1	Calibrated
$SLA$	Specific leaf area	$LAI\ kg^{-1}$	4	(Whitehead & Beadle, 2004)
$WUE$	Water use efficiency	$\frac{kg_{CO_2}}{kg_{H_2O}^{-1}}$	$5e^{-3}$	(Zhou et al., 2013)
$\alpha_B$	System maximum biomass	$kg\ m^{-2}$	69.11	Calibrated
$\mu$	The ratio between net and gross primary productivity	-	0.47	(Waring et al., 1998)
$\omega$	Conversion ratio of CO <sub>2</sub> to dry matter	$\frac{kg_{DM}}{kg_{CO_2}^{-1}}$	0.55	(Zhou et al., 2013)
<b>Flammability and fire</b>				
$\kappa_f$	Slope of probability reduction	-	$14.7e^{-2}$	Calibrated; Text S5 in supporting information
$\delta$	Maximum fire probability	$yr^{-1}$	$1.5e^{-3}$	Calibrated; Text S5 in supporting information

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1569 **Table 2-** Aridity of the eight climatic scenarios used for model simulations. MAP is mean annual  
 1570 precipitation.

<i>MAP</i>	Aridity (North facing)	Aridity (South facing)
mm	(-)	(-)
721	2.61	1.83
942	2.00	1.40
1261	1.49	1.05
1610	1.17	0.82

1571

1572 **Table 3 –** Published sources of measured sediment yield

Location	Source	MAP	Type	Time since fire	mean sediment yield reported
		mm		years	t ha <sup>-1</sup> yr <sup>-1</sup>
Stoney Gully	Noske et al. (2016)	954	small headwater	1	10.05
				5	0.12
Upper Yarra Catchment	Cawson et al. (2013)	1200	hillslope/ unbound plot	1 unburnt	0.19 1.3e <sup>-4</sup>
Ella creek	Smith et al. (2011a)	1400	catchment	2 unburnt	0.11 0.01
East Kiewa	Lane et al. (2006)	1800	catchment	1 unburnt	2.96 0.23

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1574

1575 **Table 4** - Mean sediment yield after fire and in unburnt state for simulations driven by four  
 1576 different climatic scenarios (Table 2). Values for were based on a 100 kyr simulation for each of  
 1577 the sites.

MAP	Aspect	Aridity	Time since fire	mean post-fire sediment yield* <sup>1</sup>	Modelled fire interval	Denudation rate
mm				t ha <sup>-1</sup> yr <sup>-1</sup>	yr	mm kyr <sup>-1</sup>
722	North	2.61	1 Unburnt	8.51 0.44	19	83.4
	South	1.86	1 unburnt	8.53 0.42	24	75.4
943	North	2	1 Unburnt	8.75 0.5	22	87.7
	South	1.4	1 Unburnt	2.62 0.04	42	21.1
1261	North	1.49	1 unburnt	7.89 0.22	34	48.2
	South	1.05	1 Unburnt	0.2 2e <sup>-3</sup>	66	14.0
1611	North	1.17	1 Unburnt	1.5 3e <sup>-3</sup>	54	15.7
	South	0.82	1 Unburnt	0.02 3e <sup>-3</sup>	89	13.8

\*<sup>1</sup> Calculated from first year after each fire event.

1581 **Figure Captions**

1582 **Figure 1** –(a) Conceptual model that describes the coevolution of a coupled soil-vegetation  
1583 system; and (b) a schematic representation of what eco-hydro-geomorphic processes represented  
1584 in CoolFlameS, are the manner in which they are coupled. The dynamics of soil depth ( $H$ ), soil  
1585 moisture ( $nHs$ , where  $s$  is degree of saturation and  $n$  is porosity) and standing biomass ( $B$ ) are  
1586 expressed by equations 2-4. Thick coloured arrows represent fluxes of water- (blue), energy-  
1587 (yellow), carbon- (green) and minerals- (brown). Thin dashed arrows point to the effects of soil  
1588 moisture on fire and the effect of individual fire on forest cover and soil surface properties. An  
1589 illustration of the spatial representation of the model system is presented in (c). The system  
1590 surface area is divided horizontally into vegetated ( $V_c$ ) and bare ( $1 - V_c$ ) proportions. The  
1591 vegetated area is further divided into covered ( $LAI_r$ ) and uncovered ( $1 - LAI_r$ ) proportions. both  
1592 variables depend are modelled dynamically and depend on the  $LAI_l$  using equation 5.

1593 **Figure 2** – Map of SE Australia showing the locations of sites that were used for: (i) model  
1594 grounding (Text S7; Table S5); (ii) the calibration of the Nyman Scott Rectangular Pulse (NSRP)  
1595 model (Text S1); and (iii) model evaluation.

1596 **Figure 3** – Modelled and measured number of days that degree of saturation ( $s$ ) was above (a  
1597 and b) and below (c and d) incipient stomata closure; and below the flammability threshold value  
1598 (e and f), as a function of aridity (left column) and mean annual precipitation (right column).  
1599 Modelled results display annual value of each metric for 1 kyr simulations as a function of the  
1600 simulated climatic forcings for the same year (Table 2). For each modelled value, 100-year  
1601 aridity ( $\bar{AI}_{100}$ ) was calculated as the ratio between mean evaporative demand to mean rainfall for  
1602 the previous 100 years, starting from year 101. Measured results were calculated from a year-  
1603 long monitoring of six sites (Table S6).

1604 **Figure 4** – comparison of literature to modelled values for: transpiration, soil evaporation and  
1605 interception loss as a proportion of ET (a); and transpiration, soil evaporation, interception loss  
1606 and recharge (P-ET) as a proportion of P (b). Modelled results displayed are for simulation  
1607 running south-facing (SF) wet, north-facing (NF) wet and NF damp climatic scenarios (Table 2),  
1608 which are compared to measurements described in Vertessy et al. (2001), Nolan et al. (2014) and  
1609 Mitchell et al. (2012), respectively.

1610 **Figure 5** –Distributions of fire return interval (a-c) and the cumulative number of days below  
1611 soil moisture deficit threshold ( $\bar{s}$ ) for 100 kyr-long simulation forced with (a) dry (red;  
1612 aridity=2.61), (b) damp (blue; aridity=1.49) and (c) wet (black; aridity=0.82) climatic scenarios  
1613 (Table 2).  $\bar{s}$  is used here as a proxy for flammability and is calculated using Eqn. S8.

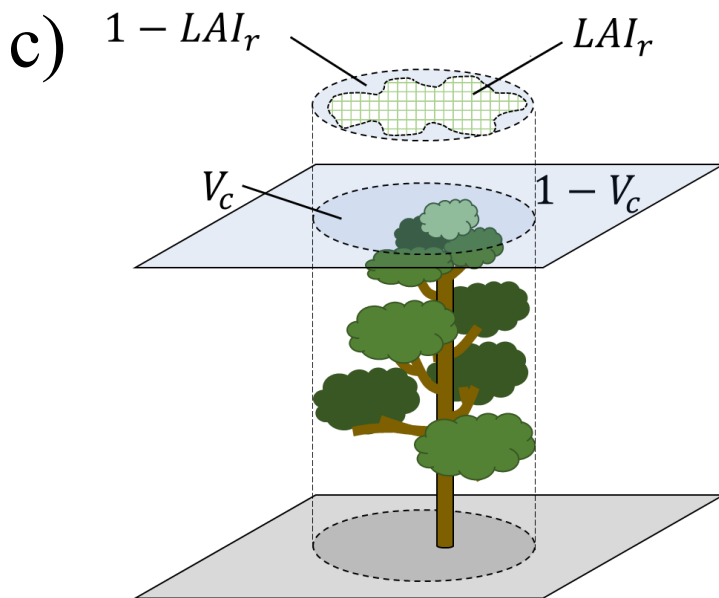
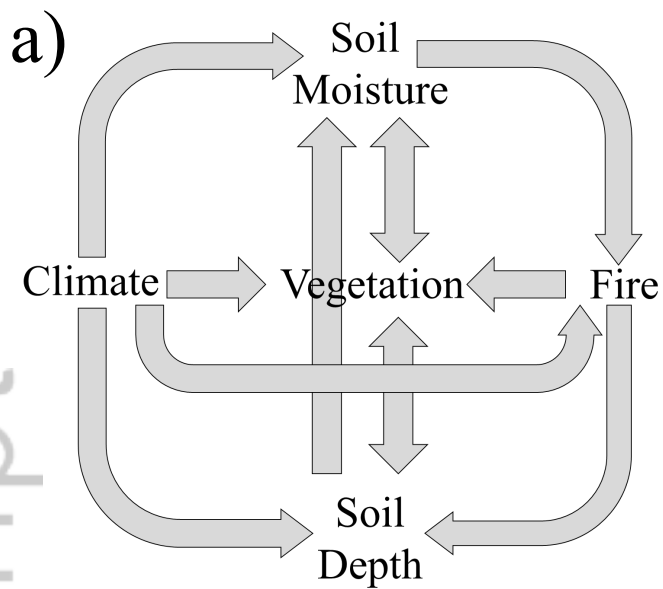
1614 **Figure 6** – Mean modelled and measured event-scale runoff ratio (SRR) for first year after fire  
1615 as a function of aridity (a); and measured and modelled discharge for the first year after a fire, as  
1616 a function of rainfall depth. Modelled values at each aridity point presented in (a) are mean SRR  
1617 that were calculated using surface runoff that originated only from rainstorms that exceeded a 5  
1618 mm h<sup>-1</sup> threshold (grey markers). The dashed line is a function fitted to measured event-based  
1619 runoff ratio from 8 meter plots for the range 0.65<aridity<1.80 (Eqn 3 in Van der Sant et al.,

1620 2018). Modelled data represent values for 50 m hillslope stretch; Dashed line in (b) is a linear  
1621 function fitted to measured data.

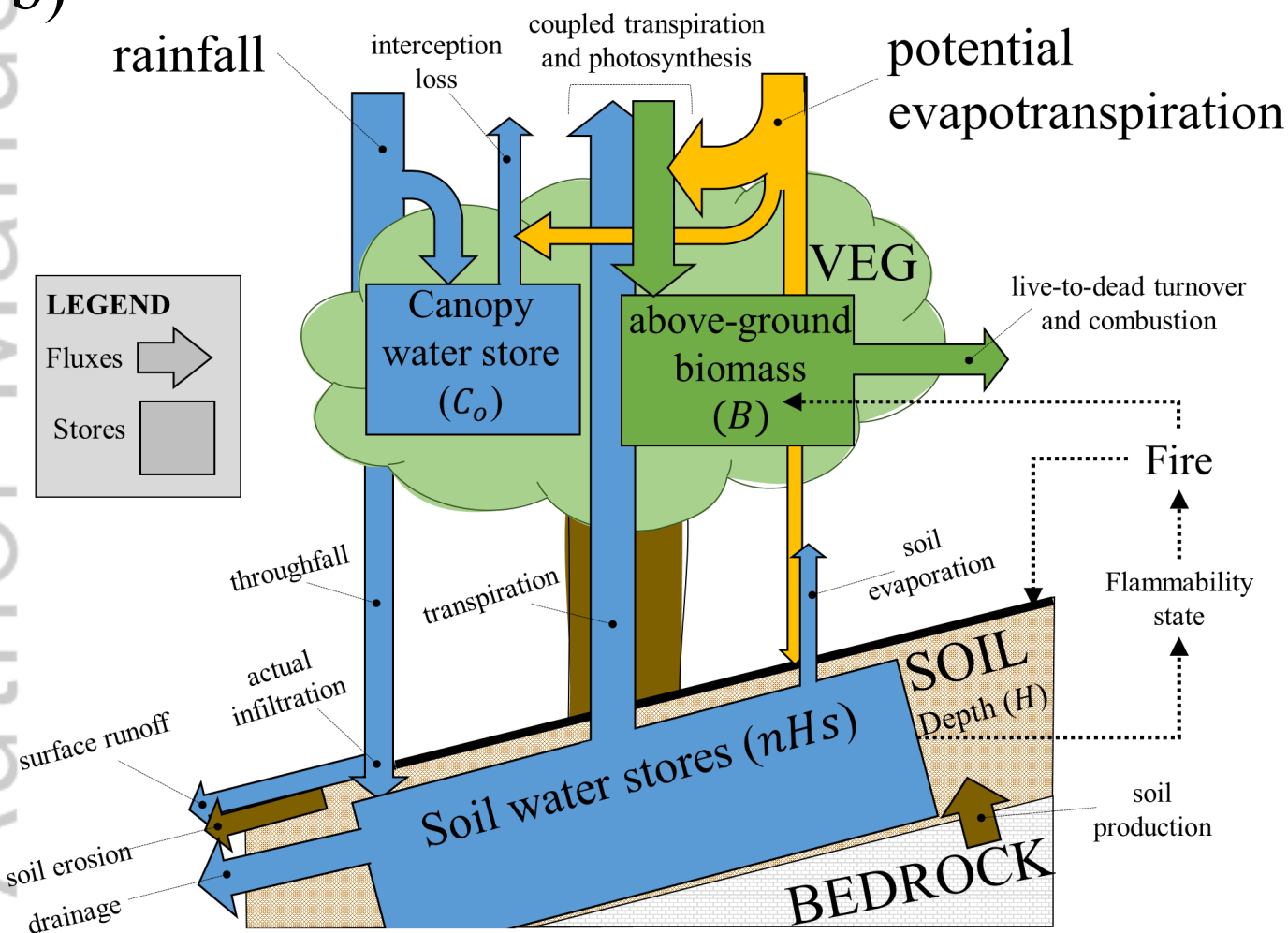
1622 **Figure 7-** modelled ( $H_{SS}$  and  $V_{c-SS}$ ) and observed soil depth and projected vegetation cover as a  
1623 function of aridity for: (a-b) simulations with (+*fire*) and without fire (*-fire*); and for  
1624 simulations with fire but without post-fire changes in: (c-d) infiltration capacity ( $-\Delta I_c$ ); (e-f) soil  
1625 cohesiveness ( $-\Delta CO$ ); and (g-h) canopy cover ( $-\Delta LAI$ ). The figure presents results for  
1626 experiment 1 (a-b) and 2 (c-h).  $H_{SS}$  and  $V_{c-SS}$  values are plotted over functions and 95%  
1627 confidence interval (grey area) fitted to soil depth measurements (Inbar et al., 2018) and  
1628 Remotely sensed vegetation cover using annual LANDSAT values (Tern AusCover, 2017) for  
1629 areas near the three steepest sites (Table S5). Confidence interval for vegetation cover was  
1630 generated for 1,000 randomly sampled values of remotely sensed vegetation cover.

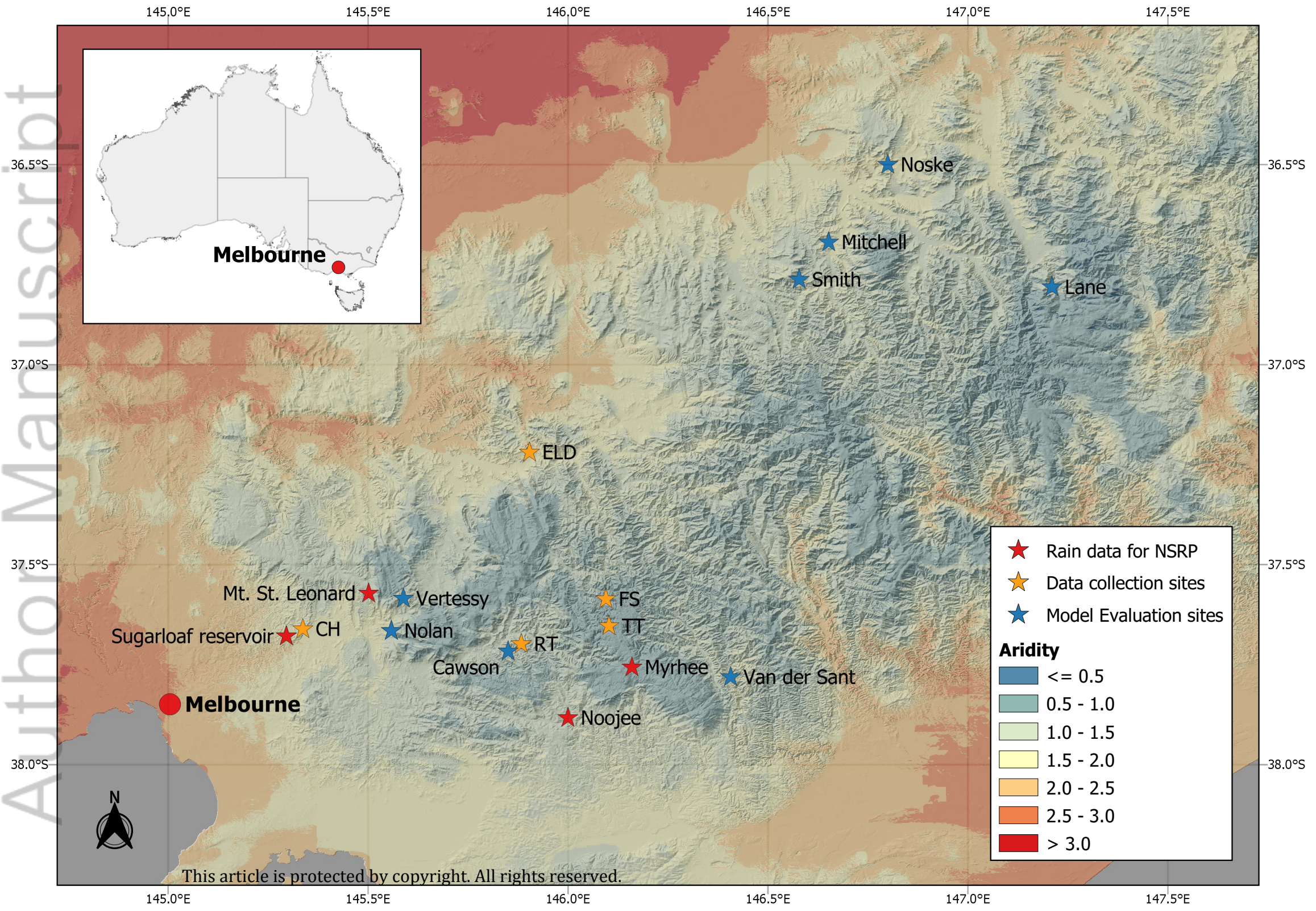
1631 **Figure 8 -** The coevolution of soil depth ( $H$ ); projected vegetation cover ( $V_c$ ); and fire return  
1632 interval (FRI) with time (a-c); and their values plotted within a 2D space (d) for simulations with  
1633 (full circular markers) and without fire (empty green triangular markers). Simulations used in  
1634 this analysis were driven by dry climate which was interrupted by a 150 kyr long wet period.  
1635 Climate changes from dry-to-wet and from wet-to-dry in (a-c) are marked by red and blue  
1636 triangles (respectively). Each circular marker in (d) represents the mean value for  $V_c$  and  $H$   
1637 calculated for 1000 yearlong bins. For simulation with fire (d), size and color of each circular  
1638 marker represent the mean FRI for the same period. To include the element of time in (d),  
1639 simulation starting and end points are marked with a cross and a plus sign (respectively), and  
1640 years 10k, 11k, 160k, 161k and 200k are marked with appropriate text.

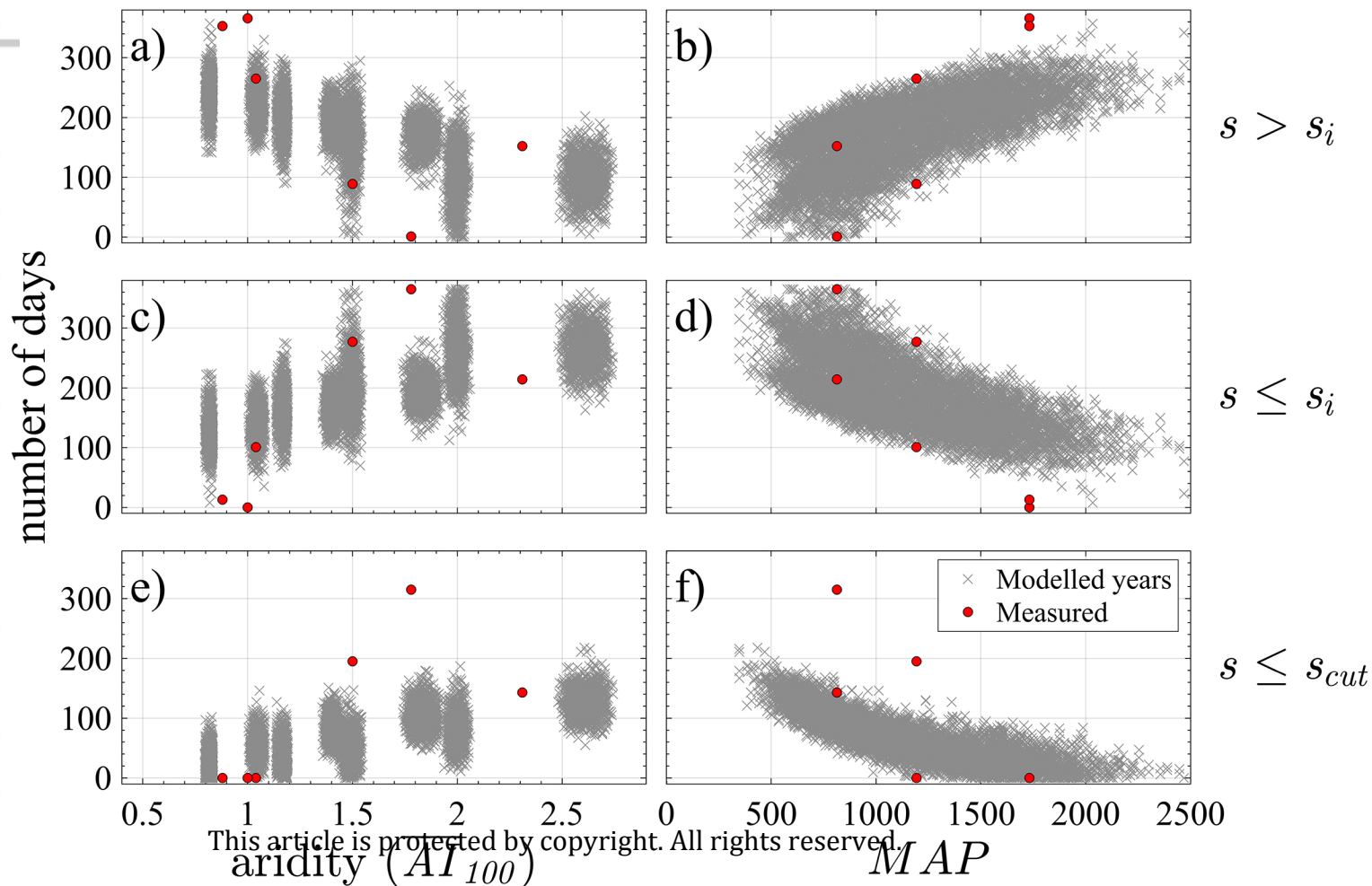
1641 **Figure 9 –** Climatically-driven feedback between soil moisture, fire return interval (FRI), fluvial  
1642 erosion and soil depth. Red arrows represent effects that are related to fire and green arrows  
1643 those that are not. In this feedback, long-term change in climate affects soil moisture, vegetation  
1644 cover and fire frequency. This, in-turn force changes on soil depth and its water holding capacity  
1645 by altering the rate of fluvial erosion, which feeds back to soil moisture, vegetation cover and  
1646 fire frequency.

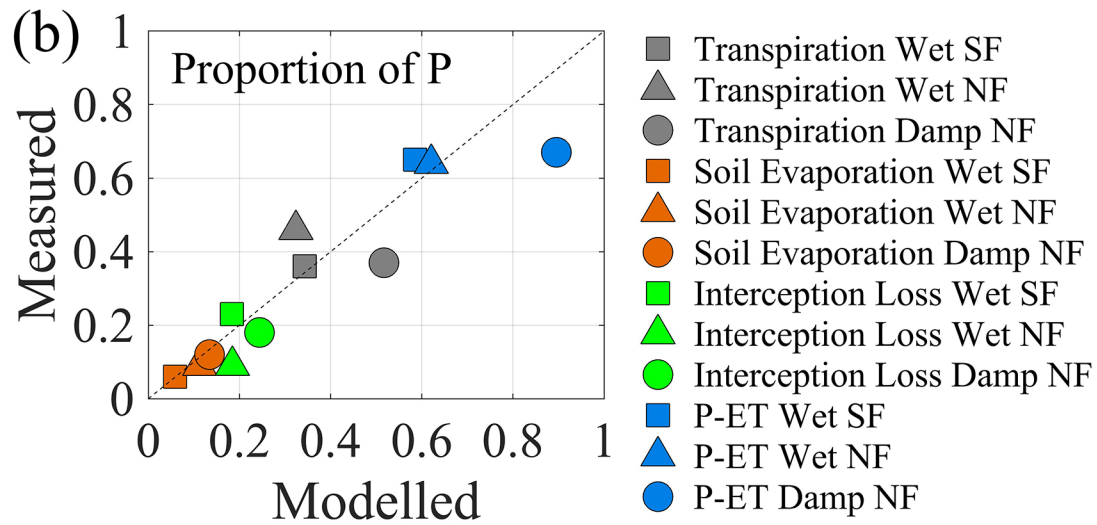
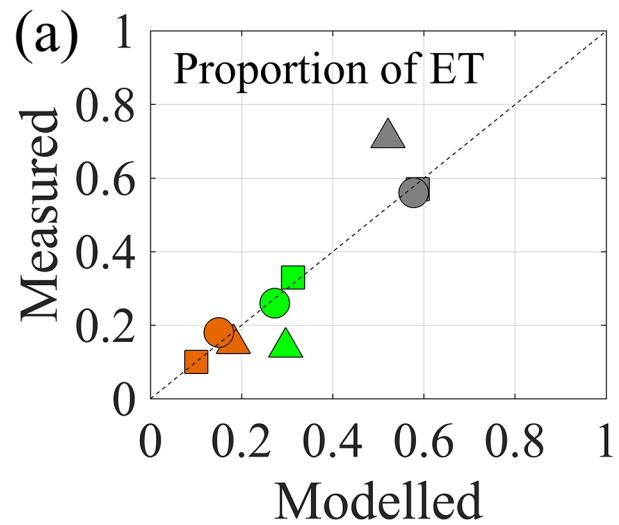


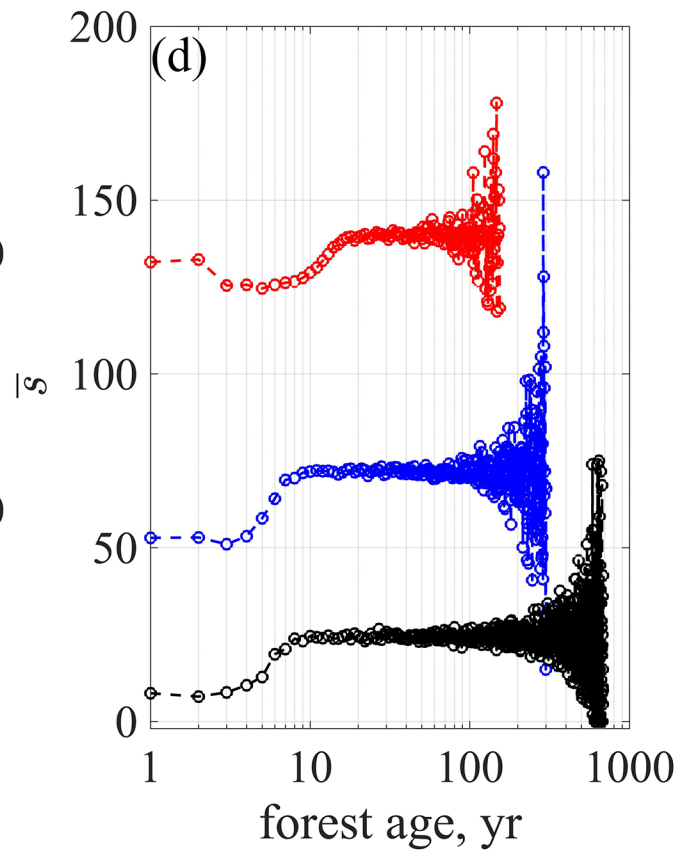
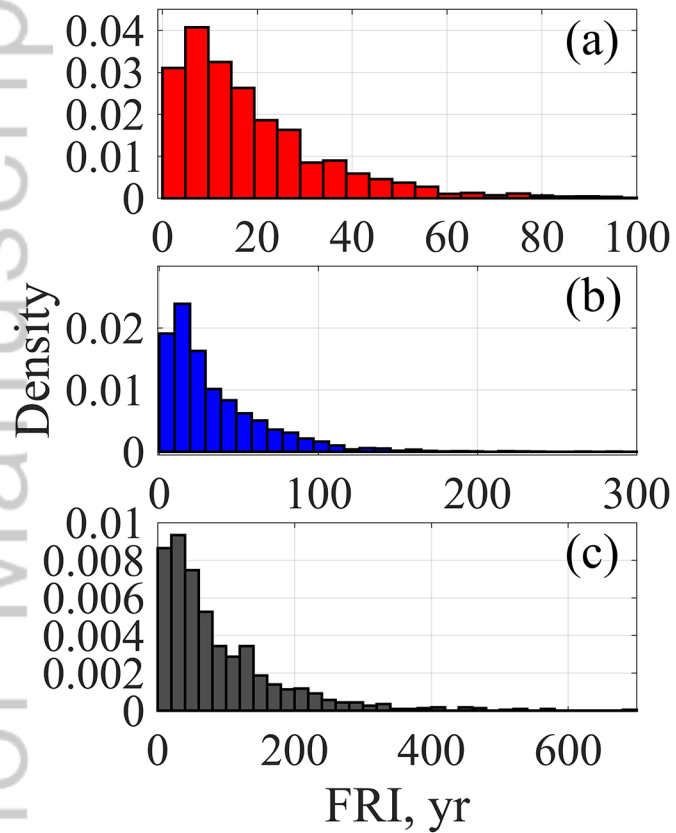
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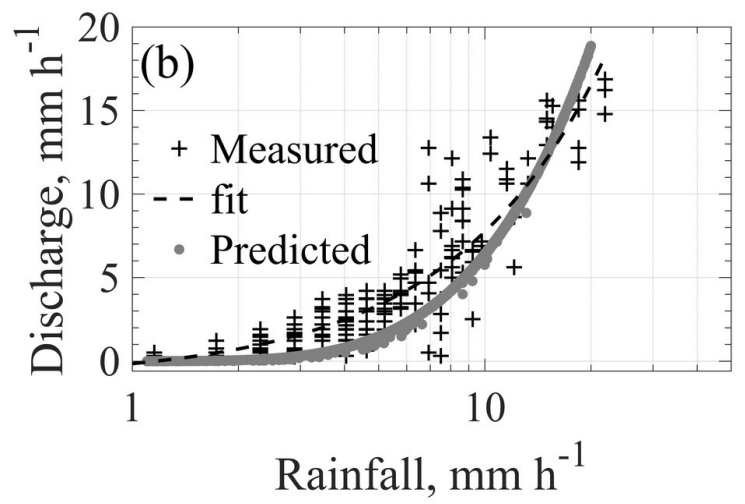
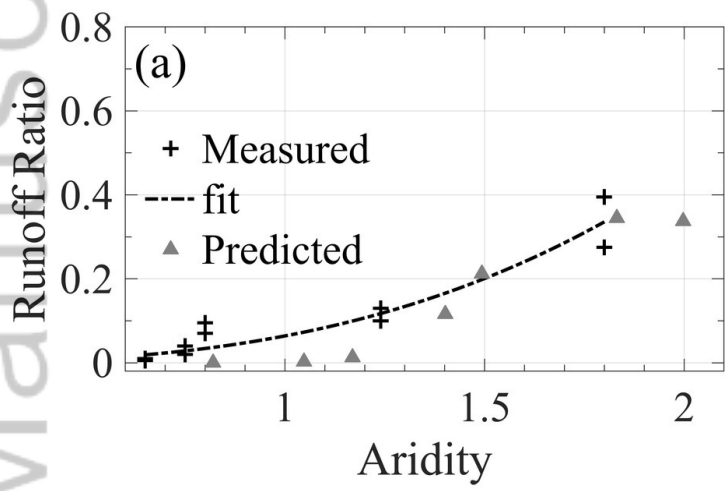




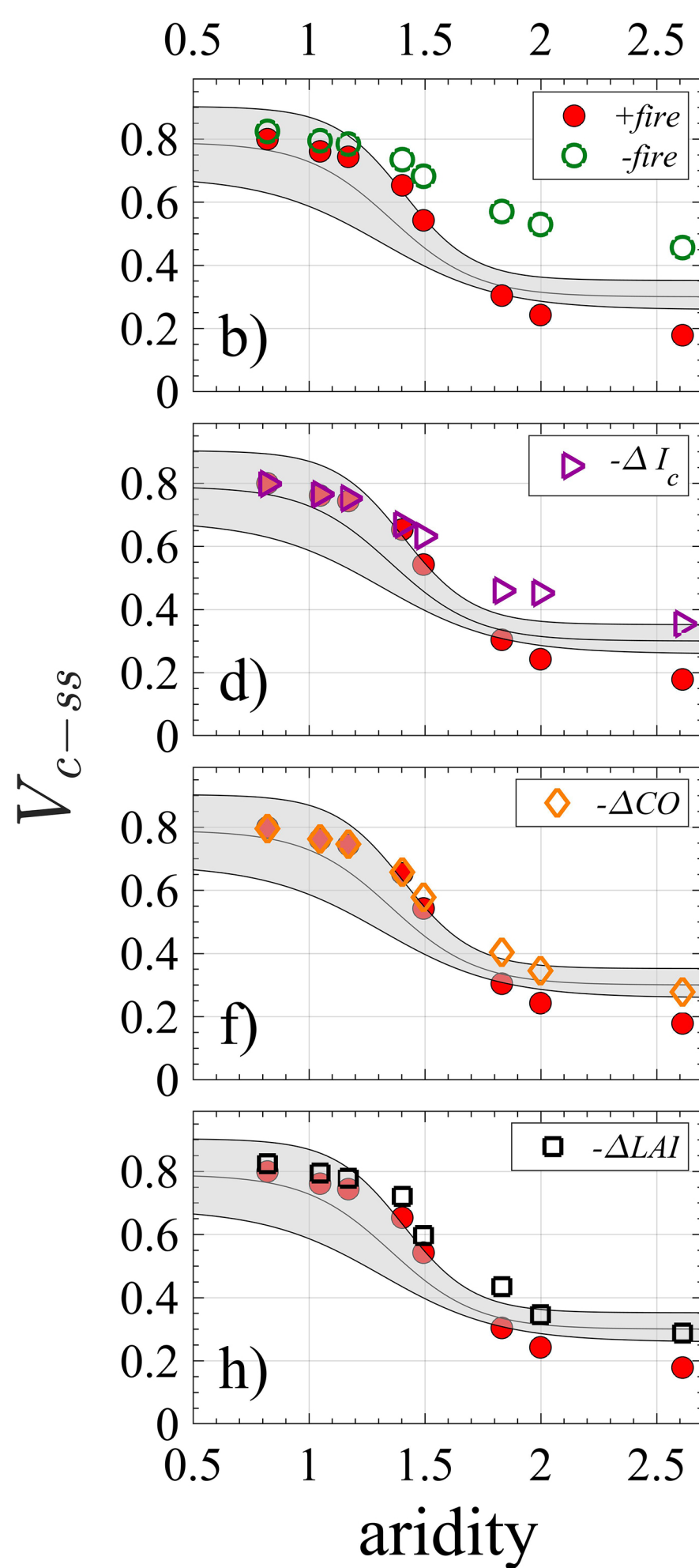
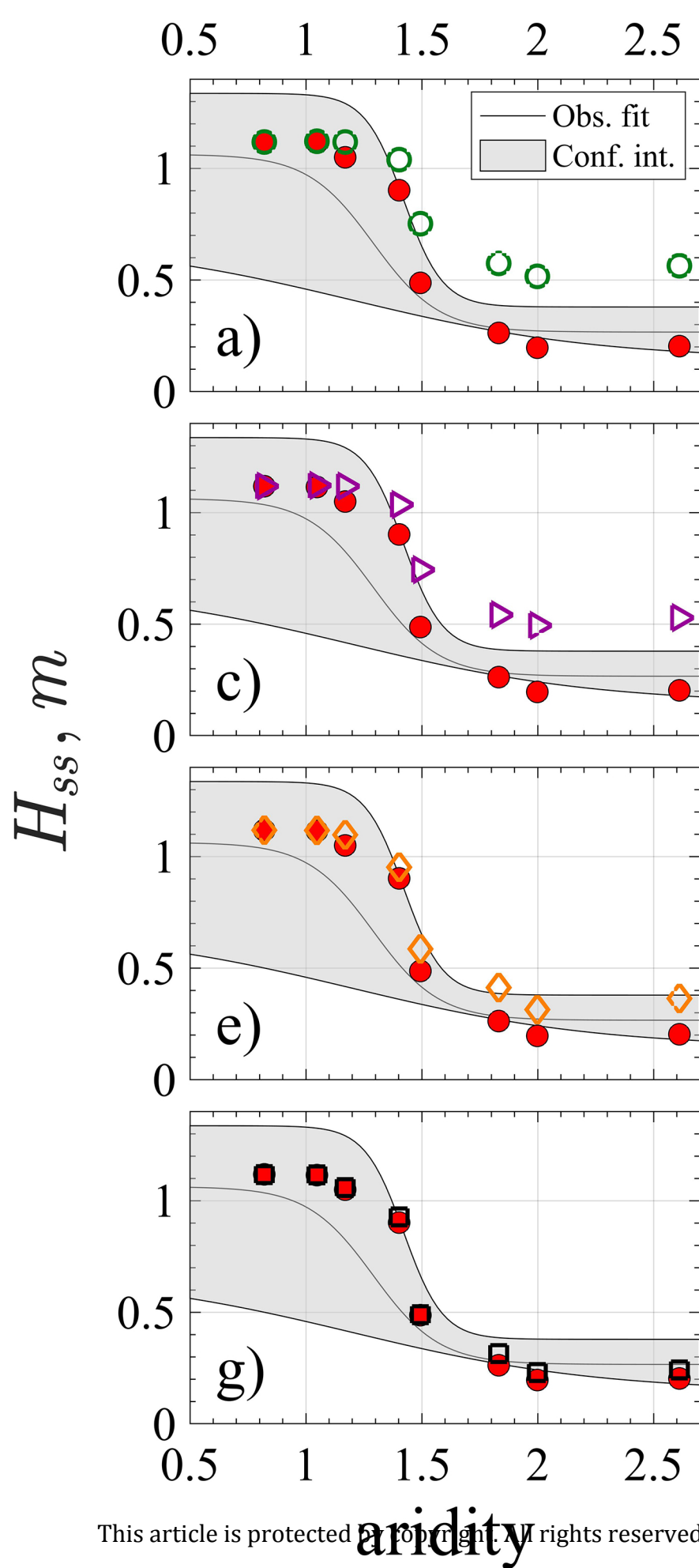


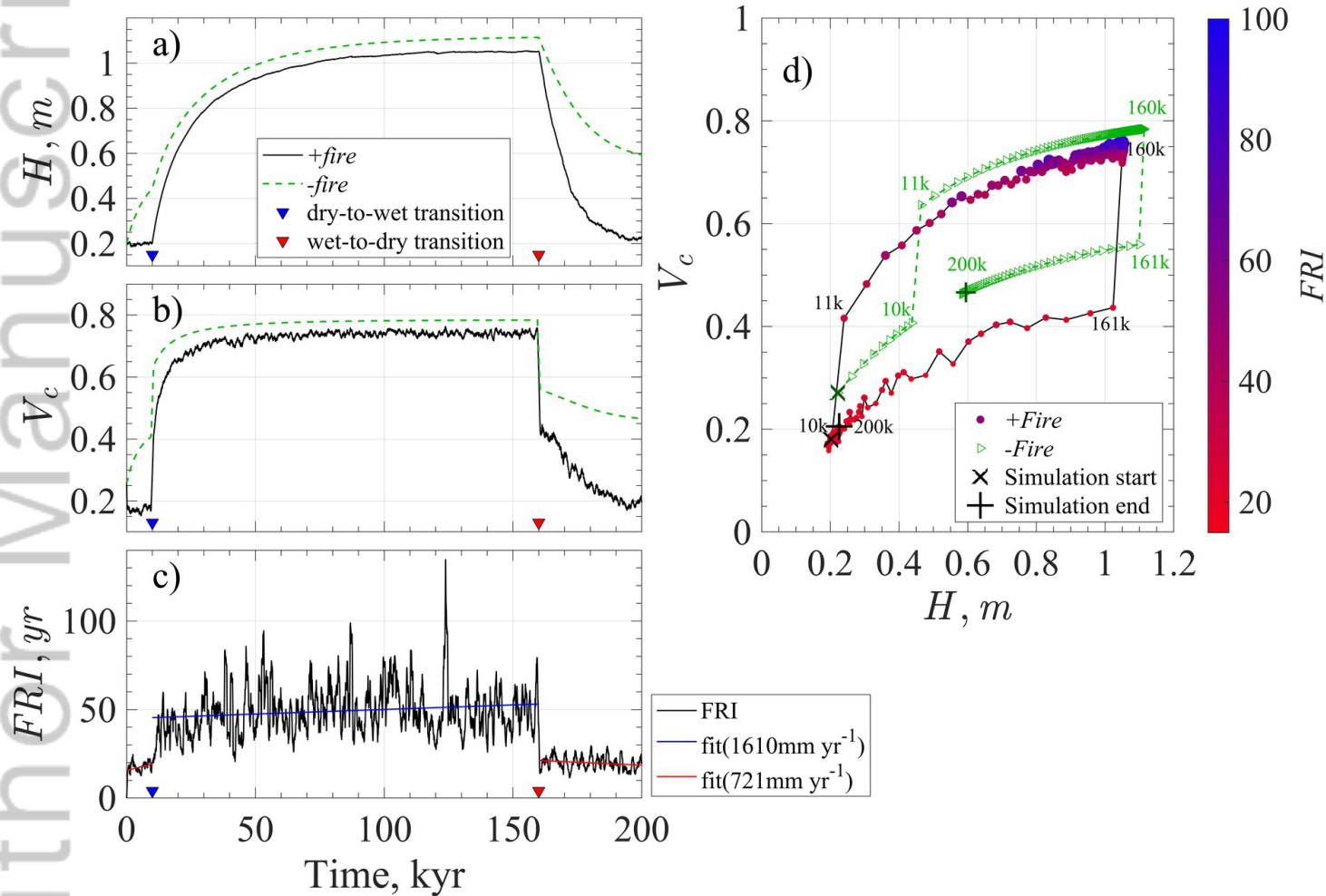






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2019WR026005-f08-z-.jpg

